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Constructing Quasi-Periodic Wave Solutions of Differential-Difference Equation by Hirota Bilinear Method

DOI 10.1515/zna-2016-0305

Received August 19, 2016; accepted October 4, 2016; previously published online November 10, 2016

Abstract: In the present paper, based on the Riemann theta function, the Hirota bilinear method is extended to directly construct a kind of quasi-periodic wave solution of a new integrable differential-difference equation. The asymptotic property of the quasi-periodic wave solution is analyzed in detail. It will be shown that quasi-periodic wave solution converge to the soliton solutions under certain conditions and small amplitude limit.

Keywords: Hirota Bilinear Method; Quasi-Periodic Wave Solution; Riemann Theta Function.

PACS: 02.30.Xx; 02.30.Mv; 02.60.Lj.

1 Introduction

Recently, differential-difference equations have stimulated considerable interest due to their numerous applications in the areas of physics and engineering [1–8]. Usually, for better understanding of the meaning of differential-difference equations, it is of great significance to search for their exact analytic solutions. The exact solution, if available, of these equations facilitates the verification of numerical solvers and aids in the stability analysis of solutions. In the past decades, there has been significant progression in the development of the methods for exact solutions such as inverse scattering method [9], Darboux transformation [10, 11], Hirota bilinear method [12, 13], algebro-geometric method [14–19], and others.

Among them, the algebro-geometric method is an analogue of inverse scattering transformation, which was first developed by Matveev, Its, Novikov, and Dubrovin et al.

The method can derive an important class of exact solutions, which is called algebro-geometric or quasi-periodic solution, to many soliton equations such as Korteweg-de Vries (KdV) equation, sine-Gordon equation, and Schrödinger equation. In recent years, such solutions of nonlinear equations have aroused much interest in mathematical physics [20–25]. However, this method usually is applied in the integrable nonlinear evolution equations admitting Lax pairs representation and involves complicated algebraic geometry theory which often requires the use of Riemann theta functions and calculus on Riemann surfaces [26–28]. These have been used far less than their soliton counterparts.

It is well known that the bilinear derivative method developed by Hirota is a powerful and direct approach to construct the exact solution of nonlinear equations [12, 13, 29–35]. Once a nonlinear equation is written in bilinear form by a dependent variable transformation, then multi-soliton solutions and rational solutions can be obtained. Recently, by means of the Hirota bilinear method, Nakamura proposed a convenient way to construct quasi-periodic solutions of nonlinear equation in his two serial papers [36, 37], where the periodic wave solutions of the KdV equation and the Boussinesq equation were obtained. Some authors, such as Ma, Zhang, Fan, and their collaborators have extended this method to investigate the breaking soliton equation, the Boussinesq equation, KdV, Kadomtsev–Petviashvili, asymmetric Nizhnik–Novikov–Vesselov, and Bogoyavlenskii equations [38–42]. In fact, the appeal and success of this method lies in the fact that it circumvents complicated algebro-geometric theory to directly get explicit quasi-periodic wave solutions. And this method also shows its effectiveness to some special types of equations, e.g. supersymmetric equations [43, 44]. However, little work has been done on differential-difference equations for the quasi-periodic wave solutions by using the Hirota bilinear method [45, 46], and it is shown that all parameters appearing in the quasi-periodic wave solutions are conditionally free variables, whereas usual quasi-periodic solutions involve some Riemann constants which are difficult to be determined explicitly.

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In the present paper, based on the Riemann theta function, we extend the Hirota bilinear method to directly construct quasi-periodic solutions for the differential-difference equations. A new integrable generalized differential-difference equation [47] is taken as an example to illustrate the method. It will be shown that its soliton solution can be obtained as a limiting case of the quasi-periodic wave solution under certain conditions and small amplitude limit.

The rest of the paper is organized as follows. In Section 2, we briefly recall bilinear form of differential-difference equation and the Riemann theta function. In Section 3, we apply the Hirota bilinear method and Riemann theta function to construct quasi-periodic wave solutions to a differential-difference equation. Further, we analyze the asymptotic behavior of the quasi-periodic wave solutions in detail in the last section. It is rigorously shown that a well-known soliton solution can be obtained from the quasi-period wave solution under a “small amplitude” limit. Further work about the multi-periodic wave solutions of differential-difference equations will be given in final.

2 The Bilinear Form and the Riemann Theta Function

In this section, we first briefly recall the integrable generalized differential-difference equation [47] whose bilinear form is

$$\left[D_t \sinh\left(\frac{1}{2}k_1 D_n\right) - 2 \sinh\left(\frac{1}{2}k_2 D_n\right) \sinh\left(\frac{1}{2}(k_1 - k_2) D_n\right) + 2\alpha \sinh\left(\frac{1}{2}k_2 D_n\right) \sinh\left(\frac{1}{2}(k_1 + k_2) D_n\right) + c \right] f(n) \cdot f(n) = 0, \quad (1)$$

where k_1 and k_2 are two integers, α is an arbitrary constant, and c is an integration constant. The bilinear differential operator D_t and difference operator e^{D_n} are defined by

$$\begin{aligned} D_t f(t) \cdot g(t) &= (\partial_t - \partial_{t'}) f(t) g(t')|_{t'=t}, \\ e^{\delta D_n} f(n) \cdot g(n) &= e^{\delta(\partial_n - \partial_{n'})} f(n) g(n')|_{n'=n} = f(n+\delta) g(n-\delta), \\ \sinh(\delta D_n) f(n) \cdot g(n) &= \frac{1}{2} (e^{\delta D_n} - e^{-\delta D_n}) \\ f(n) \cdot g(n) &= \frac{1}{2} (f(n+\delta) g(n-\delta) - f(n-\delta) g(n+\delta)). \end{aligned} \quad (2)$$

Bilinear form (1) covers many famous differential-difference equations. In particular, when $k_1=1$, $k_2=2$, (1) can easily transform into the generalized Lotka-Volterra equation found by Tsujimoto and Hirota [48]; when $\alpha=0$, taking the transformation

$$a_n = \frac{f\left(n - \frac{k_2+1}{2}\right) f\left(n + \frac{k_2+1}{2}\right)}{f\left(n - \frac{k_2-1}{2}\right) f\left(n + \frac{k_2-1}{2}\right)}, \quad (3)$$

the famous extended Lotka-Volterra equation [49, 50]

$$\frac{d}{dt} \prod_{i=0}^{m-1} a_{n - \frac{m-1}{2} + i} = \prod_{i=0}^{k-1} a_{n + \frac{m-1}{2} + i - (k-1)} - \prod_{i=0}^{k-1} a_{n - \frac{m-1}{2} + i}, \quad (4)$$

($m=1, 2, \dots; k=1, 2, \dots; m \neq k$)

can be recovered. As shown in [47] (1) is integrable in the sense of Bäcklund transformation.

The operators D_t , e^{D_n} , and $\sinh(\delta D_n)$ have very good properties when they act on exponential functions

$$\begin{aligned} D_t e^{\xi_1} \cdot e^{\xi_2} &= (\omega_1 - \omega_2) e^{\xi_1 + \xi_2}, \\ e^{\delta D_n} e^{\xi_1} \cdot e^{\xi_2} &= e^{\delta(\nu_1 - \nu_2)} e^{\xi_1 + \xi_2}, \\ \sinh(\delta D_n) e^{\xi_1} \cdot e^{\xi_2} &= \sinh[\delta(\nu_1 - \nu_2)] e^{\xi_1 + \xi_2}, \end{aligned} \quad (5)$$

where $\xi_j = \omega_j t + \nu_j n + \sigma_j$, $j=1, 2$. More generally, we have

$$G(D_t, \sinh(\delta D_n)) e^{\xi_1} \cdot e^{\xi_2} = G(\omega_1 - \omega_2, \sinh(\delta(\nu_1 - \nu_2))) e^{\xi_1 + \xi_2}$$

where $G(D_t, \sinh(\delta D_n))$ is a polynomial function with respect to the operators D_t and $\sinh(\delta D_n)$.

In the special case of $c=0$, (1) admits one-soliton solution

$$f(n) = 1 + \exp \left(\nu n + \frac{2 \sinh\left(\frac{k_2 \nu}{2}\right) \left[(1-\alpha) \sinh\left(\frac{\nu k_1}{2}\right) \cosh\left(\frac{\nu k_2}{2}\right) - (1+\alpha) \cosh\left(\frac{\nu k_1}{2}\right) \sinh\left(\frac{\nu k_2}{2}\right) \right]}{\sinh\left(\frac{k_1 \nu}{2}\right)} t + \sigma \right). \quad (6)$$

In the following, we introduce a one-dimensional Riemann theta function and discuss its quasi-periodicity, which plays a central role in this paper. The Riemann theta function reads

$$\vartheta(\xi, \epsilon, s|\tau) = \sum_{m \in \mathbb{Z}} \exp[2\pi i(\xi + \epsilon)(m + s) - \pi\tau(m + s)^2]. \quad (7)$$

Here the integer value $m \in \mathbb{Z}$, $s, \epsilon \in \mathbb{C}$, and complex phase variables $\xi = \omega t + \nu n + \sigma$ is dependent on continuous time variable t and discretized spacial variable n . The $\tau > 0$ is called the period matrix of the Riemann theta function. For simplicity, in the case when $s = \epsilon = 0$, we denote

$$\vartheta(\xi, \tau) = \vartheta(\xi, 0, 0|\tau). \quad (8)$$

Definition 2.1. A function $g(t)$ on \mathbb{C} is said to be quasi-periodic in t with fundamental periods $T_1, \dots, T_k \in \mathbb{C}$ if T_1, \dots, T_k are linearly dependent on \mathbb{Z} , and there exists a function $G(y_1, \dots, y_k) \in \mathbb{C}^k$, such that

$$G(y_1, \dots, y_j + T_j, \dots, y_k) = G(y_1, \dots, y_j, \dots, y_k), \quad (9)$$

for all $(y_1, \dots, y_k) \in \mathbb{C}^k$,

$$G(t, \dots, t, \dots, t) = g(t). \quad (10)$$

In particular, $g(t)$ becomes periodic with the period T if and only if $T_j = m_j T$.

Proposition 2.2. The Riemann theta function $\vartheta(\xi, \tau)$ defined above has the periodic properties [51, 52]

$$\vartheta(\xi + 1 + i\tau, \tau) = \exp(-2\pi i\xi + \pi\tau)\vartheta(\xi, \tau). \quad (11)$$

Proposition 2.3. The meromorphic functions $F(\xi)$ on \mathbb{C} are as follows:

$$\begin{aligned} (i) \quad & F(\xi) = \partial_\xi^2 \ln \vartheta(\xi, \tau), \quad \xi \in \mathbb{C}; \\ (ii) \quad & F(\xi) = \partial_\xi \ln \frac{\vartheta(\xi + e, \tau)}{\vartheta(\xi + h, \tau)}, \quad \xi, e, h \in \mathbb{C}; \\ (iii) \quad & F(\xi) = \frac{\vartheta(\xi + e, \tau)\vartheta(\xi - e, \tau)}{\vartheta(\xi, \tau)^2}, \quad \xi, e \in \mathbb{C}. \end{aligned} \quad (12)$$

Then all three cases (i)–(iii) hold that

$$F(\xi + 1 + i\tau) = F(\xi), \quad \xi \in \mathbb{C}, \quad (13)$$

that is, these $F(\xi)$ are quasi-periodic functions with two fundamental periods 1 and $i\tau$ [46].

3 The Quasi-Periodic Solution

Now we consider the Riemann theta function solution of the above bilinear form differential-difference equation (1)

$$f(n) = \vartheta(\xi, \tau) = \sum_{m=-\infty}^{\infty} e^{2\pi i m \xi - \pi m^2 \tau}, \quad (14)$$

where $m \in \mathbb{Z}$, $\tau > 0$, and $\xi = \omega t + \nu n + \sigma$.

Substituting (14) into (1) gives

$$\begin{aligned} G(D_t, \sinh(\delta D_n))f(n) \cdot f(n) &= G(D_t, \sinh(\delta D_n)) \\ &= \sum_{m'=-\infty}^{\infty} e^{2\pi i m' \xi - \pi m'^2 \tau} \cdot \sum_{m=-\infty}^{\infty} e^{2\pi i m \xi - \pi m^2 \tau} \\ &= \sum_{m'=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} G(D_t, \sinh(\delta D_n)) e^{2\pi i m' \xi - \pi m'^2 \tau} \cdot e^{2\pi i m \xi - \pi m^2 \tau} \\ &= \sum_{m'=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} G(2\pi i(m' - m)\omega, \sinh[2\pi i\delta\nu(m' - m)]) \\ &\quad e^{2\pi i(m' + m)\xi - \pi(m'^2 + m^2)\tau} \\ &= \sum_{l'=-\infty}^{\infty} \sum_{m'=-\infty}^{\infty} G(2\pi i(2m' - l')\omega, \sinh[2\pi i\delta\nu(2m' - l')]) \\ &\quad e^{2\pi i l' \xi - \pi[(m'^2 + (l' - m')^2)]\tau} \\ &= \sum_{l=-\infty}^{\infty} \sum_{\mu=0,1} \sum_{m'=-\infty}^{\infty} G\left(4\pi i\left(m' - l - \frac{\mu}{2}\right)\omega, \right. \\ &\quad \left. \sinh\left[4\pi i\delta\nu\left(m' - l - \frac{\mu}{2}\right)\right]\right) e^{4\pi i\left(l + \frac{\mu}{2}\right)\xi - \pi[(m'^2 + (2l + \mu - m')^2)]\tau}. \end{aligned} \quad (15)$$

Let $m' = h + l$, and using the relations

$$\begin{aligned} h + l &= \left[h - \frac{\mu}{2}\right] + \left[l + \frac{\mu}{2}\right], \\ h - l - \mu &= \left[h - \frac{\mu}{2}\right] - \left[l + \frac{\mu}{2}\right], \end{aligned} \quad (16)$$

we finally obtain that

$$\begin{aligned} G(D_t, \sinh(\delta D_n))f(n) \cdot f(n) &= \sum_{l=-\infty}^{\infty} \left\{ \sum_{\mu=0,1} \sum_{h=-\infty}^{\infty} G\left(4\pi i\left(h - \frac{\mu}{2}\right)\omega, \sinh\left[4\pi i\delta\nu\left(h - \frac{\mu}{2}\right)\right]\right) \right. \\ &\quad \left. e^{-2\pi i\left(h - \frac{\mu}{2}\right)^2 \tau} \right\} e^{4\pi i\left(l + \frac{\mu}{2}\right)\xi - 2\pi i\left(l + \frac{\mu}{2}\right)^2 \tau} \\ &= \sum_{l=-\infty}^{\infty} C(\omega, \nu, \mu) e^{4\pi i\left(l + \frac{\mu}{2}\right)\xi - 2\pi i\left(l + \frac{\mu}{2}\right)^2 \tau}, \end{aligned} \quad (17)$$

where

$$\begin{aligned} C(\omega, \nu, \mu) &= \sum_{\mu=0,1} \sum_{h=-\infty}^{\infty} G\left(4\pi i\left(h - \frac{\mu}{2}\right)\omega, \sinh\left[4\pi i\delta\nu\left(h - \frac{\mu}{2}\right)\right]\right) \\ &\quad e^{-2\pi i\left(h - \frac{\mu}{2}\right)^2 \tau}. \end{aligned} \quad (18)$$

It is seen that if the following equations $C(\omega, \nu, \mu) = 0$ are satisfied, for all possible combinations $\mu = 0, 1$, then $\vartheta(\xi, \tau)$ is a solution of the bilinear equation (1). On the other hand, the equations $G(\omega, \nu, 0) = 0$ and $G(\omega, \nu, 1) = 0$ can be explicitly written as

$$\sum_{h=-\infty}^{\infty} \{4\pi i \omega \sinh[2\pi i k_1 \nu h] - 2\sinh[2\pi i k_2 \nu h] \sinh[2\pi i (k_1 - k_2) \nu h] + 2\alpha \sinh[2\pi i k_2 \nu h] \sinh[2\pi i (k_1 + k_2) \nu h] + c\} e^{-2\pi h^2 \tau} = 0, \quad (19)$$

$$\sum_{h=-\infty}^{\infty} \left\{ 4\pi i \left(h - \frac{1}{2} \right) \omega \sinh \left[2\pi i k_1 \nu \left(h - \frac{1}{2} \right) \right] - 2\sinh \left[2\pi i k_2 \nu \left(h - \frac{1}{2} \right) \right] \sinh \left[2\pi i (k_1 - k_2) \nu \left(h - \frac{1}{2} \right) \right] + 2\alpha \sinh \left[2\pi i k_2 \nu \left(h - \frac{1}{2} \right) \right] \sinh \left[2\pi i (k_1 + k_2) \nu \left(h - \frac{1}{2} \right) \right] + c \right\} e^{-2\pi \left(h - \frac{1}{2} \right)^2 \tau} = 0, \quad (20)$$

i.e.

$$\sinh \left(\frac{1}{2} k_1 D_n \right) \vartheta'_1(0, \lambda) \omega - 2\sinh \left(\frac{1}{2} k_2 D_n \right) \sinh \left(\frac{1}{2} (k_1 - k_2) D_n \right) \vartheta_1(0, \lambda) + 2\alpha \sinh \left(\frac{1}{2} k_2 D_n \right) \sinh \left(\frac{1}{2} (k_1 + k_2) D_n \right) \vartheta_1(0, \lambda) + c \vartheta_1(0, \lambda) = 0, \quad (21)$$

$$\sinh \left(\frac{1}{2} k_1 D_n \right) \vartheta'_2(0, \lambda) \omega - 2\sinh \left(\frac{1}{2} k_2 D_n \right) \sinh \left(\frac{1}{2} (k_1 - k_2) D_n \right) \vartheta_2(0, \lambda) + 2\alpha \sinh \left(\frac{1}{2} k_2 D_n \right) \sinh \left(\frac{1}{2} (k_1 + k_2) D_n \right) \vartheta_2(0, \lambda) + c \vartheta_2(0, \lambda) = 0, \quad (22)$$

where by convention the prime means $\partial \xi$ and

$$\lambda = e^{\frac{1}{2}\pi\tau}, \quad \vartheta_1(\xi, \lambda) = \vartheta(2\xi, 2\tau) = \sum_{h=-\infty}^{+\infty} \lambda^{4h^2} \exp(4\pi i h \xi),$$

$$\vartheta_2(\xi, \lambda) = \vartheta \left(2\xi, 0, -\frac{1}{2} | 2\tau \right) = \sum_{h=-\infty}^{+\infty} \lambda^{(2h-1)^2} \exp[2\pi i (2h-1)\xi]. \quad (23)$$

By introducing the notations

$$\eta = \nu' n + \frac{2\sinh \left(\frac{k_2 \nu'}{2} \right) \left[(1-\alpha) \sinh \left(\frac{\nu' k_1}{2} \right) \cosh \left(\frac{\nu' k_2}{2} \right) - (1+\alpha) \cosh \left(\frac{\nu' k_1}{2} \right) \sinh \left(\frac{\nu' k_2}{2} \right) \right]}{\sinh \left(\frac{k_1 \nu'}{2} \right)} t + \sigma',$$

$$\theta(\xi, \tau) \rightarrow 1 + e^\eta, \quad \text{as } \lambda \rightarrow 0.$$

$$\begin{aligned} a_{11} &= \sinh \left(\frac{1}{2} k_1 D_n \right) \vartheta'_1(0, \lambda), \quad a_{12} = \vartheta_1(0, \lambda), \\ a_{21} &= \sinh \left(\frac{1}{2} k_1 D_n \right) \vartheta'_2(0, \lambda), \quad a_{22} = \vartheta_2(0, \lambda), \\ b_1 &= 2\sinh \left(\frac{1}{2} k_2 D_n \right) \sinh \left(\frac{1}{2} (k_1 - k_2) D_n \right) \vartheta_1(0, \lambda) \\ &\quad - 2\alpha \sinh \left(\frac{1}{2} k_2 D_n \right) \sinh \left(\frac{1}{2} (k_1 + k_2) D_n \right) \vartheta_1(0, \lambda), \\ b_2 &= 2\sinh \left(\frac{1}{2} k_2 D_n \right) \sinh \left(\frac{1}{2} (k_1 - k_2) D_n \right) \vartheta_2(0, \lambda) \\ &\quad - 2\alpha \sinh \left(\frac{1}{2} k_2 D_n \right) \sinh \left(\frac{1}{2} (k_1 + k_2) D_n \right) \vartheta_2(0, \lambda), \end{aligned} \quad (24)$$

systems (21) and (22) admit an explicit solution

$$\omega = \frac{b_1 a_{22} - b_2 a_{12}}{a_{11} a_{22} - a_{12} a_{21}}, \quad c = \frac{b_2 a_{11} - b_1 a_{21}}{a_{11} a_{22} - a_{12} a_{21}}. \quad (25)$$

Finally, we can obtain the quasi-periodic solution for the differential-difference equation (1)

$$f(n) = \sum_{m=-\infty}^{\infty} e^{2\pi i m \xi - \pi m^2 \tau}, \quad (26)$$

where $\xi = \omega t + \nu n + \sigma$, ν and σ are arbitrary constants, and ω and c are given by (25).

4 Asymptotic Property

In the following, we further consider asymptotic property of the one-periodic wave solution. We will directly use system (25) to analyze the asymptotic properties of the periodic solution. It will be shown that the one-soliton solution can be obtained as a limiting case of the one-periodic wave solution (26). The relations between these two solutions are established as follows.

Theorem 4.1. Suppose that the vector (ω, c) is a solution of system (25), and for the periodic wave solution (25), we let

$$\nu' = 2\pi i \nu, \quad \sigma' = 2\pi i \sigma - \pi \tau, \quad (27)$$

where the ν and σ are arbitrary constants. Then we have the following asymptotic properties

$$c \rightarrow 0, \quad 2\pi i \xi - \pi \tau \rightarrow \eta, \quad (28)$$

In other words, the periodic solution (25) tends to the soliton solution (6) under a small amplitude limit.

Proof. Here we will directly use system (25) to analyze the asymptotic properties of periodic solution, which is more simple and effective than the original method of solving system (25) as done in [40, 41]. Since the coefficients of system (24) are power series about λ , its solution (ω, c) also should be a series about λ . We explicitly expand the coefficients of system (24) as follows

$$\begin{aligned} a_{11} &= 8\pi i \sinh(2\pi i k_1 \nu) \lambda^4 + 16\pi i \sinh(4\pi i k_1 \nu) \lambda^{16} + \dots, \\ a_{12} &= 1 + 2\lambda^4 + 2\lambda^{16} \dots, \\ a_{21} &= 4\pi i \sinh(\pi i k_1 \nu) \lambda + 12\pi i \sinh(3\pi i k_1 \nu) \lambda^9 + \dots, \\ a_{22} &= 2\lambda + 2\lambda^3 + 2\lambda^9 \dots, \\ b_1 &= 4[\sinh(2\pi i k_2 \nu) \sinh(2\pi i(k_1 - k_2)\nu) \\ &\quad - \alpha \sinh(2\pi i k_2 \nu) \sinh(2\pi i(k_1 + k_2)\nu)] \lambda^4 + \dots, \\ b_2 &= 4[\sinh(\pi i k_2 \nu) \sinh(\pi i(k_1 - k_2)\nu) \\ &\quad - \alpha \sinh(\pi i k_2 \nu) \sinh(\pi i(k_1 + k_2)\nu)] \lambda + \dots. \end{aligned} \quad (29)$$

Let the solution of system (25) be in the form

$$\begin{aligned} \omega &= \omega_0 + \omega_1 \lambda + \omega_2 \lambda^2 + \dots = \omega_0 + o(\lambda), \\ c &= c_0 + c_1 \lambda + c_2 \lambda^2 + \dots = c_0 + o(\lambda). \end{aligned} \quad (30)$$

Substituting the expansions (29) and (30) into system (25) and letting $\lambda \rightarrow 0$, we immediately obtain the following relations

$$c_0 = 0, \quad w_0 = \frac{\sinh(\pi i k_2 \nu) \sinh(\pi i(k_1 - k_2)\nu) - \alpha \sinh(\pi i k_2 \nu) \sinh(\pi i(k_1 + k_2)\nu)}{\pi i \sinh(\pi i k_1 \nu)}. \quad (31)$$

Combining (30) and (31) leads to

$$2\pi i w \rightarrow \frac{2\sinh\left(\frac{k_2 \nu'}{2}\right) \left[(1-\alpha) \sinh\left(\frac{\nu' k_1}{2}\right) \cosh\left(\frac{\nu' k_2}{2}\right) - (1+\alpha) \cosh\left(\frac{\nu' k_1}{2}\right) \sinh\left(\frac{\nu' k_2}{2}\right) \right]}{\sinh\left(\frac{k_1 \nu'}{2}\right)}, \quad (32)$$

$c \rightarrow 0, \text{ as } \lambda \rightarrow 0,$

or equivalently,

$$\hat{\xi} = 2\pi i \xi - \pi \tau = \nu' n + 2\pi i w t + \sigma' \rightarrow \eta. \quad (33)$$

It remains to consider asymptotic property of the one-periodic wave solution (26) under the limit $\lambda \rightarrow 0$. For this purpose, we expand the Riemann theta function $\vartheta(\xi, \tau)$ and make use of expression (33); it follows that

$$\begin{aligned} \vartheta(\xi, \tau) &= 1 + \lambda^2 (e^{2\pi i \xi} + e^{-2\pi i \xi}) + \lambda^8 (e^{4\pi i \xi} + e^{-4\pi i \xi}) + \dots \\ &= 1 + e^{\hat{\xi}} + \lambda^4 (e^{-\hat{\xi}} + e^{2\hat{\xi}}) + \dots \rightarrow 1 + e^{\eta}, \text{ as } \lambda \rightarrow 0, \end{aligned} \quad (34)$$

which proves the above theorem. Therefore, we conclude that the periodic solution (26) just goes to the soliton solution (6) as the amplitude $\lambda \rightarrow 0$. \square

As illustrated at the beginning of Section 2, the bilinear form (1) is so general that it covers many famous differential-difference equations. For example, taking the transformation of solution (3), the extended Lotka-Volterra equation (4) becomes the bilinear form (1) with $\alpha = 0$ [50]. Then by the above analysis, we can directly get the quasi-periodic solution a_n of the extended Lotka-Volterra equation (4). The quasi-periodic and the corresponding soliton solutions of the extended Lotka-Volterra equation have been presented in Figures 1 and 2.

5 Multi-Periodic Wave Solutions

Following the procedure described in this paper, we are able to construct quasi-periodic wave solutions for other differential-difference equations. Moreover, we can construct multi-periodic wave solutions of differential-difference equations by the multi-dimensional Riemann theta function as the following form

$$\vartheta(\xi, \tau) = \sum_{\mathbf{m} \in \mathbb{Z}^N} \exp\{2\pi i \langle \xi, \mathbf{m} \rangle - \pi \langle \tau \mathbf{m}, \mathbf{m} \rangle\}, \quad (35)$$

where $\xi = (\xi_1, \xi_2, \dots, \xi_N)^T \in \mathbb{C}^N$, $\mathbf{m} = (m_1, m_2, \dots, m_N)^T \in \mathbb{Z}^N$, $\xi_j = \omega_j t + \nu_j n + \sigma_j$, $j = 1, \dots, N$, τ is a $N \times N$ symmetric positive definite matrix. The inner product is defined by

$$\langle \mathbf{f}, \mathbf{g} \rangle = f_1 g_1 + f_2 g_2 + \dots + f_N g_N, \quad (36)$$

for two vectors $\mathbf{f} = (f_1, f_2, \dots, f_N)^T$ and $\mathbf{g} = (g_1, g_2, \dots, g_N)^T$.

To make the multi-dimensional Riemann theta function (35) satisfy the bilinear equation (1), from (18) we have

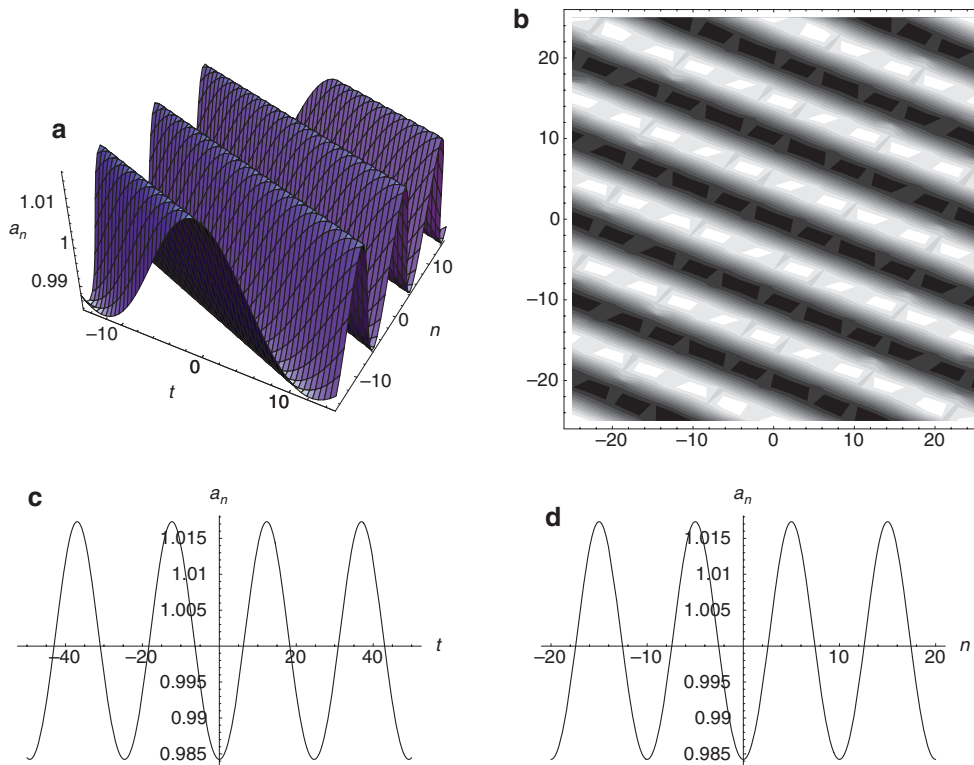


Figure 1: Quasi-periodic wave for the extended Lotka-Volterra equation (4): (a) perspective view of wave, (b) overhead view of wave, with contour plot shown, (c) along t -axis, and (d) along n -axis, where $\nu=0.1$, $k_1=2$, $k_2=1$, $\sigma=0$ and $\tau=1$.

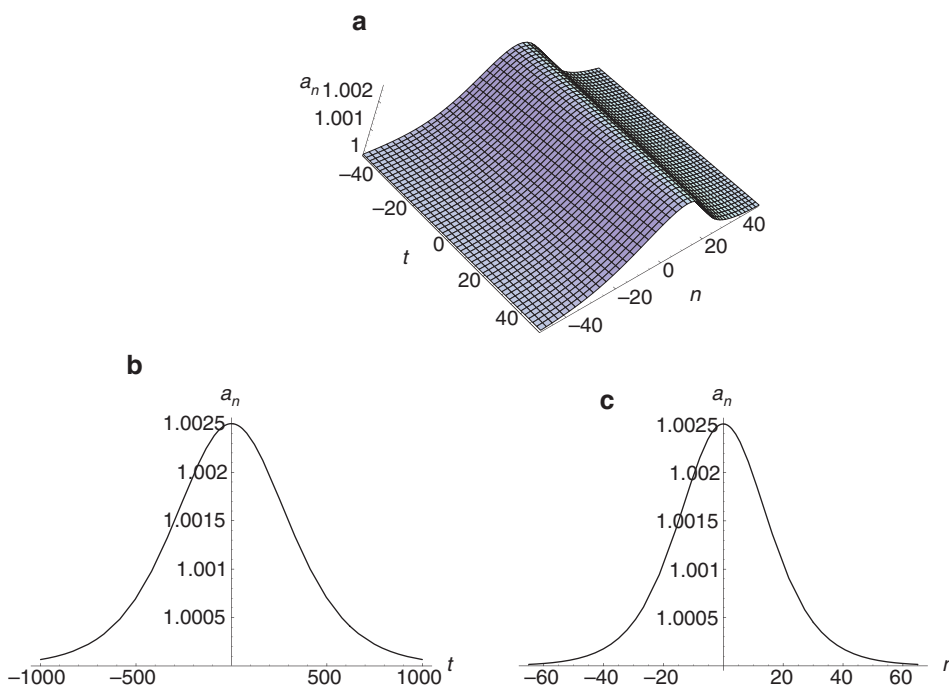


Figure 2: Solitary wave for the extended Lotka-Volterra equation (4): (a) perspective view of wave, (b) along t -axis, and (c) along n -axis, where $\nu=0.1$, $k_1=2$, $k_2=1$, $\sigma=0$ and $\tau=1$.

$$\sum_{\mu=0,1} \sum_{h_1, \dots, h_N=-\infty}^{\infty} G \left(4\pi i \sum_{j=1}^N \left(h_j - \frac{\mu_j}{2} \right) \omega_j, \right. \\ \left. \sinh \left[4\pi i \delta \sum_{j=1}^N \nu_j \left(h_j - \frac{\mu_j}{2} \right) \right] \right) \\ \times \exp \left[-2\pi \sum_{j,k=1}^N \left(h_j - \frac{\mu_j}{2} \right) \tau_{jk} \left(h_k - \frac{\mu_k}{2} \right) \right] = 0. \quad (37)$$

It is very important to consider the number of equations and unknown parameters. Obviously, in the case of differential-difference equations, the number of constraint equations of the type (17) is 2^N . On the other hand, we have parameters $\tau_{jk}=\tau_{kj}$, ω_j , ν_j , and c whose total number is $\frac{1}{2}N(N+1)+2N+1$. Among them, $2N$ parameters τ_{jj} and ν_j are taken to be the given parameters related to the amplitudes and wave numbers (or frequencies) of N -periodic waves. $\frac{1}{2}N(N-1)$ parameters τ_{jk} implicitly appear in series form, which in general cannot to be solved explicitly. Hence, the number of explicit unknown parameters is only $N+1$. The number of equations is larger than the unknown parameters in the case when $N \geq 2$. In this paper, we consider one-periodic wave solution of (1), which belongs to the case when $N=1$. There are still certain difficulties in the calculation for the case $N \geq 2$, which will be considered in our future work.

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