

Historical Perspective and Further Reading

This history section gives an overview of memory technologies, from mercury delay lines to DRAM, the invention of the memory hierarchy, and protection mechanisms, and concludes with a brief history of operating systems, including CTSS, MULTICS, UNIX, BSD UNIX, MS-DOS, Windows, and Linux.

The developments of most of the concepts in this chapter have been driven by revolutionary advances in the technology we use for memory. Before we discuss how memory hierarchies were developed, let's take a brief tour of the development of memory technology.

The ENIAC had only a small number of registers (about 20) for its storage and implemented these with the same basic vacuum tube technology that it used for building logic circuitry. However, the vacuum tube technology was far too expensive to be used to build a larger memory capacity. Eckert came up with the idea of developing a new technology based on mercury delay lines. In this technology, electrical signals were converted into vibrations that were sent down a tube of mercury, reaching the other end, where they were read out and recirculated. One mercury delay line could store about 0.5 Kbits. Although these bits were accessed serially, the mercury delay line was about a hundred times more cost-effective than vacuum tube memory. The first known working mercury delay lines were developed at Cambridge for the EDSAC. Figure e5.17.1 shows the mercury delay lines of the EDSAC, which had 32 tanks and 512 36-bit words.

Despite the tremendous advance offered by the mercury delay lines, they were terribly unreliable and still rather expensive. The breakthrough came with the invention of core memory by J. Forrester at MIT as part of the Whirlwind project in the early 1950s (see Figure e5.17.2). Core memory uses a ferrite core, which can be magnetized, and once magnetized, it acts as a store (just as a magnetic recording tape stores information). A set of wires running through the center of the core, which had a dimension of 0.1–1.0 millimeters, makes it possible to read the value stored on any ferrite core. The Whirlwind eventually included a core memory with 2048 16-bit words, or 32 Kbits. Core memory was a tremendous advance: it was cheaper, faster, much more reliable, and had higher density. Core memory was so much better than the alternatives that it became the dominant memory technology only a few years after its invention and remained so for nearly 20 years.

...the one single development that put computers on their feet was the invention of a reliable form of memory, namely, the core memory. ... Its cost was reasonable, it was reliable and, because it was reliable, it could in due course be made large.

Maurice Wilkes, Memoirs of a Computer Pioneer, 1985

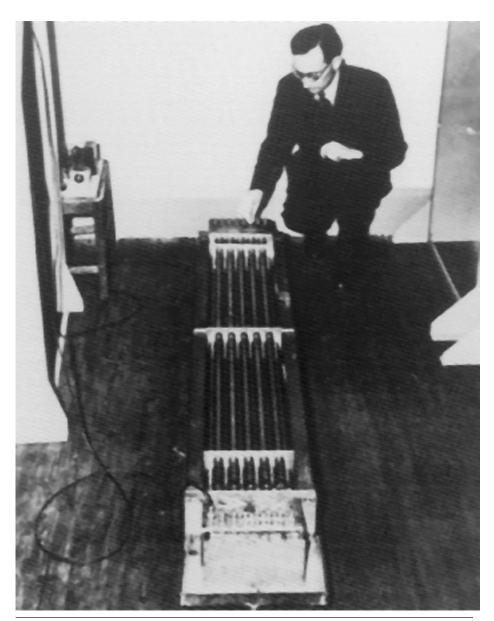


FIGURE e5.17.1 The mercury delay lines in the EDSAC. This technology made it possible to build the first stored-program computer. The young engineer in this photograph is none other than Maurice Wilkes, the lead architect of the EDSAC.

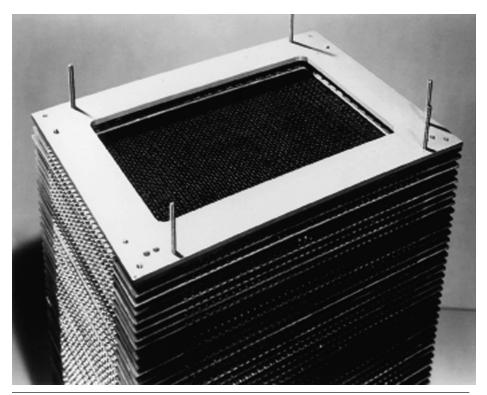


FIGURE e5.17.2 A core memory plane from the Whirlwind containing 256 cores arranged in a 16 × 16 array. Core memory was invented for the Whirlwind, which was used for air defense problems, and is now on display at the Smithsonian. (Incidentally, Ken Olsen, the founder of Digital and its president for 20 years, built the computer that tested these core memories; it was his first computer.)

The technology that replaced core memory was the same one that we now use both for logic and for memory: the integrated circuit. While registers were built out of transistorized memory in the 1960s, and IBM computers used transistorized memory for microcode store and caches in 1970, building main memory out of transistors remained prohibitively expensive until the development of the integrated circuit. With the integrated circuit, it became possible to build a DRAM (dynamic random access memory—see Appendix C for a description). The first DRAMs were built at Intel in 1970, and the computers using DRAM memories (as a high-speed option to core) came shortly thereafter; they used 1 Kbit DRAMs. In fact, computer folklore says that Intel developed the microprocessor partly to help

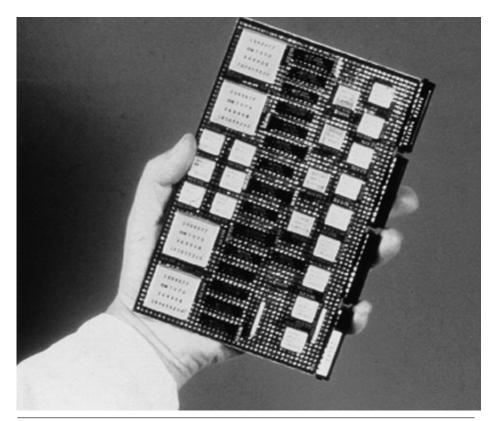


FIGURE e5.17.3 An early DRAM board. This board uses 18 Kbit chips.

sell more DRAM. Figure e5.17.3 shows an early DRAM board. By the late 1970s, core memory had become a historical curiosity. Just as core memory technology had allowed a tremendous expansion in memory size, DRAM technology allowed a comparable expansion. In the 1990s, many personal computers had as much memory as the largest computers using core memory ever had.

Nowadays, DRAMs are typically packaged with multiple chips on a little board called a DIMM (dual inline memory module). The SIMM (single inline memory module) shown in Figure e5.17.4 contains a total of 1 MB and sold for about \$5 in 1997. As of 2004, DIMMs were available with up to 1024 MB and sold for about \$100. While DRAMs will remain the dominant memory technology for some time to come, innovations in the packaging of DRAMs to provide both higher bandwidth and greater density are ongoing.

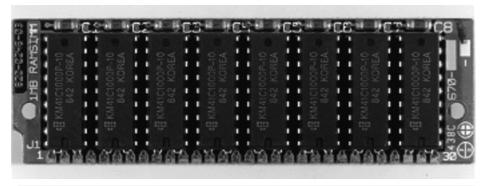


FIGURE e5.17.4 A 1MB SIMM, built in 1986, using 1Mbit chips. This SIMM sold for about \$5/MB in 1997. As of 2006, most main memory is packed in DIMMs similar to this, though using much higher-density memory chips (1 Gbit).

The Development of Memory Hierarchies

Although the pioneers of computing foresaw the need for a **memory hierarchy** and coined the term, the automatic management of two levels was first proposed by Kilburn and his colleagues and demonstrated at the University of Manchester with the Atlas computer, which implemented virtual memory. This was the year *before* the IBM 360 was announced. IBM planned to include virtual memory with the next generation (System/370), but the OS/360 operating system wasn't up to the challenge in 1970. Virtual memory was announced for the 370 family in 1972, and it was for this computer that the term *translation-lookaside buffer* was coined. The only computers today without virtual memory are a few supercomputers, and even they may add this feature in the near future.

The problems of inadequate address space have plagued designers repeatedly. The architects of the PDP-11 identified a small address space as the only architectural mistake from which it is difficult to recover. When the PDP-11 was designed, core memory densities were increasing at a very slow rate, and the competition from 100 other minicomputer companies meant that DEC might not have a cost-competitive product if every address had to go through the 16-bit datapath twice—hence, the decision to add just 4 more address bits than the predecessor of the PDP-11, to 16 from 12. The architects of the IBM 360 were aware of the importance of address size and planned for the architecture to extend to 32 bits of address. Only 24 bits were used in the IBM 360, however, because the low-end 360 models would have been even slower with the larger addresses. Unfortunately, the expansion effort was greatly complicated by programmers who stored extra information in the upper 8



"unused" address bits. The wider address lasted until 2000, when IBM expanded the architecture to 64 bits in the z-series.

Running out of address space has often been the cause of death for an architecture, while other architectures have managed to make the transition to a larger address space. For example, the PDP-11, a 16-bit computer, was replaced by the 32-bit VAX. The 80386 extended the 80286 architecture from a segmented 24-bit address space to a flat 32-bit address space in 1985. In the 1990s, several RISC instruction sets made the transition from 32-bit addressing to 64-bit addressing by providing a compatible extension of their instruction sets. MIPS was the first to do so. A decade later Intel and HP announced the IA-64 in large part to provide a 64-bit address successor to the 32-bit Intel IA-32 and HP Precision architectures. Most architects are currently betting against the revolutionary IA-64 versus the evolutionary AMD64. Both the winner and loser will certainly be noted in the history of computer architecture and in the boardrooms of both corporations.

Many of the early ideas in memory hierarchies originated in England. Just a few years after the Atlas paper, Wilkes [1965] published the first paper describing the concept of a cache, calling it a "slave":

The use is discussed of a fast core memory of, say, 32,000 words as slave to a slower core memory of, say, one million words in such a way that in practical cases the effective access time is nearer that of the fast memory than that of the slow memory.

This two-page paper describes a direct-mapped cache. Although this was the first publication on caches, the first implementation was probably a direct-mapped instruction cache built at the University of Cambridge by Scarrott and described at the 1965 IFIP Congress. It was based on tunnel diode memory, the fastest form of memory available at the time.

Subsequent to that publication, IBM started a project that led to the first commercial computer with a cache, the IBM 360/85. Gibson at IBM recognized that memory-accessing behavior would have a significant impact on performance. He described how to measure program behavior and cache behavior and showed that the miss rate varies between programs. Using a sample of 20 programs (each with 3 million references—an incredible number for that time), Gibson analyzed the effectiveness of caches using average memory access time as the metric. Conti, Gibson, and Pitowsky described the resulting performance of the 360/85 in the first paper to use the term *cache* in 1968. Since this early work, it has become clear that caches are one of the most important ideas not only in computer architecture but in software systems as well. The idea of caching has found applications in operating systems, networking systems, databases, and compilers, to name a few. There are

thousands of papers on the topic of caching, and it continues to be a popular area of research.

One of the first papers on nonblocking caches was by Kroft in 1981, who may have coined the term. He later explained that he was the first to design a computer with a cache at Control Data Corporation, and when using old concepts for new mechanisms, he hit upon the idea of allowing his two-ported cache to continue to service other accesses on a miss.

Multilevel caches were the inevitable resolution to the lack of improvement in main memory latency and the higher clock rates of microprocessors. Only those in the field for a while are surprised by the size of some second- or third-level caches, as they are larger than main memories of past machines. The other surprise is that the number of levels is continually increasing, even on a single-chip microprocessor.

Disk Storage

In 1956, IBM developed the first disk storage system with both moving heads and multiple disk surfaces in San Jose, helping to seed the development of the magnetic storage industry in the southern end of Silicon Valley. Reynold B. Johnson led the development of the IBM 305 RAMAC (Random Access Method of Accounting and Control). It could store 5 million characters (5 MB) of data on 50 disks, each 24 inches in diameter. The RAMAC is shown in Figures e5.17.5 and e5.17.6. Although the disk pioneers would be amazed at the size, cost, and capacity of modern disks, the basic mechanical design is the same as the RAMAC.

Moving-head disks quickly became the dominant high-speed magnetic storage, though their high cost meant that magnetic tape continued to be used extensively until the 1970s. The next key development for hard disks was the removable hard disk drive developed by IBM in 1962; this made it possible to share the expensive drive electronics and helped disks overtake tapes as the preferred storage medium. Figure e5.17.7 shows a removable disk drive and the multiplatter disk used in the drive. IBM also invented the floppy disk drive in 1970, originally to hold microcode for the IBM 370 series. Floppy disks became popular with the PC about 10 years later.

The sealed Winchester disk, which was developed by IBM in 1973, completely dominates disk technology today. Winchester disks benefited from two related properties. First, reductions in the cost of the disk electronics made it unnecessary to share the electronics and thus made nonremovable disks economical. Since the disk was fixed and could be in a sealed enclosure, both the environmental and control problems were greatly reduced, allowing significant gains in density. The first disk that IBM shipped had two spindles, each with a 30 MB disk; the moniker "30-30" for the disk led to the name Winchester. Winchester disks grew rapidly in popularity in the 1980s, completely replacing removable disks by the middle of that decade.

The historic role of IBM in the disk industry came to an end in 2002, when IBM sold its disk storage division to Hitachi. IBM continues to make storage subsystems, but it purchases its disk drives from others.



FIGURE e5.17.5 A magnetic drum made by Digital Development Corporation in the 1960s and used on a CDC machine. The electronics supporting the read/write heads can be seen on the outside of the drum.

A Very Brief History of Flash Memory

Flash memory was invented by researchers at Toshiba in the 1980s. They invented both the NOR-based Flash memory in 1984 and the denser NAND-based Flash memory in 1989. The first use was in digital cameras, starting with the CompactFlash form factor for NOR Flash memory and the SmartMedia form factor for NAND Flash memory. Today, all digital cameras, cell phones, music placers, and tablets rely on Flash memory, and an increasing fraction of laptops use flash memory instead of disk.



FIGURE e5.17.6 The RAMAC disk drive from IBM, made in 1956, was the first disk drive with a moving head and the first with multiple platters. The IBM storage technology Web site has a discussion of IBM's major contributions to storage technology.

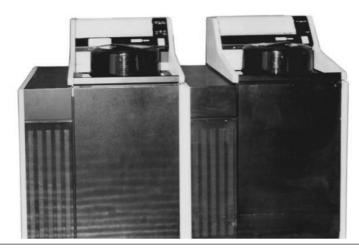


FIGURE e5.17.7 This is a DEC disk drive and the removable pack. These disks became popular starting in the mid-1960s and dominated disk technology until Winchester drives in the late 1970s. This drive was made in the mid-1970s; each disk pack in this drive could hold 80 MB.

A Brief History of Databases

Although there had been data stores of punch cards and later magnetic tapes, the emergence of the magnetic disk led to modern databases.

In 1961, Charles Bachman at General Electric created a pioneering database management system called Integrated Data Store (IDS) to take advantage of the new magnetic disks. In 1971, Bachman and others published standards on how to manage databases using Cobol programs, named the Codasyl approach after

the standards committee on which they served. Many companies offered Codasyl-compatible databases, but not IBM. In 1968 IBM had introduced IMS, which was derived from IBM's work on the NASA Apollo project. Both Codasyl databases and IMS are classified as navigational databases because programs had to navigate through the data.

Ted Codd, a researcher at IBM, thought the navigational approach was wrong-headed. He recalled that people didn't write programs when dealing with the old punch card databases. Instead, they set up data flows through series of punch card machines that would perform simple functions like copy or sort. Once the card machines were set up, you just pushed all the cards through to get your results. In his view, users should only declare the type of data they were looking for and leave it up to computers to process it. In 1970, he published a new way to organize and access data called the relational model. It was based on set theory; data was independent of the implementation and users described what they were looking for in a declarative, nonprocedural language.

This paper led to considerable controversy within IBM, because it already had a database product. Codd even arranged a public debate between him and Bachman, which led to internal criticism at IBM that Codd was undermining IMS. The good news was that the debate led researchers at IBM and U.C. Berkeley to try to demonstrate the viability of relational databases by building System R and Ingres.

System R in 1974–79 demonstrated its feasibility and, perhaps more importantly, created the Structured Query Language (SQL) that is still widely used today. However, these results were not sufficient to convince IBM, and some of the researchers left IBM to build relational databases for other companies.

Mike Stonebraker and Gene Wong were interested in geographic data systems, and in 1973 they decided to pursue relational databases. Rather than build on IBM mainframes, the Ingres project was built on DEC minicomputers and Unix. Ingres was important because it led to a company that tried to commercialize the ideas, because 1000 copies of its source code were openly distributed, and because it trained a generation of database developers and researchers. The code and people led to many other companies, including Sybase. Larry Ellison started Oracle by first reading the papers from the System R and Ingres groups and then by hiring people who worked on those projects. Microsoft later purchased a copy of Sybase sources that became the foundation of its SQL Server product.

Relational databases matured in the 1980s, with IBM developing its own relational databases, including DB2. The 1990s saw both the development of object-oriented databases, to address the impedance mismatch between databases and programming, and the evolution of parallel databases for analytic processing and data mining.

ACM showered awards on this community. The ACM Turing Award went to Charles Bachman in 1973 for his contributions via IDS and the Codasyl group. Codd won it in 1980 for the relational model. In 1988, the developers of System R (Donald Chamberlin, Jim Gray, Raymond Lorie, Gianfranco Putzolu, Patricia Selinger, and Irving Traiger) shared the ACM Systems Software Award with the developers of Ingres (Gerald Held, Michael Stonebraker, and Eugene Wong). Jim

Gray won the Turing Award in 1998 for his contributions to transaction processing and databases. Finally, the first two ACM SIGMOD Innovations Awards went to Stonebraker and Gray, and the 2002 and 2003 editions went to Selinger and Chamberlin.

RAID

The small-form-factor hard disks for PCs in the mid-1980s led a group at Berkeley to propose redundant arrays of inexpensive disks (RAID). This group had worked on the reduced instruction set computer effort, and so expected much faster processors to become available. Their two questions were: What could be done with the small disks that accompanied their PCs? What could be done in the area of I/O to keep up with much faster processors? They argued to replace one large mainframe drive with 50 small drives, as you could get much greater performance with that many independent arms. The many small drives even offered savings in power consumption and floor space.

The downside of many disks was much lower MTTF. Hence, on their own they reasoned out the advantages of redundant disks and rotating parity to address how to get greater performance with many small drives yet have reliability as high as that of a single mainframe disk.

The problem they experienced when explaining their ideas was that some researchers had heard of disk arrays with some form of redundancy, and they didn't understand the Berkeley proposal. Hence, the first RAID paper [Patterson, Gibson, and Katz 1987] is not only a case for arrays of small-form-factor disk drives, but also something of a tutorial and classification of existing work on disk arrays. Mirroring (RAID 1) had long been used in fault-tolerant computers such as those sold by Tandem. Thinking Machines had arrays with 32 data disks and 7 check disks using ECC for correction (RAID 2) in 1987, and Honeywell Bull had a RAID 2 product even earlier. Also, disk arrays with a single parity disk had been used in scientific computers in the same time frame (RAID 3). Their paper then described a single parity disk with support for sector accesses (RAID 4) and rotated parity (RAID 5). Chen et al. [1994] survey the original RAID ideas, commercial products, and other developments.

Unknown to the Berkeley group, engineers at IBM working on the AS/400 computer also came up with rotated parity to give greater reliability for a collection of large disks. IBM filed a patent on RAID 5 shortly before the Berkeley group submitted their paper. Patents for RAID 1, RAID 2, and RAID 3 from several companies predate the IBM RAID 5 patent, which has led to plenty of courtroom action.

EMC had been a supplier of DRAM boards for IBM computers, but around 1988 new policies from IBM made it nearly impossible for EMC to continue to sell IBM memory boards. The Berkeley paper crossed the desks of EMC executives, and so they decided to go after the market dominated by IBM disk storage products. As the paper advocated, their model was to use many small drives to compete with mainframe drives, and EMC announced a RAID product in 1990. It relied on

mirroring (RAID 1) for reliability; RAID 5 products came much later for EMC. Over the next year, Micropolis offered a RAID 3 product; Compaq offered a RAID 4 product; and Data General, IBM, and NCR offered RAID 5 products.

The RAID ideas soon spread to the rest of the workstation and server industry. An article explaining RAID in *Byte* magazine led to RAID products being offered on desktop PCs, which was something of a surprise to the Berkeley group. They had focused on performance with good availability, but higher availability was attractive to the PC market.

Another surprise was the cost of the disk arrays. With redundant power supplies and fans, the ability to "hot-swap" a disk drive, the RAID hardware controller itself, the redundant disks, and so on, the first disk arrays cost many times the cost of the disks. Perhaps as a result, the "inexpensive" in RAID morphed into "independent." Many marketing departments and technical writers today know of RAID only as "redundant arrays of independent disks."

In 2004, more than 80% of the nondesktop drive sales were found in RAIDs. In recognition of their role, in 1999 Garth Gibson, Randy Katz, and David Patterson received the IEEE Reynold B. Johnson Information Storage Award "for the development of Redundant Arrays of Inexpensive Disks (RAID)."

Protection Mechanisms

Architectural support for protection has varied greatly over the past 20 years. In early computers, before virtual memory, protection was very simple at best. In the 1960s, more elaborate mechanisms that supported different protection levels (called rings) were invented. In the late 1970s and early 1980s, very elaborate mechanisms for protection were devised and later built; these mechanisms supported a variety of powerful protection schemes that allowed controlled instances of sharing, in such a way that a process could share data while controlling exactly what was done to the data. The most powerful method, called *capabilities*, created a data object that described the access rights to some portion of memory. These capabilities could then be passed to other processes, thus granting access to the object described by the capability. Supporting this sophisticated protection mechanism was both complex and costly, because creation, copying, and manipulation of capabilities required a combination of operating system and hardware support. Recent computers all support a simpler protection scheme based on virtual memory, similar to that discussed in Section 5.7. Given current concerns about computer security due to the costs of worms and viruses, perhaps we will see a renaissance in protection research, potentially renewing interest in 20-year-old publications.

As mentioned in the text, system virtual machines were pioneered at IBM as part of its investigation into virtual memory. IBM's first computer with virtual memory was the IBM 360/67, introduced in 1967. IBM researchers wrote the program CP-67, which created the illusion of several independent 360 computers. They then wrote an interactive, single-user operating system called CMS that ran on these virtual machines. CP-67 led to the product VM/370, and today IBM sells z/VM for its mainframe computers.

A Brief History of Modern Operating Systems

MIT developed the first timesharing system, CTSS (Compatible Time-Sharing System), in 1961. John McCarthy is generally given credit for the idea of timesharing, but Fernando Corbato was the systems person who realized the concept in the form of the CTSS. CTSS allowed three people to share a machine, and its response time of minutes or seconds was a dramatic improvement over the batch processing system it replaced. Moreover, it demonstrated the value of interactive computing.

Flush with the success of their first system, this group launched into their second system, MULTICS (Multiplexed Information and Computing Service). They included many innovations, such as strong protection, controlled sharing, and dynamic libraries. However, it suffered from the "second system effect." Fred Brooks, Jr. described the second system effect in his classic book about lessons learned from developing an operating system for the IBM mainframe, *The Mythical Man Month*:

When one is designing the successor to a relatively small, elegant, and successful system, there is a tendency to become grandiose in one's success and design an elephantine feature-laden monstrosity.

MULTICS took sharing to a logical extreme to discover the issues, including that it was too extreme. MIT, General Electric, and later Bell Labs all tried to build an economical and useful system. Despite a great deal of time and money, they did not succeed.

Berkeley was building their own timesharing system, Cal TSS. The people leading that project included Peter Deutsch, Butler Lampson, Chuck Thacker, and Ken Thompson. They added paging virtual memory hardware to an SDS 920 and wrote an operating system for it. SDS sold this computer as the SDS-930, and it was the first commercially available timesharing system to have operational hardware and software. Thompson graduated and joined Bell Labs. The others founded Berkeley Computer Corporation (BCC), with the goal of selling time-sharing hardware and software. We'll pick up BCC later in the story, but for now let's follow Thompson.

At Bell Labs in 1971, Thompson led the development of a simple timesharing system that had some of the good ideas of MULTICS but left out many of the complex features. To demonstrate the contrast, it was first called UNICS. As they were joined by others at Bell Labs who had been burned from the MULTICS experience, it was renamed UNIX, with the *x* coming from Phoenix, the legendary bird that rose from the ashes.

Their result was the most elegant operating system ever built. Forced to live in the 16-bit address space of the DEC minicomputers, it had an amazing amount of functionality per line of code. Major contributions were pipes, a uniform file system, a uniform process model, and the shell user interface that allowed users to connect programs together using pipes and files.

Dennis Ritchie joined the UNIX team in 1973 from MIT, where he had experience in MULTICS, which was written in a high-level language. Like prior operating systems, UNIX had been written in assembly language. Ritchie designed a language for system implementation called C, and it was used to make UNIX portable.

Between 1971 and 1976, Bell released six editions of the UNIX timesharing system. Thompson took a sabbatical at his alma mater and brought UNIX with him. Berkeley and many other universities began to use UNIX on the popular PDP-11 minicomputer.

When DEC announced the VAX, a 32-bit virtual address successor to the PDP-11, the question arose as to what operating system should be run. UNIX became the first operating system to port to a different computer when it was ported to the VAX.

Students at Berkeley had one of the first VAXes, and they were soon adding features to UNIX for the VAX, such as paging and a very efficient implementation of the TCP/IP protocol. The Berkeley implementation of TCP/IP was notable not just because it was fast. It was essentially the *only* implementation of TCP/IP for years, since early implementations in most other operating systems consisted of copying the Berkeley code verbatim, with minimal changes to integrate into the local system.

The Advanced Research Project Agency (ARPA), which funded computer science research, asked a Stanford professor, Forrest Basket, to recommend which system the academic community should use: the DEC operating system VMS, led by David Cutler, or the Berkeley version of UNIX, led by a graduate student named Bill Joy. He recommended the latter, and Berkeley UNIX soon became the academic standard bearer.

The Berkeley Software Distribution (BSD) of UNIX, first released in 1978, was essentially one of the first open source movements. The sources were shipped with the tapes, and systems developers around the world learned their craft by studying the UNIX code.

BSD was also the first split of UNIX, because AT&T Bell Labs continued to develop UNIX on its own. This eventually led to a forest of UNIXes, as each company compiled the UNIX source code for their architecture. Bill Joy graduated from Berkeley and helped found Sun Microsystems, so naturally Sun OS was based on BSD UNIX. Among the many UNIX flavors were Santa Cruz Operation UNIX, HP-UX, and IBM's AIX. AT&T and Sun attempted to unify UNIX by striking a deal whereby AT&T and Sun would combine forces and jointly develop AT&T UNIX. This led to an adverse reaction from HP, IBM, and others, because they did not want a competitor supplying their code, so they created the Open Source Foundation as a competing organization.

In addition to the UNIX variants from companies, public domain versions also proliferated. The BSD team at Berkeley rewrote substantial portions of UNIX so that they could distribute it without needing a license from AT&T. This eventually led to a lawsuit, which Berkeley won. BSD UNIX soon split into FreeBSD, NetBSD, and OpenBSD, provided by competing camps of developers. Apple's current operating system, OS X, is based on Free BSD.

Let's go back to Berkeley Computer Corporation. Alas, this effort was not commercially viable. About the same time as BCC was getting in trouble, Xerox hired Robert Taylor to build the computer science division of the new Xerox Palo

Alto Research Center (PARC) in 1970. He had just returned from a tour of duty at ARPA, where he had funded the Berkeley research. He recruited Deutsch, Lampson, and Thacker from BCC to form the core of PARC's team: 11 of the first 20 employees were from BCC, and they decided to build small computers for individuals rather than large computers for groups. This first personal computer, called the Alto, was built from the same technology as minicomputers, but it had a keyboard, mouse, graphical display, and windows. It popularized windows and led to many inventions, including client-server computing, the Ethernet, and print servers. It directly inspired the Macintosh, which was the successor to the popular Apple II.

IBM had long been interested in selling to the home, so the success of the Apple II led IBM to start a competing project. In contrast to its tradition, for this project IBM designed everything from components outside of the company. They selected the new 16-bit microprocessor from Intel, the 8086. (To lower costs, they started with the version with the 8-bit bus, called the 8088.) They visited Microsoft to see if this small company would be willing to sell their popular Basic interpreter and asked for recommendations for an operating system. Gates volunteered that Microsoft could deliver both an interpreter and an operating system, as long as they were paid a royalty fee of between \$10 and \$50 for each copy rather than a flat fee. IBM agreed, provided Microsoft could meet their deadlines. Microsoft didn't have an operating system, nor the time and resources to build one, but Gates knew that a Seattle company had developed an operating system for the Intel 8086. Microsoft purchased QDOS (Quick and Dirty Operating System) for \$15,000, made a small change and relabeled it MS-DOS. MS-DOS was a simple operating system without any modern features—no protection, no processes, and no virtual memory—in part because they believed it wasn't necessary for a personal computer.

Announced in 1980, the IBM PC became a tremendous success for IBM and the companies it relied upon. Microsoft sold 500,000 copies of MS-DOS by 1983, and the \$10 million income allowed Microsoft to start new software projects.

After seeing a version of the Macintosh under development, Microsoft hired some people from PARC to lead its reply. The Macintosh was announced in 1984, and Windows was available on PCs the following year. It was originally an application that ran on top of DOS, but was later integrated with DOS and renamed Windows 2.0. Microsoft hired Cutler from DEC to lead the development of Windows NT, a new operating system. NT was a modern operating system with protection, processors, and so on and has much in common with DEC's VMS. Today's PC operating systems are more sophisticated than any of the timesharing systems of 20 years ago, yet they still suffer from the need to maintain compatibility with the crippled first PC operating systems such as MS-DOS.

The popularity of the PC led to a desire for a UNIX that ran on it. Many tried to develop one, but the most successful was written from scratch in 1991 by Linus Torvalds. In addition to making the source code available, like BSD, he allowed everyone to make changes and submit them for inclusion in his next release. Linux popularized open source development as we know it today, with such software getting hundreds of volunteers to test releases and add new features.

Many people in this story won awards for their roles in the development of modern operating systems. McCarthy received an ACM Turing Award in 1971 in part for his contributions to timesharing. In 1983, Thompson and Ritchie received one for UNIX. The announcement said that "the genius of the UNIX system is its framework, which enables programmers to stand on the work of others." In 1990, Corbato received the Turing Award for his contributions to CTSS and MULTICS. Two years later, Lampson won it in part for his work on personal computing and operating systems.

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