

RESEARCH PAPER

FRACTIONAL-HYPERBOLIC SYSTEMS

Anatoly N. Kochubei

Abstract

We describe a class of evolution systems of linear partial differential equations with the Caputo-Dzhrbashyan fractional derivative of order $\alpha \in (0, 1)$ in the time variable t and the first order derivatives in spatial variables $x = (x_1, \dots, x_n)$, which can be considered as a fractional analogue of the class of hyperbolic systems. For such systems, we construct a fundamental solution of the Cauchy problem having exponential decay outside the fractional light cone $\{(t, x) : |t^{-\alpha}x| \leq 1\}$.

MSC 2010: Primary 35R11, 35L99

Key Words and Phrases: hyperbolic systems; Caputo-Dzhrbashyan fractional derivative; fundamental solution of the Cauchy problem

1. Introduction

Evolution equations with fractional time derivatives are among central objects of the modern theory of partial differential equations – due both to various physical applications (dynamical processes in fractal and viscoelastic media [16],[18],[21]) and to the rich mathematical content of this subject; see, for example, the monographs [4],[12] and references therein. The theory has reached sufficient maturity to investigate not only specific classes of equations like fractional diffusion and diffusion-wave equations, but to study general systems of fractional-differential equations. In particular, Heibig [10] obtained an L^2 -existence theorem for general fractional systems while the author [13] investigated a class of fractional-parabolic systems.

In this paper we turn to a fractional version of a class of first order hyperbolic systems with constant coefficients (for the classical material, see [1],[3],[8],[22]). A prototype is the *fractional diffusion-wave equation*

$$\left(\mathbb{D}_t^{(\beta)} u\right)(t, x) = \Delta u(t, x), \quad t \in (0, T], \quad x \in \mathbb{R}^n, \quad (1.1)$$

where $1 < \beta < 2$, $\mathbb{D}_t^{(\beta)}$ is the *Caputo-Dzhrbashyan fractional derivative*, that is

$$\begin{aligned} \left(\mathbb{D}_t^{(\beta)} u\right)(t, x) = & \frac{1}{\Gamma(2-\beta)} \frac{\partial^2}{\partial t^2} \int_0^t (t-\tau)^{-\beta+1} u(\tau, x) d\tau \\ & - t^{-\beta+1} \frac{u_t(0, x)}{\Gamma(2-\beta)} - t^{-\beta} \frac{u(0, x)}{\Gamma(1-\beta)}. \end{aligned} \quad (1.2)$$

Below we explain how to reduce equation (1.1) to a system of equations of order $\beta/2 \in (0, 1)$ in t and of the first order in spatial variables.

This equation was studied by many authors ([7],[9],[14],[15],[19],[20] and others). For the Cauchy problem corresponding to the initial conditions

$$u(0, x) = u_0(x), \quad u_t(0, x) = 0, \quad (1.3)$$

a solution is obtained as a convolution with the Green kernel,

$$u(t, x) = \int_{\mathbb{R}^n} G(t, x - \xi) u_0(\xi) d\xi, \quad (1.4)$$

where, as it was proved in [7] for $n = 1$, and in [19] for the general case,

$$|G(t, x)| \leq C t^{-\frac{\beta n}{2}} \gamma_n(|x| t^{-\beta/2}) E(|x| t^{-\beta/2}),$$

$$\gamma_n(z) = \begin{cases} 1, & \text{if } n = 1, \\ |\log z|, & \text{if } n = 2, \\ z^{-n+2}, & \text{if } n \geq 3, \end{cases}$$

$$E(z) = \exp\left(-a z^{\frac{2}{2-\beta}}\right), \quad C, a > 0$$

(here and below the letters C, a will denote various positive constants).

For a comparison, note that for the wave equation corresponding formally to $\beta = 2$, with the initial conditions (1.3), a counterpart of the kernel G from (1.4) is a distribution supported on the light cone $\{|x|t^{-1} \leq 1\}$, if n is even, or its boundary, if n is odd. There is a similar behavior, for example, for some symmetric hyperbolic systems of the first order.

Thus in the fractional order case, though the fundamental solution of the Cauchy problem (FSCP) is not concentrated on the set $\{|x|t^{-\frac{\beta}{2}} \leq 1\}$, it decays exponentially outside it, possessing a kind of *weak hyperbolicity*

property. Of course, the equation (1.1) “*interpolates*” between the heat and wave equations, and possesses some “*parabolic*” properties too, as it is clear from (1.4).

In this paper we describe a class of general time-fractional systems of partial differential equations with constant coefficients, of the form

$$\left(\mathbb{D}_t^{(\alpha)} u_j\right)(t, x) = \sum_{k=1}^m P_{jk} \left(i \frac{\partial}{\partial x}\right) u_k(t, x), \quad j = 1, \dots, m, \quad 0 < t \leq T, x \in \mathbb{R}^n, \quad (1.5)$$

where $0 < \alpha < 1$,

$$\left(\mathbb{D}_t^{(\alpha)} \varphi\right)(t) = \frac{1}{\Gamma(1-\alpha)} \left[\frac{\partial}{\partial t} \int_0^t (t-\tau)^{-\alpha} \varphi(\tau) d\tau - t^{-\alpha} \varphi(0) \right],$$

P_{jk} are first order polynomials with complex coefficients from the derivatives $i \frac{\partial}{\partial x_1}, \dots, i \frac{\partial}{\partial x_n}$ ($i = \sqrt{-1}$), for which, as in the above example, there exists a FSCP with an exponential decay away from the set $\{|x|t^{-\alpha} \leq 1\}$. This property implies the existence of solutions for the initial functions with exponential growth. We call such systems “*fractional-hyperbolic*”. We follow the techniques by Gel’fand and Shilov [8] and Friedman [6], with modifications needed to cover the fractional situation.

2. Auxiliary Results

2.1. Derivatives of the Mittag-Leffler functions. The Mittag-Leffler function

$$E_\alpha(z) = \sum_{l=0}^{\infty} \frac{z^l}{\Gamma(\alpha l + 1)} \quad (2.1)$$

is a fractional calculus counterpart of the exponential function. The function $u(t) = E(\lambda t^\alpha)$ is a solution of the Cauchy problem $(\mathbb{D}_t^{(\alpha)} u)(t) = \lambda u(t)$, $u(0) = 1$ ($0 < \alpha < 1$, $\lambda \in \mathbb{C}$); this representation of the solution remains valid for matrix-valued solutions in the case where λ is a matrix.

The generalized Mittag-Leffler functions

$$E_{\alpha, \gamma}(z) = \sum_{l=0}^{\infty} \frac{z^l}{\Gamma(\alpha l + \gamma)} \quad (2\text{-index})$$

and

$$E_{\alpha, \gamma}^\rho(z) = \sum_{l=0}^{\infty} \frac{(\rho)_l}{\Gamma(\alpha l + \gamma)} \frac{z^l}{l!} \quad (3\text{-index}),$$

where

$$(\rho)_l = \rho(\rho+1) \cdots (\rho+l-1), \quad l \geq 1; \quad (\rho)_0 = 1,$$

are also very useful and popular in fractional calculus related problems.

In this paper we will need estimates for derivatives of the function (2.1). It is known (see the identities (1.8.23) and (1.9.1) in [12]) that

$$\frac{d^k}{dz^k} E_\alpha(z) = k! E_{\alpha, 1+\alpha k}^{k+1}(z) \quad (2.2)$$

and

$$E_{\alpha, \gamma}^\rho(z) = \frac{1}{\Gamma(\rho)} {}_1\Psi_1 \left[\begin{matrix} (\rho, 1) \\ (\gamma, \alpha) \end{matrix} \middle| z \right].$$

Here ${}_1\Psi_1$ is the Wright function,

$${}_1\Psi_1 \left[\begin{matrix} (\rho, 1) \\ (\gamma, \alpha) \end{matrix} \middle| z \right] = \sum_{l=0}^{\infty} \frac{\Gamma(l+\rho)}{\Gamma(\alpha l + \gamma)} \frac{z^l}{l!}.$$

The asymptotic behavior of ${}_1\Psi_1$ as $z \rightarrow \infty$ was studied in [23], [2]. The results for our case are as follows. If $|\arg z| \leq \frac{\pi\alpha}{2} - \varepsilon$, $0 < \varepsilon < \frac{\pi\alpha}{2}$, then

$$E_{\alpha, \gamma}^\rho(z) \sim \text{const} \cdot \exp(z^{1/\alpha}), \quad z \rightarrow \infty. \quad (2.3)$$

If $|\arg(-z)| \leq (1 - \frac{\alpha}{2})\pi - \varepsilon$, $0 < \varepsilon < (1 - \frac{\alpha}{2})\pi$, then

$$E_{\alpha, \gamma}^\rho(z) \sim Q(-z), \quad z \rightarrow \infty, \quad (2.4)$$

where $Q(z)$ is the sum of residues of the function

$$s \mapsto z^s \Gamma(-s) \Gamma(s + \rho) / \Gamma(\alpha s + \gamma)$$

at the points $s = -\rho - \nu$, $\nu = 0, 1, 2, \dots$. This means that

$$|E_{\alpha, \gamma}^\rho(z)| \leq C|z|^{-\rho}, \quad |z| \geq 1, |\arg(-z)| \leq (1 - \frac{\alpha}{2})\pi - \varepsilon. \quad (2.5)$$

For the remaining region, $\frac{\alpha\pi}{2} - \varepsilon \leq \pm \arg z \leq \frac{\alpha\pi}{2} + \varepsilon$, where $\varepsilon > 0$ is small enough,

$$E_{\alpha, \gamma}^\rho(z) \sim Q(\mp z) + \exp(z^{1/\alpha}). \quad (2.6)$$

It follows from (2.2), (2.4), and (2.5) that for any $\varepsilon > 0$,

$$\left| \frac{d^k}{dz^k} E_\alpha(z) \right| \leq \begin{cases} C e^{\text{Re } z^{1/\alpha}}, & \text{if } |\arg z| \leq \frac{\alpha\pi}{2}, \\ C_\varepsilon (1 + |z|)^{-k-1}, & \text{if } |\arg z| > \frac{\alpha\pi}{2} + \varepsilon. \end{cases} \quad (2.7)$$

By (2.6),

$$\left| \frac{d^k}{dz^k} E_\alpha(z) \right| \leq C, \quad \text{if } |\arg z| \geq \frac{\alpha\pi}{2}. \quad (2.8)$$

2.2. Eskin's extension of the Paley-Wiener-Schwartz theorem. The Paley-Wiener-Schwartz theorem gives an interpretation of a subclass of the class of entire functions of exponential type as the set of Fourier transforms of distributions with compact supports. Eskin [5] considered the case of entire functions of order greater than 1.

PROPOSITION 1 (Eskin [5]). Let $Q(s) = Q(s_1, \dots, s_n)$, $s_1, \dots, s_n \in \mathbb{C}$, be an entire function of order $p > 1$ satisfying the inequality

$$|Q(\sigma + i\tau)| \leq C(1 + |\sigma|)^l e^{a|\tau|^p}, \quad \sigma, \tau \in \mathbb{R}^n, \quad (2.9)$$

where l is a nonnegative integer. Consider $Q(\sigma)$, $\sigma \in \mathbb{R}^n$, as a distribution from $\mathcal{S}'(\mathbb{R}^n)$. Then its Fourier transform $\tilde{Q}$ has the form

$$\tilde{Q}(x) = \sum_{k=1}^N R_k \left(\frac{\partial}{\partial x} \right) F_k(x) \quad (2.10)$$

(in the distribution sense), where the orders of the differential operators R_k do not exceed $l + n + 1$, if this number is even, or $l + n + 2$ otherwise, F_k are continuous functions satisfying, for any $\varepsilon > 0$, the inequality

$$|F_k(x)| \leq C_\varepsilon e^{-(b-\varepsilon)|x|^{p'}}, \quad k = 1, \dots, N, \quad (2.11)$$

with $\frac{1}{p} + \frac{1}{p'} = 1$, $b = \frac{1}{p'} \left(\frac{1}{ap} \right)^{p'/p}$.

In a further generalization we consider the case where the function Q depends on an additional parameter $t \in [0, T]$, is continuous in (s, t) , and both the functions Q and $\mathbb{D}_t^{(\alpha)} Q$ ($0 < \alpha < 1$) have the upper bounds (2.9) with all the parameters independent of t . Then in (2.10), the operators R_k do not depend on t , the functions F_k and $\mathbb{D}_t^{(\alpha)} F_k$ are continuous in (x, t) and have the upper bounds as in (2.11) with all the parameters independent of t . This follows easily from the proof given in [5] and was noticed (for $\alpha = 1$) by Friedman ([6], Theorem 3').

3. Fractional Hyperbolicity

3.1. Definition. Let us consider system (1.5). It is convenient to use its vector form

$$\left(\mathbb{D}_t^{(\alpha)} U \right) (t, x) = \mathbf{P} \left(i \frac{\partial}{\partial x} \right) U(t, x), \quad 0 < t \leq T, x \in \mathbb{R}^n, \quad (3.1)$$

where U is a function with values in $\mathbb{C}^m$, $\mathbf{P}$ is a $m \times m$ matrix whose elements are first order differential operators. In the “dual” representation, $\mathbf{P}(s)$ is a matrix whose elements are polynomials in the variables $s_1, \dots, s_n$ of degree 1.

Denote by $\lambda_1(s), \dots, \lambda_m(s)$ the roots of the characteristic equation

$$\det(\mathbf{P}(s) - \lambda I) = 0.$$

Let

$$\Lambda_\alpha(s) = \max_{|\arg \lambda_k(s)| \leq \alpha\pi/2} \operatorname{Re} \lambda_k^{1/\alpha}(s). \quad (3.2)$$

If $|\arg \lambda_k(s)| > \alpha\pi/2$ for all $k = 1, \dots, m$, then we set $\Lambda_\alpha(s) = 0$. In any case, $\Lambda_\alpha(s) \geq 0$.

We call the system (3.1) *fractional-hyperbolic*, if

$$\Lambda_\alpha(s) \leq C \left(|\tau|^{1/\alpha} + \log(|\sigma| + 1) \right), \quad s \in \mathbb{C}^n, \quad (3.3)$$

where $s = \sigma + i\tau$, $\sigma, \tau \in \mathbb{R}^n$.

3.2. Special classes of systems. Let us consider systems satisfying the condition

$$\operatorname{Re} \lambda_k(s) \leq a|\tau| + b \quad (k = 1, \dots, m) \quad (3.4)$$

where $a, b \geq 0$. Then (3.3) is satisfied. Indeed, if $|\arg \lambda_k(s)| \leq \alpha\pi/2$, then

$$\operatorname{Re} \lambda_k^{1/\alpha}(s) = |\lambda_k(s)|^{1/\alpha} \cos\left(\frac{1}{\alpha} \arg \lambda_k(s)\right).$$

An elementary investigation shows that $\cos(\frac{1}{\alpha}\varphi) \leq (\cos \varphi)^{1/\alpha}$, if $|\varphi| \leq \alpha\pi/2$. Therefore

$$\operatorname{Re} \lambda_k^{1/\alpha}(s) \leq (\operatorname{Re} \lambda_k(s))^{1/\alpha} \leq (a|\tau| + b)^{1/\alpha} \leq C \left(|\tau|^{1/\alpha} + 1 \right),$$

which implies (3.3).

Note that the condition (3.4) is slightly stronger than the Gel'fand-Shilov hyperbolicity condition for differential systems [8].

An important class of fractional-hyperbolic systems is that of “symmetric systems”

$$\left(\mathbb{D}_t^{(\alpha)} U \right) (t, x) + \sum_{\nu=1}^n A_\nu \frac{\partial U(t, x)}{\partial x_\nu} + BU(t, x) = 0, \quad (3.5)$$

where A_ν , $\nu = 1, \dots, n$, are Hermitian matrices, B is an arbitrary matrix. In this case

$$\mathbf{P}(s) = i \left(\sum_{\nu=1}^n s_\nu A_\nu + iB \right).$$

Let $\mu_k(s)$, $k = 1, \dots, n$, be the eigenvalues of the matrix $L(s) = \sum_{\nu=1}^n s_\nu A_\nu + iB$. Then $\operatorname{Re} \lambda_k(s) = \operatorname{Im} \mu_k(s)$ for each k . By Hirsch's theorem (see Theorem 1.3.1 in Chapter 3 of [17]), $|\mu_k(s)| \leq nM$ where M is the maximum of absolute values of elements of the matrix $\frac{1}{2i}(L(s) - L(s)^*) = \sum_{\nu=1}^n \tau_\nu A_\nu + i(B - B^*)$. This implies the inequality (3.4).

3.3. Reduction of the diffusion-wave equation to a system. Let us consider the diffusion-wave equation (1.1) (where $1 < \beta < 2$) with the

initial conditions

$$u(0, x) = u_0(x), \quad u_t(0, x) = u_1(x), \quad (3.6)$$

where u_0, u_1 are continuous functions. In this section we deal with classical solutions, that is we assume that $u \in C^2$ in the spatial variables, $u \in C^1$ jointly in all the variables, there exists, for each $t > 0$, the Riemann-Liouville fractional derivative

$$\left(D_{0+,t}^\beta u\right)(t, x) = \frac{1}{\Gamma(2-\beta)} \frac{\partial^2}{\partial t^2} \int_0^t (t-\tau)^{-\beta+1} u(\tau, x) d\tau,$$

and the equalities (1.1) and (3.6) are satisfied pointwise.

Denote $v(t, x) = (\mathbb{D}^{(\beta/2)} u)(t, x)$. On a function $\varphi \in C^1$,

$$\left(\mathbb{D}^{(\beta/2)} \varphi\right)(t) = \frac{1}{\Gamma(1-\frac{\beta}{2})} \int_0^t (t-\tau)^{-\beta/2} \varphi'(\tau) d\tau, \quad (3.7)$$

so that

$$\left| \left(\mathbb{D}^{(\beta/2)} \varphi\right)(t) \right| \leq C t^{1-\frac{\beta}{2}} \rightarrow 0, \quad \text{as } t \rightarrow 0.$$

Therefore $v(0, x) = 0$, and $\mathbb{D}^{(\beta/2)} v$ coincides with the Riemann-Liouville fractional derivative

$$\left(D_{0+,t}^{\beta/2} v\right)(t, x) = \frac{1}{\Gamma(1-\frac{\beta}{2})} \frac{\partial}{\partial t} \int_0^t (t-\tau)^{-\beta/2} v(\tau, x) d\tau,$$

In order to calculate $D_{0+,t}^{\beta/2} v$, we write, as in (3.7),

$$v(t, x) = I_{0+,t}^{1-\frac{\beta}{2}} u_t(t, x),$$

where

$$\left(I_{0+,t}^\gamma \varphi\right)(t) = \frac{1}{\Gamma(\gamma)} \int_0^t (t-\tau)^{\gamma-1} \varphi(\tau) d\tau, \quad \gamma > 0,$$

is the Riemann-Liouville fractional integral. Using the identity $I_{0+}^{\gamma_1} I_{0+}^{\gamma_2} = I_{0+}^{\gamma_1+\gamma_2}$ ([12], (2.1.30)) we find that

$$D_{0+}^{\beta/2} v = D_{0+}^{\beta/2} I_{0+}^{1-\frac{\beta}{2}} u_t = \frac{\partial}{\partial t} I_{0+}^{1-\frac{\beta}{2}} I_{0+}^{1-\frac{\beta}{2}} u_t = \frac{\partial}{\partial t} I_{0+}^{2-\beta} u_t = \frac{\partial}{\partial t} \left(\mathbb{D}^{(\beta-1)} u\right),$$

so that

$$\begin{aligned} \left(D_{0+,t}^{\beta/2}v\right)(t,x) &= \frac{\partial}{\partial t} \left[\left(D_{0+,t}^{\beta-1}u\right)(t,x) - \frac{u_0(x)}{\Gamma(2-\beta)}t^{-\beta+1} \right] \\ &= \frac{\partial}{\partial t} \left(D_{0+,t}^{\beta-1}u \right)(t,x) - \frac{u_0(x)}{\Gamma(1-\beta)}t^{-\beta}. \end{aligned}$$

Since $\frac{\partial}{\partial t}D_{0+,t}^{\beta-1} = D_{0+,t}^{\beta}$ ([12], (2.1.34)), we obtain from definition (1.2) of $\mathbb{D}^{(\beta)}$ that

$$\left(\mathbb{D}_t^{(\beta/2)}v\right)(t,x) = \left(\mathbb{D}_t^{(\beta)}u\right)(t,x) + \frac{u_t(0,x)}{\Gamma(2-\beta)}t^{-\beta+1}.$$

We have found that the Cauchy problem (1.1), (3.6) is reduced to the inhomogeneous problem

$$\begin{aligned} \left(\mathbb{D}_t^{(\beta/2)}v\right)(t,x) &= \Delta u(t,x) + u_1(x)\frac{t^{-\beta+1}}{\Gamma(2-\beta)}, \\ \left(\mathbb{D}_t^{(\beta/2)}u\right)(t,x) &= v(t,x), \end{aligned}$$

$$v(0,x) = 0, \quad u(0,x) = u_0(x).$$

If $u_1(x) \equiv 0$, so that we consider the conditions (1.3), we can reduce the problem further, to a system of the form (3.5). Namely, we set

$$\begin{aligned} v^0(t,x) &= \left(\mathbb{D}_t^{(\beta/2)}u\right)(t,x), \\ v^j(t,x) &= \frac{\partial u(t,x)}{\partial x_j}, \quad j = 1, \dots, n. \end{aligned}$$

Denoting $V(t,x) = (v^0(t,x), v^1(t,x), \dots, v^n(t,x))$, we obtain the system

$$\left(\mathbb{D}_t^{(\beta/2)}V\right)(t,x) + \sum_{j=1}^n A_j \frac{\partial V(t,x)}{\partial x_j} = 0,$$

where

$$A_j = \begin{pmatrix} 0 & 0 & \dots & 0 & -1 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 & 0 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ -1 & 0 & \dots & 0 & 0 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 0 & 0 & 0 & \dots & 0 \end{pmatrix}$$

(-1 is in the $(j+1)$ -th place).

4. Fundamental Solution of the Cauchy Problem

4.1. Resolvent matrix-function. Looking for a FSCP satisfying (3.1) with the initial condition $U(0, x) = \delta(x)$, we apply formally the Fourier transform in x getting the Cauchy problem

$$\left(\mathbb{D}_t^{(\alpha)} \tilde{U}\right)(t, s) = \mathbf{P}(s) \tilde{U}(t, s), \quad \tilde{U}(0, s) = I,$$

where I is the unit matrix. Then

$$\tilde{U}(t, s) = E_\alpha(t^\alpha \mathbf{P}(s)). \quad (4.1)$$

The function (4.1) is called *the resolvent matrix-function* corresponding to the system (3.1).

Below we will denote the inverse Fourier transform (in the sense specified later) of the function (4.1) by $G(t, x)$ leaving the notation $U(t, x)$ for a vector-valued solution with a general initial vector-function.

PROPOSITION 2. For all $t \in (0, T)$, $x \in \mathbb{R}^n$,

$$\|E_\alpha(t^\alpha \mathbf{P}(s))\| \leq C (1 + t^\alpha |s|)^{m-1} e^{t\Lambda_\alpha(s)}. \quad (4.2)$$

Proof. Let us obtain an estimate for $\|E_\alpha(t^\alpha \mathcal{P})\|$, where $\mathcal{P}$ is an arbitrary matrix with eigenvalues $\mu_1, \dots, \mu_m$. Suppose first that all the eigenvalues are different. Then $E_\alpha(t^\alpha \mathcal{P}) = f(\mathcal{P})$ where f is the Newton interpolation polynomial

$$f(\mu) = b_1 + b_2(\mu - \mu_1) + b_3(\mu - \mu_1)(\mu - \mu_2) + \dots + b_m(\mu - \mu_1) \dots (\mu - \mu_{m-1}),$$

and the coefficients are chosen in such a way that $f(\mu_j) = E_\alpha(t^\alpha \mu_j)$, $j = 1, \dots, m$; see, for example, [11] regarding functions of matrices.

It follows from general estimates given in [8] (Chapter II, Section 6.1) that

$$|b_k| \leq \max_{\mu \in B_k} \left| \frac{d^{k-1}}{d\mu^{k-1}} E_\alpha(t^\alpha \mu) \right|, \quad k = 1, \dots, m,$$

where B_k is the smallest convex polygon containing the points $\mu_1, \dots, \mu_k$. Using (2.7) and (2.8) we come to the inequality

$$|b_k| \leq C t^{\alpha(k-1)} e^{tM}, \quad M = \max_{|\arg \mu_j| \leq \frac{\alpha\pi}{2}} \operatorname{Re} \mu_j^{1/\alpha}.$$

Therefore,

$$\begin{aligned} \|E_\alpha(t^\alpha \mathcal{P})\| &= \|f(\mathcal{P})\| \\ &\leq C e^{tM} [1 + t^\alpha (\|\mathcal{P}\| + |\mu_1|) + t^{2\alpha} (\|\mathcal{P}\| + |\mu_1|)(\|\mathcal{P}\| + |\mu_2|) + \dots] \\ &\leq C e^{tM} \left(1 + 2t^\alpha \|\mathcal{P}\| + \dots + (2t^\alpha)^{(m-1)} \|\mathcal{P}\|^{m-1}\right), \end{aligned}$$

since $|\mu_j| \leq \|\mathcal{P}\|$ for all j . Here the constant C does not depend on $\mathcal{P}$ and its eigenvalues. For continuity reasons, the above inequality holds for any matrix $\mathcal{P}$, not necessarily with distinct eigenvalues.

Now we set $\mathcal{P} = \mathbf{P}(s)$. Since $\|\mathcal{P}\|^2$ does not exceed the sum of squared absolute values of all the elements, and since polynomials appearing as elements of $\mathbf{P}(s)$ have degrees ≤ 1 , we find that $\|\mathbf{P}(s)\| \leq C(1 + |s|)$. Substituting and recalling that in this case $M = \Lambda_\alpha(s)$, we obtain the required inequality (4.2). $\square$

If our system (3.1) is fractional-hyperbolic, that is it satisfies (3.3), then it follows from (4.2) that

$$\|E_\alpha(t^\alpha \mathbf{P}(s))\| \leq C(1 + |\sigma|)^q e^{at|\tau|^{1/\alpha}} \quad (4.3)$$

with some $q > 0$. We call the minimal possible nonnegative integer q , for which (4.3) holds, *the exponent* of the system (3.1). In particular, if our system satisfies (3.4), then $q \leq m - 1$.

Note that

$$\mathbb{D}_t^{(\alpha)} E_\alpha(t^\alpha \mathbf{P}(s)) = \mathbf{P}(s) E_\alpha(t^\alpha \mathbf{P}(s)),$$

so that

$$\left\| \mathbb{D}_t^{(\alpha)} E_\alpha(t^\alpha \mathbf{P}(s)) \right\| \leq C(1 + |\sigma|)^{q+1} e^{at|\tau|^{1/\alpha}},$$

since the matrix $\mathbf{P}(i \frac{\partial}{\partial x})$ contains only first order differential operators.

4.2. The Cauchy problem. Let us consider the system (3.1) satisfying (3.3), with the initial condition $U(0, x) = U_0(x)$, $x \in \mathbb{R}^n$. A vector-function $U(t, x)$, $0 \leq t \leq T$, $x \in \mathbb{R}^n$, is called a *classical solution* of the Cauchy problem, if it is continuous in (t, x) , as well as its first derivatives in x , the fractional integral

$$(I_{0+}^{1-\alpha} U)(t, x) = \frac{1}{\Gamma(1-\alpha)} \int_0^t (t-\tau)^{-\alpha} U(\tau, x) d\tau$$

has the first derivative in t , continuous in (t, x) , and the equation (3.1) and the initial condition are satisfied pointwise.

Though our aim is to construct a classical solution of the Cauchy problem, at the first stage it will be defined as a generalized solution. Given the estimate (4.3), the further reasoning is very similar to that of [6] (in particular, to the case of correctly posed systems with positive genus μ); only the exponent $\frac{p_0}{p_0 - \mu}$, where p_0 is the reduced order, is replaced with $\frac{1}{1-\alpha}$. Therefore here and in the proof of the theorem below, we do not repeat the lengthy calculations from [6] referring instead to specific sections of Friedman's work.

Denote by $W_{\frac{1}{1-\alpha},c}$ ($c > 0$) the Frechet space of such functions $\varphi \in C^\infty(\mathbb{R})$ that for any $c' < c$,

$$\left| \varphi^{(j)}(z) \right| \leq C_{j,c'} e^{-(1-\alpha)|c'z|^{\frac{1}{1-\alpha}}}, \quad j = 0, 1, 2, \dots,$$

for all $z \in \mathbb{R}$. Our basic space Φ of test functions is the direct product of n copies of $W_{\frac{1}{1-\alpha},c}$. We will need also a larger space Φ^0 , the direct product of n copies of $W_{\frac{1}{1-\alpha},c-\varepsilon}$, $0 < \varepsilon < c$.

The Fourier transform $\mathcal{F}$ maps $W_{\frac{1}{1-\alpha},c}$ onto the space $W_{\frac{1}{\alpha},\frac{1}{c}}$ of such entire functions $\psi(s)$, $s = \sigma + i\tau$, $\sigma, \tau \in \mathbb{R}$, that for any $d > \frac{1}{c}$, $s \in \mathbb{C}$,

$$\left| s^k \psi(s) \right| \leq C_{k,d} \exp \left(\alpha |d\tau|^{\frac{1}{\alpha}} \right), \quad k = 0, 1, 2, \dots$$

Denote $\Psi = \mathcal{F}\Phi$, $\Psi^0 = \mathcal{F}\Phi^0$. These spaces have an obvious direct product structure.

It follows from the estimate (4.3) and the description of multipliers in $W_{\frac{1}{\alpha},\frac{1}{c}}$ ([8], Section I.2.4) that multiplication by $E_\alpha(t^\alpha \mathbf{P}(s))$ ($0 \leq t \leq T$) sends Ψ into Ψ^0 , if T is small enough. Therefore the above multiplication defines an action between the conjugate spaces $(\Psi^0)' \rightarrow \Psi'$. Thus, if $U_0 \in (\Phi^0)'$, then $\widetilde{U}_0 = \mathcal{F}U_0 \in (\Psi^0)' \subset \Psi'$, so that $\widetilde{U}(t, s) = E_\alpha(t^\alpha \mathbf{P}(s))\widetilde{U}_0(s)$ is a generalized solution over Ψ . Therefore,

$$U(t, x) = (G(t, \cdot) * U_0(\cdot))(x) \quad (4.4)$$

is a generalized solution in the sense of the distribution space Φ' , defined for $t \leq T$, if T is small enough.

THEOREM 3. *There exists such a positive number γ that for any initial function U_0 possessing continuous derivatives $D^\nu U_0$, $|\nu| \leq q + n + 3$ (q is the exponent of the system), such that*

$$|D^\nu U_0(x)| \leq C e^{\gamma|x|^{\frac{1}{1-\alpha}}}, \quad x \in \mathbb{R}^n, \quad (4.5)$$

the generalized solution (4.4) is a classical solution of the Cauchy problem, with the estimate

$$|U(t, x)| \leq C e^{\gamma'|x|^{\frac{1}{1-\alpha}}}, \quad 0 \leq t \leq T, x \in \mathbb{R}^n, \quad (4.6)$$

where $C, \gamma' > 0$ do not depend on t, x . The fundamental solution $G(t, x)$ has the form

$$G(t, x) = \sum_{k=1}^M R_k \left(\frac{\partial}{\partial x} \right) f_k(t, x) \quad (4.7)$$

(the differential operators R_k of orders $\leq q + n + 3$ are understood in the sense of $\mathcal{S}'(\mathbb{R}^n)$), f_k are continuous functions satisfying the estimates

$$|f_k(t, x)| \leq C e^{-\gamma_1 |t^{-\alpha} x|^{\frac{1}{1-\alpha}}}, \quad \gamma_1 > 0, \quad (4.8)$$

with the constants independent of t, x .

The properties (4.7)-(4.8) express the “fractional-hyperbolic” behavior of the class of systems considered in this paper.

Scheme of proof. The representation (4.7) with the estimates (4.8) follow from (4.3) and Proposition 1 (including its generalization described in Section 2.2). Note that the inequality (2.11) implies the estimate

$$|f_k(t, x)| \leq C_\varepsilon e^{-(\gamma_2 t^{-\frac{\alpha}{1-\alpha}} - \varepsilon)|x|^{\frac{1}{1-\alpha}}}, \quad \gamma_2 > 0,$$

Taking $\varepsilon < \frac{\gamma_2}{2} T^{-\frac{\alpha}{1-\alpha}}$ we come to (4.8) with $\gamma_1 = \gamma_2/2$.

It is shown in [6], pages 355-356, that if the convolution $U(t, x)$ defined as a distribution from Φ' is in fact a continuous function in (t, x) and has, with all the derivatives appearing in (3.1), the upper bounds like that in (4.6) with coefficients $\gamma' < (1 - \alpha)c^{\frac{1}{1-\alpha}}$, where c is the constant involved in the definition of the space Φ , then U is the classical solution.

Next ([6], page 356), in the situation considered here, the convolutions in the distribution sense coincide with the classical ones, so that the estimates of convolutions for functions of exponential growth and exponential decay ([6], page 362) are applicable, and differential operators in expressions like (2.10) can be switched upon smooth convolutors ([6], page 357). Taking into account the assumption (4.5) and using the above convolution estimates we obtain (4.6) for any given T , if γ is small enough. $\square$

Acknowledgement

This work was supported in part by Grant No. 01-01-12 of the National Academy of Sciences of Ukraine under the program of joint Ukrainian-Russian projects.

References

- [1] S. Benzoni-Gavage and D. Serre, *Multidimensional Hyperbolic Partial Differential Equations*. Clarendon Press, Oxford, 2007.
- [2] B.L.J. Braaksma, Asymptotic expansions and analytic continuation for a class of Barnes integrals. *Compositio Math.* **15** (1964), 239–341.
- [3] R. Courant and D. Hilbert, *Methods of Mathematical Physics, Vol. II: Partial Differential Equations*. Interscience, New York, 1962.

- [4] S.D. Eidelman, S.D. Ivasyshen, and A.N. Kochubei, *Analytic Methods in the Theory of Differential and Pseudo-Differential Equations of Parabolic Type*. Birkhäuser, Basel, 2004.
- [5] G.I. Eskin, A generalization of the Paley-Wiener-Schwartz theorem. *Uspekhi Mat. Nauk* **16**, No 1 (1961), 185–188; also in: *Amer. Math. Soc. Translations* **28** (1963), 187–190.
- [6] A. Friedman, Existence of smooth solutions of the Cauchy problem for differential systems of any type. *J. Math. Mech.* **12** (1963), 335–374.
- [7] Y. Fujita, Integrodifferential equation which interpolates the heat equation and the wave equation. *Osaka J. Math.* **27** (1990), 309–321.
- [8] I.M. Gel'fand and G.E. Shilov, *Generalized Functions. Vol. 3. Theory of Differential Equations*. Academic Press, New York, 1967.
- [9] A. Hanyga, Multidimensional solutions of time-fractional diffusion-wave equations. *Proc. Roy. Soc. London, Ser. A* **458** (2002), 933–957.
- [10] A. Heibig, Existence of solutions for a fractional derivative system of equations. *Integr. Equ. Oper. Theory* **72** (2012), 483–508.
- [11] N.J. Higham, *Functions of Matrices*. SIAM, Philadelphia, 2008.
- [12] A.A. Kilbas, H.M. Srivastava, and J.J. Trujillo, *Theory and Applications of Fractional Differential Equations*. Elsevier, Amsterdam, 2006.
- [13] A.N. Kochubei, Fractional-parabolic systems. *Potential Anal.* **37** (2012), 1–30.
- [14] Yu. Luchko, F. Mainardi and Yu. Povstenko, Propagation speed of the maximum of the fundamental solution to the fractional diffusion-wave equation. *Computers and Mathematics with Applications* **66**, No 5 (2013), 774–784; doi: <http://dx.doi.org/10.1016/j.camwa.2013.01.005>.
- [15] F. Mainardi, The fundamental solution for the fractional diffusion-wave equation. *Appl. Math. Lett.* **9** (1996), 23–28.
- [16] F. Mainardi, *Fractional Calculus and Waves in Linear Viscoelasticity*. Imperial College Press, London, 2010.
- [17] M. Markus and H. Minc, *A Survey of Matrix Theory and Matrix Inequalities*. Allyn and Bacon, Boston, 1964.
- [18] R. Metzler and J. Klafter, The restaurant at the end of the random walk: recent developments in the description of anomalous transport by fractional dynamics. *J. Phys. A* **37** (2004), R161–R208.
- [19] A.V. Pskhu, The fundamental solution of a diffusion-wave equation of fractional order. *Izv. Math.* **73** (2009), 351–392.
- [20] W.R. Schneider, W. Wyss, Fractional diffusion and wave equations. *J. Math. Phys.* **30** (1989), 134–144.
- [21] V.V. Uchaikin, *Fractional Derivatives for Physicists and Engineers*. Springer, Berlin, and Higher Education Press, Beijing, 2013.

- [22] V.S. Vladimirov, *Generalized Functions in Mathematical Physics*. Mir, Moscow, 1979.
- [23] E.M. Wright, The asymptotic expansion of the generalized hypergeometric function., *J. London Math. Soc.* **10** (1935), 286–293.

*Institute of Mathematics
National Academy of Sciences of Ukraine
Tereshchenkivska 3
Kiev, 01601, UKRAINE*

e-mail: kochubei@i.com.ua

Received: February 16, 2013

Please cite to this paper as published in:

Fract. Calc. Appl. Anal., Vol. **16**, No 4 (2013), pp. 860–873;
DOI: 10.2478/s13540-013-0053-4