

Research Article

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A higher-dimensional categorical perspective on 2-crossed modules

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Abstract: In this study, we will express the 2-crossed module of groups from a higher-dimensional categorical perspective. According to simplicial homotopy theory, a 2-crossed module is the Moore complex of a 2-truncated simplicial group. Therefore, the 2-crossed module is an algebraic homotopy model for the homotopy 3-types. Tricategories are a three-dimensional generalization of the bicategory concept. Any tricategory is triequivalent to the **Gray** category, where **Gray** is a category enriched over the monoidal category **2Cat** equipped with the Gray tensor product. Briefly, a **Gray** category is a semi-strict 3-category for homotopy 3-types. Naturally, the tricategory perspective is used in homotopy theory. The 2-crossed module is associated with the concept of the **Gray** category. The aim of this study is to obtain a single object tricategory from any 2-crossed module of groups.

Keywords: crossed module, 2-crossed module, categorification, sestertius category, tricategory

MSC 2020: 18G45, 18N10, 18N20, 18N25

1 Introduction

Whitehead described crossed modules in [1,2] for modeling homotopy 2-types from the algebraic homotopy theory perspective. Roughly speaking, in terms of nonabelian algebraic homotopy 2-types, any crossed module of groups $\mathcal{G}_1 = (E \xrightarrow{\partial} G)$ has a classification space X such that $\pi_2(X) \cong \ker(\partial)$ and $\pi_1(X) \cong \operatorname{coker}(\partial)$, while each of the homotopy groups $\pi_i(X)$ for $i > 2$ is trivial. Loday introduced cat^1 -groups, a similar structure for homotopy 2-types in [3]. From a categorical point of view, Brown and Spencer [4,5] associated crossed modules of groupoids with double groupoids. In terms of structures in categories, a crossed module of groups is equivalent to an internal category in the category of groups **Grp** [6,7]. From the point of view of monoidal categories in [8], crossed modules are equivalent to strict 2-groups.

Gordon et al. [9] introduced the tricategory concept, the natural three-dimensional generalization of bicategory [10]. Also, bicategories are called weak 2-categories [8]. Any tricategory is triequivalent to the **Gray** category, where **Gray** is a category enriched over the monoidal category **2Cat** equipped with the **Gray** tensor product [9]. Briefly, the **Gray** category means exactly a strict cubical tricategory. Furthermore, a strict cubical tricategory is a semi-strict 3-category for homotopy 3-types, as a **Gray** category [11,12].

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Conduché [13] defined a 2-crossed module for the algebraic homotopy 3-type models using simplicial homotopy theory. In brief, the 2-crossed module is the Moore complex of a 2-truncated simplicial group. In [14,15], the 2-crossed module is associated with the concept of the **Gray** category.

The aim of this study is to obtain a single object tricategory from any 2-crossed module of groups. For this, we will first construct a strict 2-group from a crossed module of groups by a categorical point of view. In contrast to crossed modules, the categorical structure must change as one moves towards higher dimensions. Because the 2-crossed module defined on the pre-crossed module does not form a strict 3-category structure. The algebraic homotopy 3-type models related to the concept of semi-strict 3-group are sestertius categories. The word sestertius is derived from the Latin phrase “SEMIS TERTIVS,” which is translated as “2 1/2.” Mathematically, a sestertius category is defined by a three-dimensional generalization of a strict 2-category, called a sesquicategory, for which there is no interchange law (for a different perspective, refer [16]). Therefore, we will obtain a sestertius category with one object in which all 1-, 2-, and 3-morphisms are invertible from a 2-crossed module of groups. Afterwards, we will construct a tricategory from this sestertius category.

2 Preliminaries

Before giving the definition of a tricategory, we will simply give an overview of the two- and three-dimensional categories.

Roughly speaking, a category consists of objects and the morphisms between them, as follows:

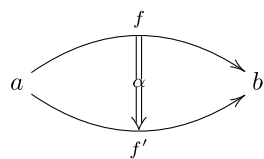
$$a \xrightarrow{f} b.$$

For these structures, we will use the nomenclature 0- and 1-cells, respectively. If we use the 0-source and 0-target functions to describe the 0-cells, we obtain $s_0(f) = a$ and $t_0(f) = b$. Naturally, this structure has to satisfy unit and associative composition:

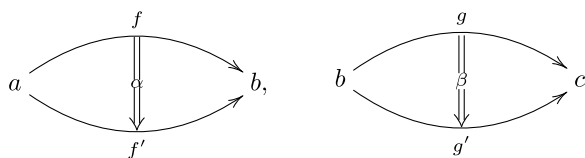
$$a \xrightarrow{1_a} a, \quad a \xrightarrow{f} b \xrightarrow{g} c, \quad a \xrightarrow{g \#_0 f} c.$$

Note that the composition of the 1-cells is “ $\#_0$.” We may write this composition as $g \#_0 f$ (meaning first g and f). Throughout our work, we will describe all compositions in this way. Of course, the composite of $g \#_0 f$ of two 1-cells is defined if and only if $t_0(f) = s_0(g)$. Thus, for composition $g \#_0 f$, $s_0(g \#_0 f) = s_0(f)$, and $t_0(g \#_0 f) = t_0(g)$. In addition, if the morphisms of 1-cells are invertible, this structure is a groupoid.

If we want to add 2-cell to this structure, we have the following:



As the diagram shows, the 1-source and 1-target of the 2-cell α are $s_1(\alpha) = f$ and $t_1(\alpha) = f'$, respectively. Let us have 2-cells with source and target compatibility as follows:



Thus, we can define whiskering diagrams as follows:

$$\begin{array}{c}
 \begin{array}{c} f \\ \curvearrowright \\ a \quad b \\ \curvearrowleft \\ f' \end{array} \xrightarrow{g} c = \begin{array}{c} g \#_0 f \\ \curvearrowright \\ a \quad c \\ \curvearrowleft \\ g \#_0 f' \end{array} \\
 \begin{array}{c} g \\ \curvearrowright \\ a \quad b \\ \curvearrowleft \\ g' \end{array} \xrightarrow{f'} c = \begin{array}{c} g \#_0 f' \\ \curvearrowright \\ a \quad c \\ \curvearrowleft \\ g' \#_0 f' \end{array}
 \end{array}$$

In addition, the horizontal composition of 2-cells “ $\#_0$ ” is defined as follows:

$$\begin{array}{c} f \\ \curvearrowright \\ a \quad b \\ \curvearrowleft \\ f' \end{array} \quad \begin{array}{c} g \\ \curvearrowright \\ b \quad c \\ \curvearrowleft \\ g' \end{array} = \begin{array}{c} g \#_0 f \\ \curvearrowright \\ a \quad c \\ \curvearrowleft \\ g' \#_0 f' \end{array}$$

Further, if we have 2-cells α and α' where the 1-target of α is f' and the 1-source of α' is f' , then the vertical composition of these 2-cells, “ $\#_1$,” is defined as follows:

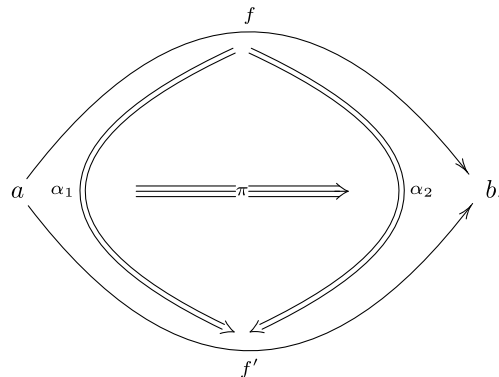
$$\begin{array}{c} f \\ \curvearrowright \\ a \quad b \\ \curvearrowleft \\ f' \end{array} \quad \begin{array}{c} f' \\ \curvearrowright \\ a \quad b \\ \curvearrowleft \\ f'' \end{array} = \begin{array}{c} f \\ \curvearrowright \\ a \quad b \\ \curvearrowleft \\ f'' \end{array}$$

Additionally, the vertical composition $\#_1$ of 2-cells is compatible with the horizontal composition $\#_0$ of 2-cells. If we show the interchange law diagrammatically, we have

$$\begin{array}{c} f \\ \curvearrowright \\ a \quad b \\ \curvearrowleft \\ f' \end{array} \quad \begin{array}{c} g \\ \curvearrowright \\ b \quad c \\ \curvearrowleft \\ g' \end{array} \quad \begin{array}{c} f' \\ \curvearrowright \\ a \quad b \\ \curvearrowleft \\ f'' \end{array} \quad \begin{array}{c} g' \\ \curvearrowright \\ b \quad c \\ \curvearrowleft \\ g'' \end{array} = \begin{array}{c} g \#_0 f \\ \curvearrowright \\ a \quad c \\ \curvearrowleft \\ g'' \#_0 f'' \end{array}$$

$$(\beta' \#_1 \beta) \#_0 (\alpha' \#_1 \alpha) = (\beta' \#_0 \alpha') \#_1 (\beta \#_0 \alpha).$$

We can upgrade this structure as much as we want. If we add 3-cells, we have



Note that the 2-source and 2-target of 3-cell π are $s_2(\pi) = \alpha_1$ and $t_2(\pi) = \alpha_2$, respectively. Thus, we would expect to have a vertical composition $\#_2$ for 3-cells. Of course, it is necessary to satisfy the interchange law for 3-cells. If the morphisms of these 1-, 2-, and 3-cells are invertible, then this structure is a 3-groupoid.

We will consider the tricategory structure, which is a particular type of the 3-category structure. Tricategory is some kind of algebraic notation for weak 3-categories. We recall the definition of tricategory given in [9,17].

Definition 2.1. A tricategory $\mathfrak{T}$ consists of following data subject to the following axioms.

DATA:

- (1) A set $Ob\mathfrak{T}$ of objects of $\mathfrak{T}$.
- (2) For $(a, b) \in Ob\mathfrak{T} \times Ob\mathfrak{T}$, a bicategory (weak 2-category) $\mathfrak{T}(a, b)$, called the hom-bicategory of $\mathfrak{T}$ at a and b , exists. The objects of $\mathfrak{T}(a, b)$ will be referred to as the 1-cells of $\mathfrak{T}$ with source a and target b , the arrows of $\mathfrak{T}(a, b)$ will be referred to as 2-cells of $\mathfrak{T}$ (with their same source and target), and the 2-cells of $\mathfrak{T}(a, b)$ will be referred to as 3-cells of $\mathfrak{T}$ (also with their same source and target).
- (3) For objects a, b , and c of $Ob\mathfrak{T}$, a functor $\otimes: \mathfrak{T}(b, c) \times \mathfrak{T}(a, b) \rightarrow \mathfrak{T}(a, c)$ exists called composition.
- (4) For an object a of $Ob\mathfrak{T}$, a functor $I_a: 1 \rightarrow \mathfrak{T}(a, a)$, exists where 1 denotes the unit bicategory.
- (5) For objects a, b, c , and d of $Ob\mathfrak{T}$, an adjoint equivalence α

$$\begin{array}{ccc}
 \mathfrak{T}(c, d) \times \mathfrak{T}(b, c) \times \mathfrak{T}(a, b) & \xrightarrow{\otimes \times 1} & \mathfrak{T}(b, d) \times \mathfrak{T}(a, b) \\
 \downarrow 1 \times \otimes & \Downarrow \alpha & \downarrow \otimes \\
 \mathfrak{T}(c, d) \times \mathfrak{T}(a, c) & \xrightarrow{\otimes} & \mathfrak{T}(a, d)
 \end{array}$$

in **Bicat** $(\mathfrak{T}(c, d) \times \mathfrak{T}(b, c) \times \mathfrak{T}(a, b), \mathfrak{T}(a, d))$ exists.

- (6) For objects a, b of $Ob\mathfrak{T}$, adjoint equivalences $\mathfrak{l}$ and $\mathfrak{r}$

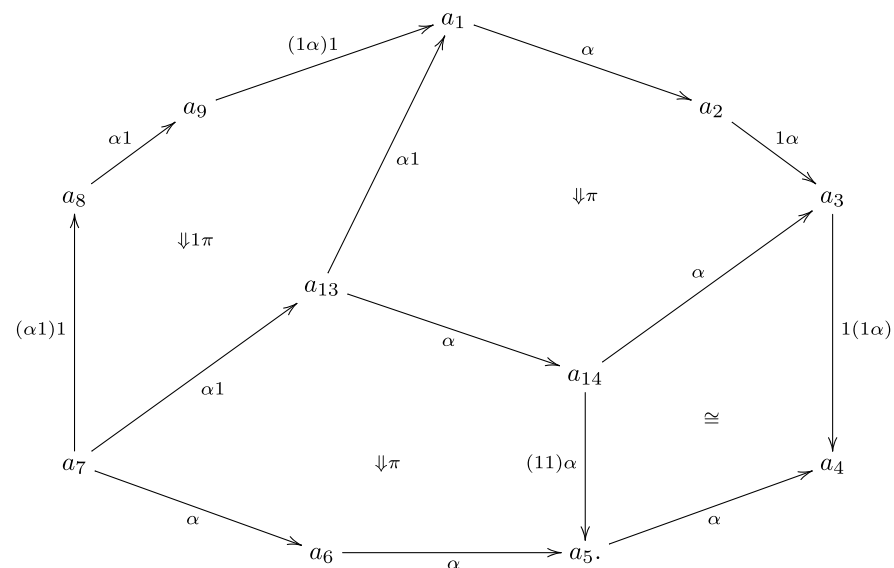
$$\begin{array}{ccc}
 & \mathfrak{T}(b, b) \times \mathfrak{T}(a, b) & \\
 I_b \times 1 \nearrow & \Downarrow \mathfrak{l} & \searrow \otimes \\
 \mathfrak{T}(a, b) & \xrightarrow{1} & \mathfrak{T}(a, b)
 \end{array}
 \quad
 \begin{array}{ccc}
 & \mathfrak{T}(a, b) \times \mathfrak{T}(a, a) & \\
 1 \times I_a \nearrow & \Downarrow \mathfrak{r} & \searrow \otimes \\
 \mathfrak{T}(a, b) & \xrightarrow{1} & \mathfrak{T}(a, b)
 \end{array}$$

in **Bicat** $(\mathfrak{T}(a, b), \mathfrak{T}(a, b))$ exists.

(7) For $a, b, c, d, e \in \text{Ob} \mathfrak{T}$, an isomorphism 2-cell π (i.e., an invertible modification)

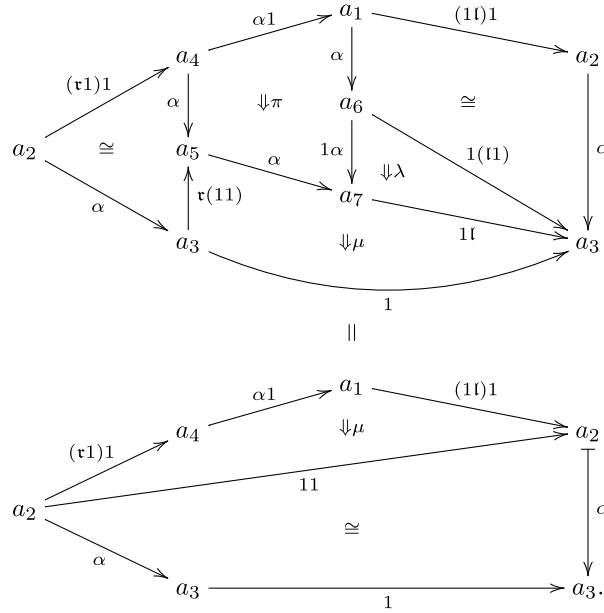
in the bicategory $\mathbf{Bicat}(\mathfrak{T}^4(a, b, c, d, e), \mathfrak{T}(a, e))$ exists, where $\mathfrak{T}^4 = \mathfrak{T}^4(a, b, c, d, e)$ is abbreviation for $\mathfrak{T}(d, e) \times \mathfrak{T}(c, d) \times \mathfrak{T}(b, c) \times \mathfrak{T}(a, b)$.

(8) For objects a, b, c of $\mathfrak{T}$, invertible modifications exist.



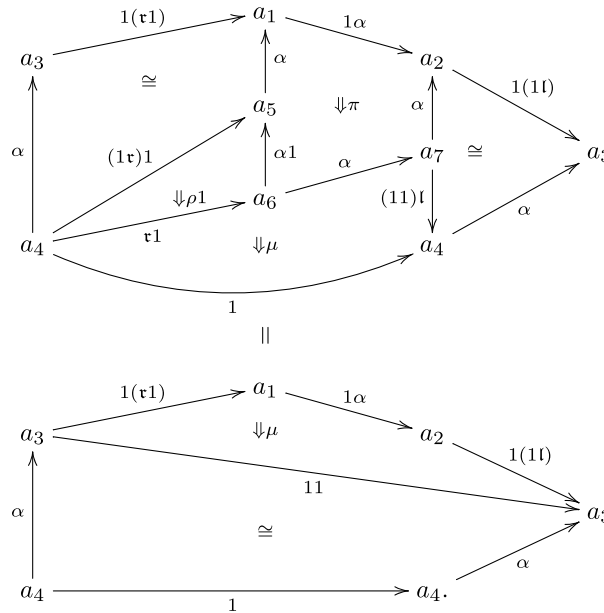
(2) [Left normalization] The following equation of 2-cells holds in the bicategory $\mathfrak{T}(a_1, a_4)$, where the unmarked isomorphisms are either naturality isomorphisms for α or unique coherence isomorphisms from the *Hom*-bicategory.

$$\begin{aligned} a_1 &= (h \otimes (l \otimes g)) \otimes f, & a_2 &= (h \otimes g) \otimes f, & a_3 &= h \otimes (g \otimes f), \\ a_4 &= ((h \otimes l) \otimes g) \otimes f, & a_5 &= (h \otimes l) \otimes (g \otimes f), & a_6 &= h \otimes ((l \otimes g) \otimes f), \\ a_7 &= h \otimes (l \otimes (g \otimes f)); \end{aligned}$$



(3) [Right normalization] The following equation of 2-cells holds in the bicategory $\mathfrak{T}(a_1, a_4)$.

$$\begin{aligned} a_1 &= h \otimes ((g \otimes l) \otimes f), & a_2 &= h \otimes (g \otimes (l \otimes f)), & a_3 &= h \otimes (g \otimes f), \\ a_4 &= (h \otimes g) \otimes f, & a_5 &= (h \otimes (g \otimes l)) \otimes f, & a_6 &= ((h \otimes g) \otimes l) \otimes f, \\ a_7 &= (h \otimes g) \otimes (l \otimes f); \end{aligned}$$



Example 2.2.

- (1) A monoidal bicategory is a tricategory with a single object.
- (2) **BiCat** is a tricategory with objects being bicategories; 1-cells are homomorphisms between these bicategories; 2-cells are pseudonatural transformations; and 3-cells are modifications. As seen in [18], **BiCat** is not triequivalent to **Gray**, but it can be **Gray**-categorized in a special way [17].
- (3) Fundamental 3-groupoids are tricategories. 3-groupoids are a generalization of 2-groupoids in higher-dimensional category theory. If we look at fundamental groupoids with a higher categorical approach, the fundamental 3-groupoid is a tricategory whose objects are spaces, 1-cells are continuous maps, and higher cells are the appropriate mediator homotopy types. This structure is explored in detail in [19]. In [17], in terms of the fundamental 3-groupoid, the objects of an X space are points of X , and the higher cells are paths, two-dimensional disks, and equivalence classes of three-dimensional disks in X . This structure is also a tricategory.

Remark 2.3. A tricategory is strict if all of its constraints are identities; that is, if the invertible modifications (5)–(8) in Definition 2.1 are identities [9].

Lemma 2.4. Let $\mathfrak{T}$ be a tricategory; if it satisfies the following conditions, it is a cubical tricategory [17].

- (1) Each bicategory $\mathfrak{T}(a, b)$ is a strict 2-category.
- (2) Each functor $I_a : 1 \rightarrow \mathfrak{T}(a, a)$ is a cubical functor.
- (3) For objects a, b , and c of $Ob\mathfrak{T}$, each $\otimes : \mathfrak{T}(b, c) \times \mathfrak{T}(a, b) \rightarrow \mathfrak{T}(a, c)$ is a cubical functor.

Definition 2.5. Let $\mathfrak{T}$ and $\mathfrak{T}'$ be tricategories. A trihomomorphism $\mathfrak{F}$ from $\mathfrak{T}$ to $\mathfrak{T}'$ is a map that consists of the following data and axioms:

DATA:

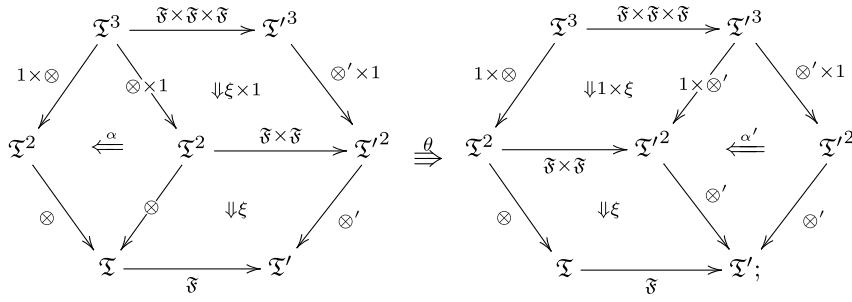
- (1) A morphism $Ob\mathfrak{T} \rightarrow Ob\mathfrak{T}'$.
- (2) For $a, b \in Ob\mathfrak{T}$, a functor $\mathfrak{F}_{ab} : \mathfrak{T}(a, b) \rightarrow \mathfrak{T}'(\mathfrak{F}a, \mathfrak{F}b)$.
- (3) For a, b , and $c \in Ob\mathfrak{T}$, an adjoint equivalence $\xi : \otimes' \circ (\mathfrak{F} \times \mathfrak{F}) \Rightarrow \mathfrak{F} \circ \otimes$ with left adjoint is illustrated in the following diagram:

$$\begin{array}{ccc}
 \mathfrak{T}(b, c) \times \mathfrak{T}(a, b) & \xrightarrow{\mathfrak{F} \times \mathfrak{F}} & \mathfrak{T}'(\mathfrak{F}b, \mathfrak{F}c) \times \mathfrak{T}'(\mathfrak{F}a, \mathfrak{F}b) \\
 \downarrow \otimes & \nearrow \xi & \downarrow \otimes' \\
 \mathfrak{T}(a, c) & \xrightarrow{\mathfrak{F}} & \mathfrak{T}'(\mathfrak{F}a, \mathfrak{F}c);
 \end{array}$$

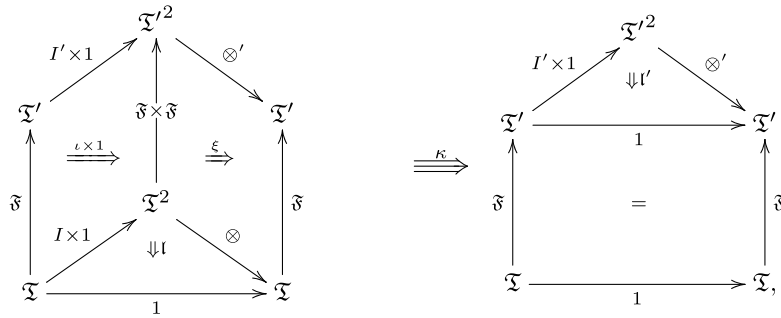
- (4) For all $a \in Ob\mathfrak{T}$, an adjoint equivalence $\iota : I'_{\mathfrak{F}a} \Rightarrow \mathfrak{F} \circ I_a$ with left adjoint is illustrated in the following diagram:

$$\begin{array}{ccc}
 1 & \xrightarrow{I'_{\mathfrak{F}a}} & \mathfrak{T}'(\mathfrak{F}a, \mathfrak{F}a) \\
 \searrow I_a & \Downarrow \iota & \nearrow \mathfrak{F} \\
 & \mathfrak{T}(a, a); &
 \end{array}$$

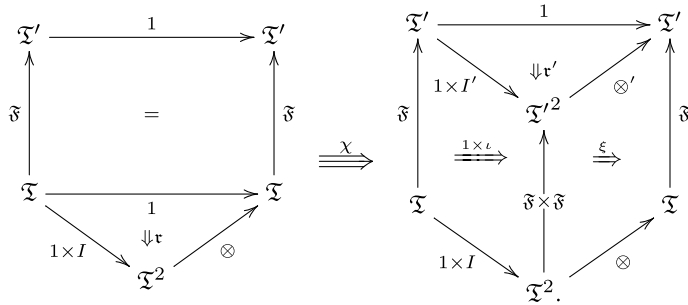
(5) For $a, b, c, d \in \text{Ob} \mathfrak{T}$, an invertible modification θ is illustrated in the following diagram:



(6) For $a, b \in \text{Ob} \mathfrak{T}$, invertible modifications κ and χ is illustrated in the following diagram:



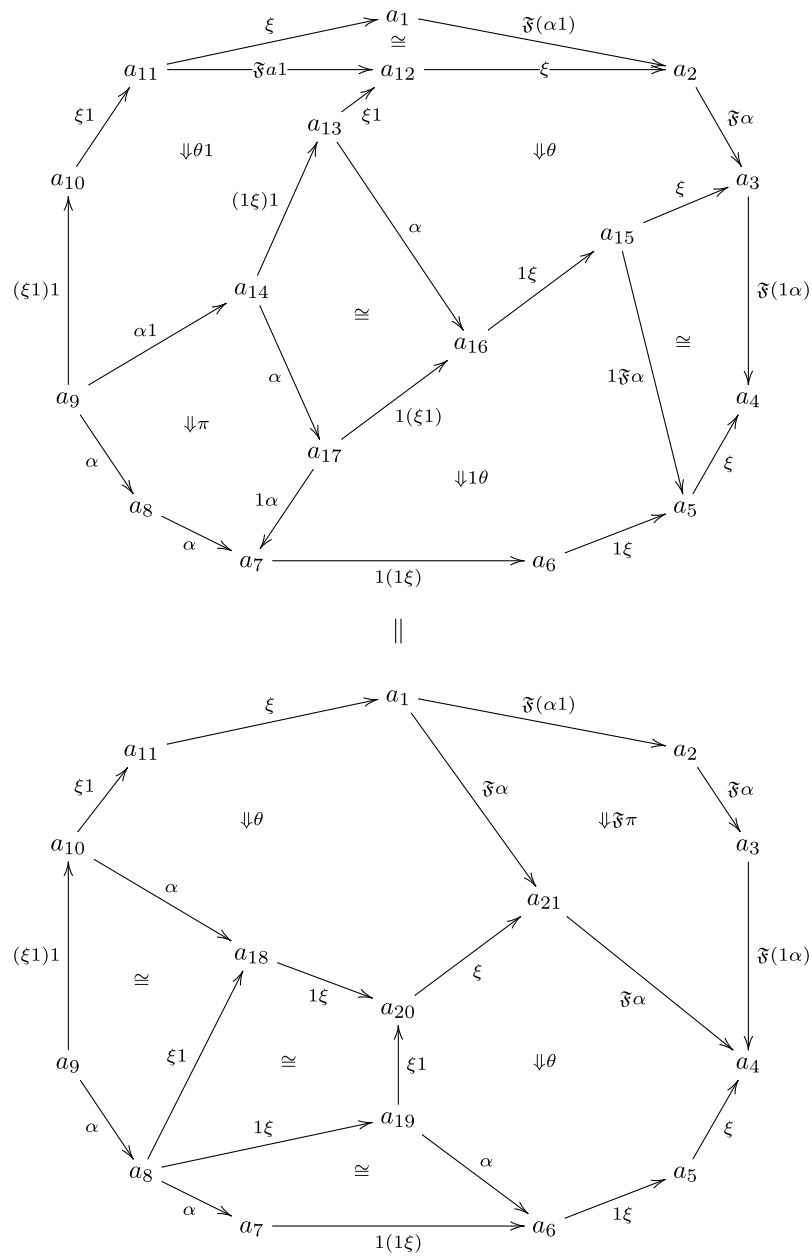
and



AXIOMS:

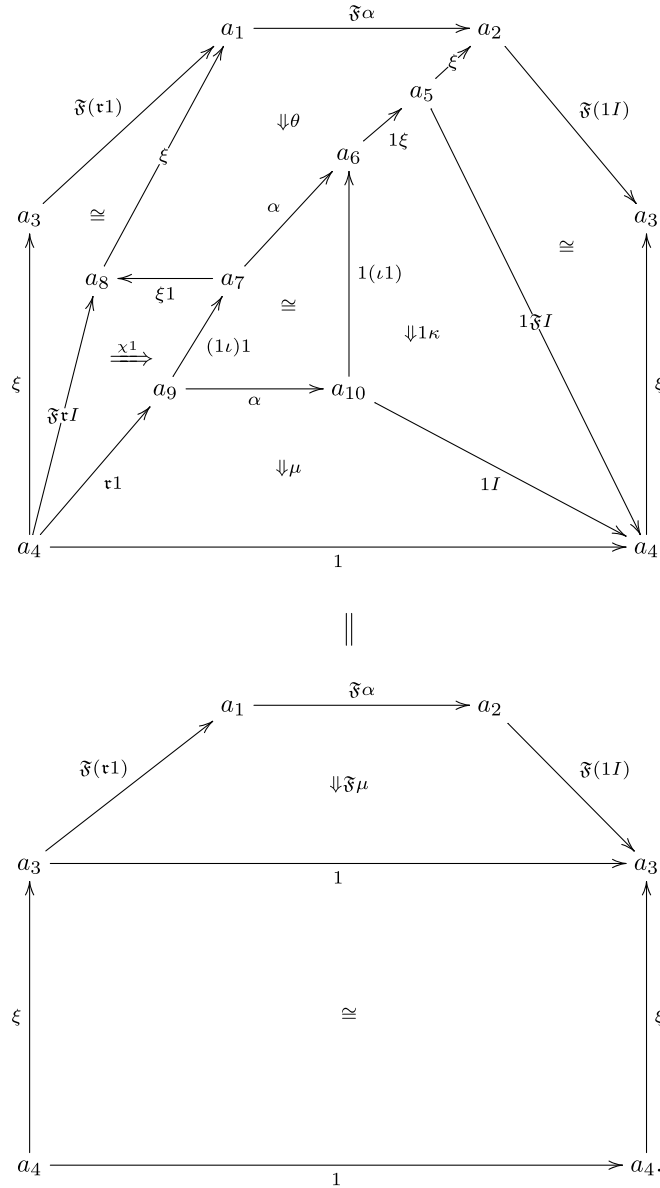
(1) For all 1-morphisms $(x, y, z, w) \in \mathfrak{T}(d, e) \times \mathfrak{T}(c, d) \times \mathfrak{T}(b, c) \times \mathfrak{T}(a, b)$, the following equation of modifications holds:

$$\begin{array}{lll}
 a_1 = \mathfrak{T}(((fg)j)k), & a_2 = \mathfrak{T}((f(gj))k), & a_3 = \mathfrak{T}(f((gj)k)), \\
 a_4 = \mathfrak{T}(f(g(jk))), & a_5 = \mathfrak{T}f(\mathfrak{T}g(jk)), & a_6 = \mathfrak{T}f(\mathfrak{T}g\mathfrak{T}(jk)), \\
 a_7 = \mathfrak{T}f(\mathfrak{T}g(\mathfrak{T}j\mathfrak{T}k)), & a_8 = (\mathfrak{T}f\mathfrak{T}g)(\mathfrak{T}j\mathfrak{T}k), & a_9 = ((\mathfrak{T}f\mathfrak{T}g)\mathfrak{T}j)\mathfrak{T}k, \\
 a_{10} = (\mathfrak{T}(f\mathfrak{T}g)\mathfrak{T}j)\mathfrak{T}k, & a_{11} = \mathfrak{T}((fg)j)\mathfrak{T}k, & a_{12} = \mathfrak{T}(f(gj))\mathfrak{T}k, \\
 a_{13} = (\mathfrak{T}f\mathfrak{T}(gj))\mathfrak{T}k, & a_{14} = (\mathfrak{T}f(\mathfrak{T}g\mathfrak{T}j))\mathfrak{T}k, & a_{15} = \mathfrak{T}f\mathfrak{T}((gj))k, \\
 a_{16} = \mathfrak{T}f(\mathfrak{T}(gj)\mathfrak{T}k), & a_{17} = \mathfrak{T}f(\mathfrak{T}(gj)\mathfrak{T}k), & a_{18} = \mathfrak{T}(fg)(\mathfrak{T}j\mathfrak{T}k), \\
 a_{19} = (\mathfrak{T}f\mathfrak{T}g)\mathfrak{T}(jk), & a_{20} = \mathfrak{T}(fg)\mathfrak{T}(jk), & a_{21} = \mathfrak{T}((fg)(jk));
 \end{array}$$



(2) For all 1-cells $(x, y) \in \mathfrak{T}(b, c) \times \mathfrak{T}(a, b)$, the following equation of modifications holds:

$$\begin{aligned}
 a_1 &= \mathfrak{F}((fI)g), & a_2 &= \mathfrak{F}(f(Ig)), & a_3 &= \mathfrak{F}(fg), \\
 a_4 &= \mathfrak{F}f\mathfrak{F}g, & a_5 &= \mathfrak{F}f\mathfrak{F}(Ig), & a_6 &= \mathfrak{F}f(\mathfrak{F}I\mathfrak{F}g), \\
 a_7 &= (\mathfrak{F}f\mathfrak{F}I)\mathfrak{F}g, & a_8 &= \mathfrak{F}(fI)\mathfrak{F}g, & a_9 &= (\mathfrak{F}fI)\mathfrak{F}g, \\
 a_{10} &= \mathfrak{F}f(I\mathfrak{F}g);
 \end{aligned}$$



3 Algebraic type models for homotopy theory

3.1 Algebraic 2-types

In this section, we will give information about crossed modules.

Definition 3.1. A crossed module of groups, $\mathcal{G}_1 = (E \xrightarrow{\partial} G)$, consists of two groups G and E with a left group action of G on E , and group homomorphism $\partial : E \rightarrow G$ satisfying the following conditions:

$\mathcal{XMOD-1}$ $\partial({}^g e) = g\partial(e)g^{-1}$, $\forall g \in G$ and $e \in E$,

$\mathcal{XMOD-2}$ $\partial(e)e' = ee'e^{-1}$, $\forall e, e' \in E$.

If $\mathcal{G}_1 = (E \xrightarrow{\partial} G)$ only satisfies the $\mathcal{XMOD-1}$ condition, it is a pre-crossed module.

Example 3.2.

- (1) Let G be a group and $\text{Aut}(G)$ be the automorphism group of group G . With the conjugation homomorphism ϕ , the following structure is a crossed module:

$$\phi : G \longrightarrow \text{Aut}(G).$$

This structure is called the automorphism crossed module of group G .

- (2) Let $F \xrightarrow{i} E \xrightarrow{p} B$ be a fibration sequence of pointed spaces. Then, p is a fibration that satisfies $F = p^{-1}(b_0)$, where b_0 is the basepoint of B . Say that the fibre F is pointed at f_0 , and f_0 is also considered to be the basepoint of E . Then, we have an induced map of fundamental groups as follows:

$$\pi_1(F) \xrightarrow{\pi_1(i)} \pi_1(E).$$

Triple $(\pi_1(F), \pi_1(E), \pi_1(i))$ is a crossed module. Refer [20] for detailed information.

Definition 3.3. Let $\mathcal{G}_1 = (E \xrightarrow{\partial} G)$ and $\mathcal{G}'_1 = (E' \xrightarrow{\partial'} G')$ be two crossed modules of groups. A $f = (f_1, f_0)$ morphism of crossed modules from $\mathcal{G}_1$ to $\mathcal{G}'_1$ consists of group homomorphisms $f_1 : E \rightarrow E'$ and $f_0 : G \rightarrow G'$, also the following equations are satisfied:

- (1) $f_0 \partial = \partial' f_1$,
 - (2) $f_1({}^g e) = f_0(g) f_1(e)$,
- for each $g \in G$ and $e \in E$.

Thus, we can define the category $\mathcal{XMOD}_{Grp}$, formed by the crossed modules of groups and their morphisms.

Now let us categorically express the crossed module $\mathcal{G}_1 = (E \xrightarrow{\partial} G)$. Kamps and Porter [14] barely mentioned that one converts a crossed module to a 2-groupoid, but we will give in detail how to construct a 2-group $\mathfrak{G}(\mathcal{G}_1)$ (strict 2-groupoid with one object) as follows.

$\{\bullet\}$ is the 0-cells of the $\mathfrak{G}(\mathcal{G}_1)$ 2-groupoid that we will construct. The bottom group of the crossed module, G , forms the 1-cells (elements of group G) of this 2-groupoid. The composition “ $\#_0$ ” is defined as follows:

$$\bullet \xrightarrow{g_2} \bullet \xrightarrow{g_1} \bullet \\ \text{with } g_1 \#_0 g_2 = g_1 g_2$$

The semi-direct product group $E \rtimes G$ will give the 2-cells of $\mathfrak{G}(\mathcal{G}_1)$. For the 2-cell (e, g) , ($g \in G$ and $e \in E$), the 1-source and 1-target are $s_1((e, g)) = g$ and $t_1((e, g)) = \partial(e)g$, respectively. In addition, for each $g \in G$, $i_1(g) = (1_E, g)$. This is the picture of 2-cell (e, g)

$$(e, g) : g \rightrightarrows \partial(e)g : \bullet \longrightarrow \bullet,$$

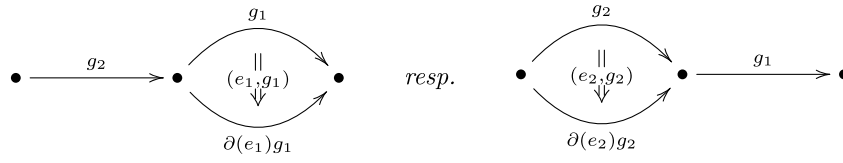
from the 2-categorical point of view, as follows:

$$\begin{array}{ccc} & g & \\ & \parallel & \\ \bullet & \xrightarrow{(e, g)} & \bullet \\ & \downarrow \partial(e)g & \end{array}$$

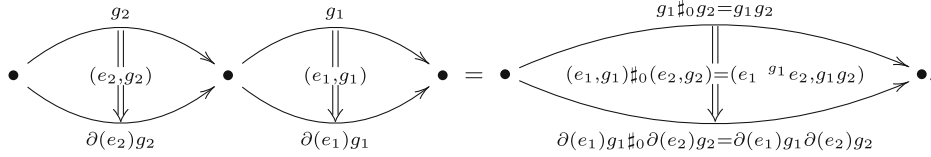
3.1.1 Horizontal composition of 2-cells

Suppose $(e_2, g_2) : g_2 \rightrightarrows \partial(e_2)g_2 : \bullet \longrightarrow \bullet$ and $(e_1, g_1) : g_1 \rightrightarrows \partial(e_1)g_1 : \bullet \longrightarrow \bullet \in E \rtimes G$, then $(e_1, g_1) \#_0 (e_2, g_2) = (e_1, g_1)(e_2, g_2) = (e_1 e_2, g_1 g_2)$. Thus, the horizontal composition “ $\#_0$ ” for 2-cells is defined as follows. First, let us define whiskering compositions as follows.

Whiskering as



clearly gives $(e_1, g_1 g_2)$ and $(e_1^{g_1} e_2, g_1 g_2)$, respectively. The duality of whiskerings is defined similarly. Naturally, the horizontal composition of 2-cells of 2-groupoid $\mathfrak{G}(\mathcal{G}_1)$ is shown from the 2-categorical point of view as follows:



From the definition of the 1-source s_1 and 1-target t_1 , we have

$$s_1((e_1, g_1) \#_0 (e_2, g_2)) = s_1(e_1^{g_1} e_2, g_1 g_2) = g_1 g_2$$

and

$$\begin{aligned} t_1((e_1, g_1) \#_0 (e_2, g_2)) &= t_1(e_1^{g_1} e_2, g_1 g_2) \\ &= \partial(e_1^{g_1} e_2) g_1 g_2 \\ &= \partial(e_1) \partial(e_1^{g_1} e_2) g_1 g_2 \\ &= \partial(e_1) g_1 \partial(e_2) g_1^{-1} g_1 g_2 \\ &= \partial(e_1) g_1 \partial(e_2) g_2. \end{aligned}$$

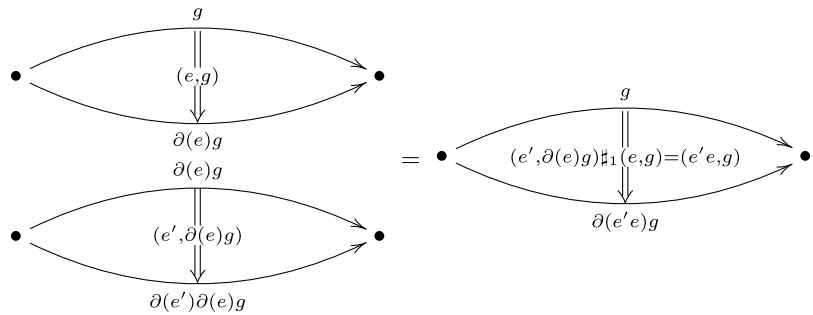
In the last calculations, we used $\mathcal{XMOD}$ -1 in Definition 3.1.

3.1.2 Vertical composition of 2-cells

Suppose $(e', \partial(e)g)$ is another element in $(E \rtimes G)$. The vertical composition “ $\#_1$ ” of 2-cells is given by

$$(e', \partial(e)g) \#_1 (e, g) = (e'e, g).$$

The vertical composition of 2-cells is illustrated as follows:



$$s_1((e', \partial(e)g) \#_1 (e, g)) = s_1(e'e, g) = g,$$

and

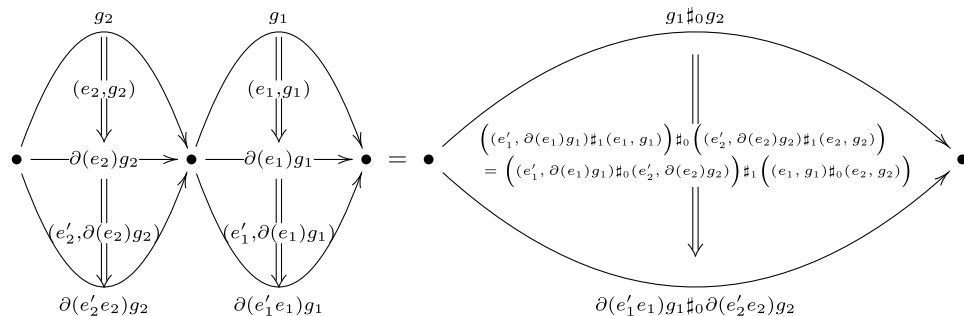
$$t_1((e', \partial(e)g) \#_1 (e, g)) = t_1(e'e, g) = \partial(e'e)g.$$

3.1.3 Interchange law of 2-cells

The $\mathcal{XMOD}$ -2 condition in the definition of crossed module of groups 3.1 establishes the interchange law between the horizontal and vertical compositions, and as a result, we have a strict 2-groupoid. The interchange law holds. It is explicitly expressed as

$$\begin{aligned}
 ((e'_1, \partial(e_1)g_1) \#_1 (e_1, g_1)) \#_0 ((e'_2, \partial(e_2)g_2) \#_1 (e_2, g_2)) &= (e'_1 e_1, g_1) \#_0 (e'_2 e_2, g_2) \\
 &= (e'_1 e_1 g_1 (e'_2 e_2), g_1 g_2) \\
 &= (e'_1 e_1^{g_1} e'_2 e_1^{-g_1} e_2, g_1 g_2) \\
 &= (e_1^{\partial(e_1)} (e'_1 e'_2) e_1^{g_1} e_2, g_1 g_2) \\
 &= (e_1^{\partial(e_1)g_1} e'_2 e'_2 e_1^{g_1} e_2, g_1 g_2) \\
 &= (e_1^{\partial(e_1)g_1} e'_2, \partial(e_1)g_1 \partial(e_2)g_2) \#_1 (e_1^{g_1} e_2, g_1 g_2) \\
 &= ((e'_1, \partial(e_1)g_1) \#_0 (e'_2, \partial(e_2)g_2)) \#_1 ((e_1, g_1) \#_0 (e_2, g_2)),
 \end{aligned}$$

and it can be drawn as follows:



Consequently, we construct the following strict 2-group structure:

$$\mathfrak{G}(\mathcal{G}_1) = \left(E \times G \begin{array}{c} \xrightarrow{s_1} \\ \xleftarrow{t_1} \end{array} G \begin{array}{c} \xrightarrow{s_0} \\ \xleftarrow{t_0} \end{array} \{\bullet\} \right).$$

i_1 i_0

Conversely, any strict 2-group is a crossed module of groups. More specifically, let $\mathfrak{G}$ be a 2-groupoid with a single object as follows:

$$\mathfrak{G} = \left(G_2 \begin{array}{c} \xrightarrow{s_1} \\ \xleftarrow{t_1} \end{array} G_1 \begin{array}{c} \xrightarrow{s_0} \\ \xleftarrow{t_0} \end{array} G_0 = \{\bullet\} \right).$$

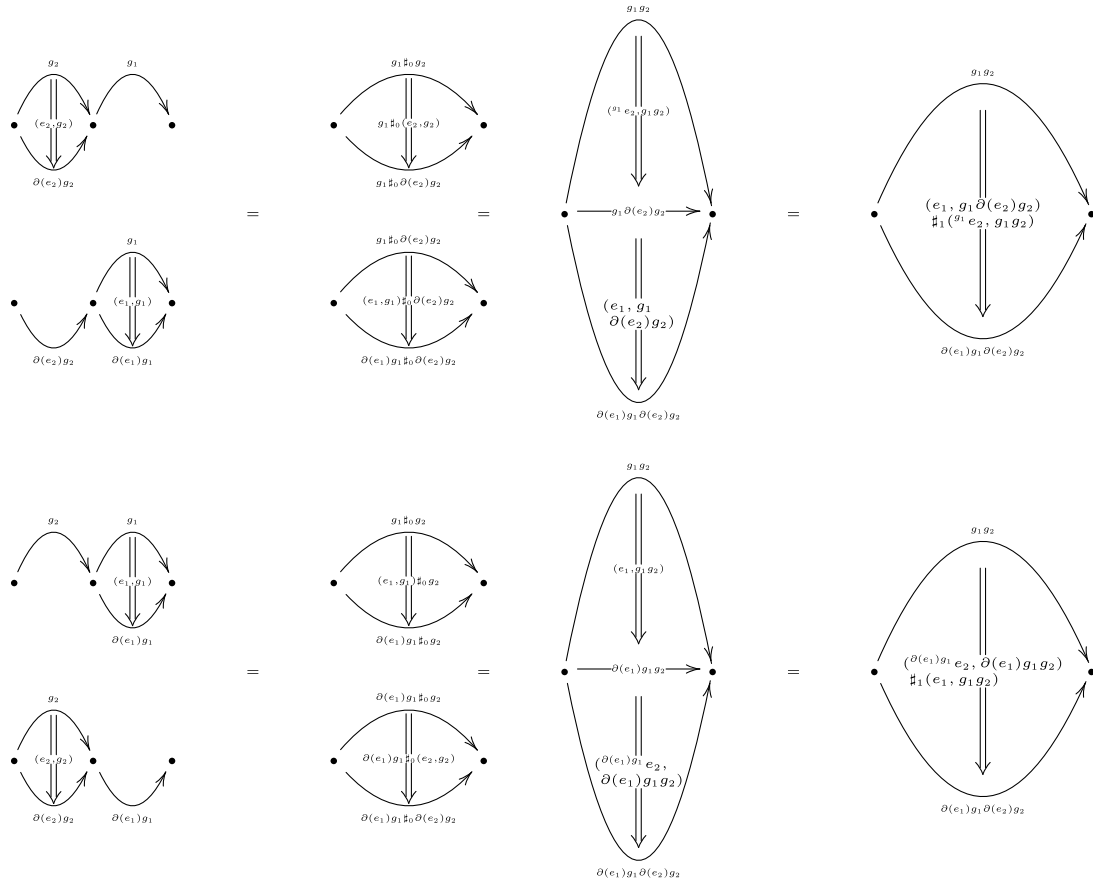
i_1 i_0

To obtain the crossed module of groups from a strict 2-group $\mathfrak{G}$, we have $\{\bullet\} = G_0$, $G = G_1$, and $E = \text{Ker}s_1 \subseteq G_2$. Let $\partial : E \rightarrow G$ be the restriction of the 1-target map $t_1 : G_2 \rightarrow G_1$, and the left action is as follows:

$${}^g e = i_1(g) \#_0 e \#_0 i_1(g)^{-1}$$

for each $g \in G$ and $e \in E$.

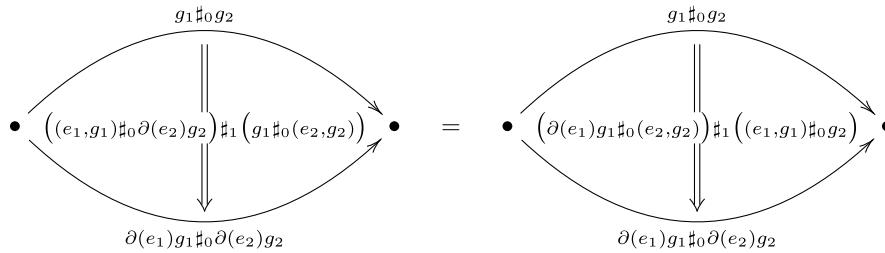
Naturally, any crossed module is a sesquicategory. If we look at it in more detail as follows, it satisfies the condition of being a sesquicategory becoming a 2-category in [12,21]. For all $g \in G$ and $e \in E$, we have:



Therefore, we have

$$\begin{aligned}
 ((e_1, g_1) \#_0 \partial(e_2)g_2) \#_1 (g_1 \#_0 (e_2, g_2)) &= (e_1, g_1 \partial(e_2)g_2) \#_1 (g_1 e_2, g_1 g_2) \\
 &= (e_1 g_1 e_2, g_1 g_2) \\
 &= (e_1 g_1 e_2 e_1^{-1} e_1, g_1 g_2) \\
 &= (\partial(e_1) (g_1 e_2) e_1, g_1 g_2) \\
 &= (\partial(e_1) g_1 e_2 e_1, g_1 g_2) \\
 &= (\partial(e_1) g_1 e_2, \partial(e_1) g_1 g_2) \#_1 (e_1, g_1 g_2) \\
 &= (\partial(e_1) g_1 \#_0 (e_2, g_2)) \#_1 ((e_1, g_1) \#_0 g_2).
 \end{aligned}$$

We can diagrammatically represent this sesquicategory condition as follows:



The 2-group construction that we obtained above can also be constructed from the bicategory perspective that Jean Bénabou gives in [10]. Roughly, in the bicategory $\mathfrak{B}(\mathcal{G}_1)$, we construct from the crossed module $\mathcal{G}_1$, $Ob\mathfrak{B}(\mathcal{G}_1) = \{\bullet\}$ is the set of objects, and for $\bullet \in Ob\mathfrak{B}(\mathcal{G}_1)$, $\mathfrak{B}(\mathcal{G}_1)(\bullet, \bullet)$ is a category, as shown below:

$$\mathfrak{B}(\mathcal{G}_1)(\bullet, \bullet) = \left(\begin{array}{ccc} & g & \\ \bullet & \begin{array}{c} \xrightarrow{\quad} \\ \parallel \\ \xleftarrow{\quad} \end{array} & \bullet \\ & \partial(e)g & \end{array} \right)$$

- **Objects:** Every 1-cell, $g : \bullet \rightarrow \bullet \in G$, is an object.
- **1-Morphisms:** Every 2-cell, $(e, g) : g \Rightarrow \partial(e)g \in E \rtimes G$, is a 1-morphism. $\mathfrak{B}(\mathcal{G}_1)(\bullet, \bullet)$ is a strict category with the composition $\#_1$.

3.2 Algebraic 3-types

First of all, we give related knowledge about the 2-crossed modules of groups given in [13,22,23].

Definition 3.4. A 2-crossed module of groups $\mathcal{G}_2 = (L \xrightarrow{\delta} E \xrightarrow{\partial} G, \{-, -\})$ is a semi-exact sequence of G-groups, together with left group actions of G on E and L (and on G by conjugation), and a G -equivariant function,

$$\{-, -\} : E \times E \longrightarrow L,$$

called the Peiffer lifting. Here G -equivariance means:

$${}^g\{e_1, e_2\} = \{{}^g e_1, {}^g e_2\}.$$

For each $g \in G$ and $e_1, e_2 \in E$ the following should be satisfied:

2XMOD-1 $\partial\delta = 1$,

2XMOD-2 $\delta(\{e_1, e_2\}) = \langle e_1, e_2 \rangle = e_1 e_2 e_1^{-1} \partial(e_1) e_2^{-1}$,

2XMOD-3 $\{\delta(l_1), \delta(l_2)\} = [l_1, l_2] = l_1 l_2 l_1^{-1} l_2^{-1}$,

2XMOD-4 $\{\delta(l), e\} \{e, \delta(l)\} = l^{\partial(e)} l_{-1}$,

2XMOD-5 $\{e_1 e_2, e_3\} = \{e_1, e_2 e_3 e_2^{-1} \partial(e_1)\} \{e_2, e_3\}$,

2XMOD-6 $\{e_1, e_2 e_3\} = \{e_1, e_2\}^{\partial(e_1) e_2} \{e_1, e_3\}$,

for each $g \in G$, $e \in E$, and $l \in L$.

Remark 3.5. It should be noted that $(L \xrightarrow{\delta} E)$ is a crossed module, with

$${}_e l = l \{\delta(l)^{-1}, e\}$$

for each $e \in E$ and $l \in L$. However, $(E \xrightarrow{\partial} G)$ is just a pre-crossed module.

Lemma 3.6. Let $\mathcal{G}_2 = (L \xrightarrow{\delta} E \xrightarrow{\partial} G, \{-, -\})$ be a 2-crossed module of groups. Then, ${}^g(e)l = {}^g e({}^g l)$, for each $g \in G$, $e \in E$, and $l \in L$ [22,23].

Example 3.7.

- (1) From a functorial point of view, any crossed module of groups $E \xrightarrow{\partial} G$ is a 2-crossed module $1 \xrightarrow{0} E \xrightarrow{\partial} G$, with trivial Pfeiffer lifting [20].
- (2) The quadratic modules that Baues [24] defined are a special version of the 2-crossed modules, satisfying certain additional nilpotency conditions. Refer [25] for its relation to 2-crossed modules.

Definition 3.8. Let $\mathcal{G}_2 = (L \xrightarrow{\delta} E \xrightarrow{\partial} G, \{-, -\})$ and $\mathcal{G}' = (L' \xrightarrow{\delta'} E' \xrightarrow{\partial'} G', \{-, -\})$ be two 2-crossed modules of groups. A morphism of 2-crossed modules from $\mathcal{G}$ to $\mathcal{G}'$ is illustrated by the following commutative diagram:

$$\begin{array}{ccccc} L & \xrightarrow{\delta} & E & \xrightarrow{\partial} & G \\ f_2 \downarrow & & f_1 \downarrow & & \downarrow f_0 \\ L' & \xrightarrow{\delta'} & E' & \xrightarrow{\partial'} & G', \end{array}$$

where $f_2 : L \rightarrow L'$, $f_1 : E \rightarrow E'$, and $f_0 : G \rightarrow G'$ are group homomorphisms, and also the following equations are satisfied:

$$\begin{aligned} f_1({}^g e) &= f_0({}^g e) f_1(e), \\ f_2({}^g l) &= f_0({}^g l) f_2(l), \\ f_2(\{e_1, e_2\}) &= \{f_1(e_1), f_1(e_2)\}, \end{aligned}$$

for each $g \in G$, $e \in E$, and $l \in L$.

We shall let $2XMOD_{Grp}$ denote the category whose objects are 2-crossed modules of groups and morphisms are morphisms of 2-crossed modules, as defined above.

Now let us construct a 2-crossed module $\mathcal{G}_2 = (L \xrightarrow{\delta} E \xrightarrow{\partial} G, \{-, -\})$ as a categorical $\mathfrak{G}(\mathcal{G}_2)$. We have:

$$\mathfrak{G}(\mathcal{G}_2)_0 = \{\bullet\}, \quad \mathfrak{G}(\mathcal{G}_2)_1 = G, \quad \mathfrak{G}(\mathcal{G}_2)_2 = E \rtimes G, \quad \mathfrak{G}(\mathcal{G}_2)_3 = L \rtimes E \rtimes G.$$

The 1-, 2-, and 3-cells are as follows:

$$(l, e, g) : (e, g) \rightrightarrows (\delta(l)e, g) : g \rightrightarrows \partial(e)g : \bullet \longrightarrow \bullet,$$

for $g \in G$, $e \in E$, and $l \in L$. For the 3-cell (l, e, g) , the 2-source and 2-target are $s_2((l, e, g)) = (e, g)$ and $t_2((l, e, g)) = (\delta(l)e, g)$, respectively. In addition, for each $g \in G$ and $e \in E$, $i_2((e, g)) = (1_L, e, g)$. We can show it 2-categorically diagrammatically as follows:

$$\begin{array}{ccc} & (e, g) & \\ & \downarrow \parallel & \\ g & \xrightarrow{\quad} & \partial(e)g. \\ & \uparrow \parallel & \\ & (\delta(l)e, g) & \end{array}$$

If we want to picture this structure 3-categorically diagrammatically, we can describe it as follows:

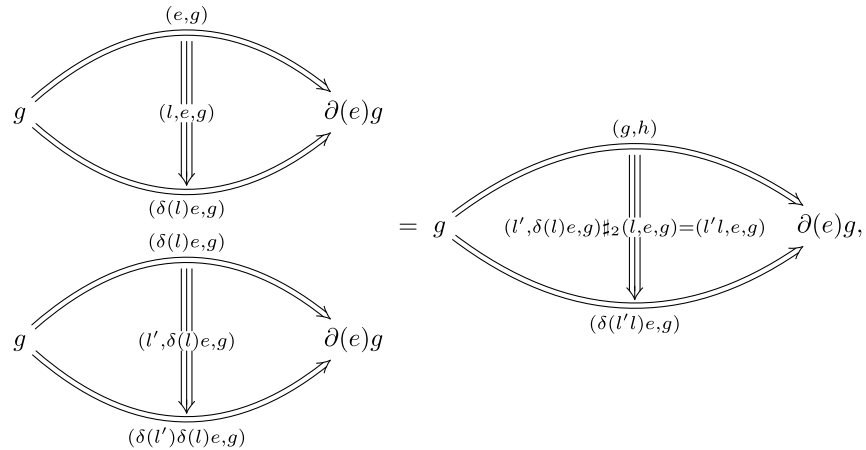
$$\begin{array}{ccc} & g & \\ & \downarrow & \\ \bullet & \xrightarrow{\quad} & \bullet \\ & \uparrow & \\ & \partial(e)g & \end{array}$$

3.2.1 Vertical composition of 3-cells

Suppose $(l', \delta(l)e, g)$ is another element in $(L \rtimes E \rtimes G)$. The vertical composition “ $\#_2$ ” of 3-cells is given by

$$(l', \delta(l)e, g) \#_2 (l, e, g) = (l'l, e, g).$$

The vertical composition of 3-cells is illustrated as follows:



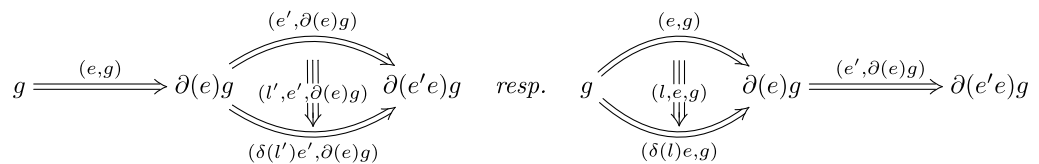
$$s_2((l', \delta(l)e, g) \#_2 (l, e, g)) = s_2((l'l, e, g)) = (e, g)$$

and

$$t_2((l', \delta(l)e, g) \#_2 (l, e, g)) = t_2((l'l, e, g)) = (\delta(l'l)e, g).$$

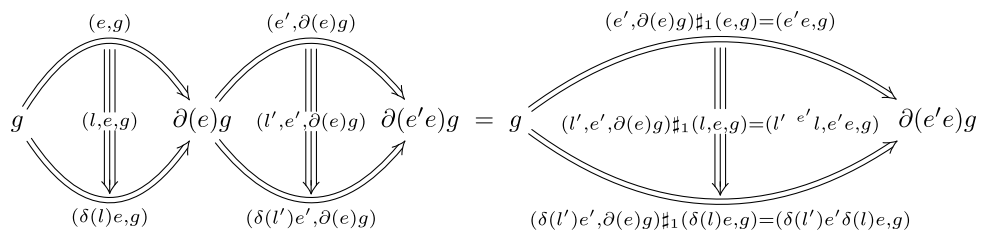
3.2.2 Horizontal composition of 3-cells

Whiskering as



clearly gives $(l', e', \partial(e)g) \#_1 (e, g) = (l', e'e, g)$ and $(e', \partial(e)g) \#_1 (l, e, g) = (e'l, e'e, g)$, respectively. Naturally, 2-source and 2-target are defined as follows: $s_2((l', e'e, g)) = (e'e, g) = s_2((e'l, e'e, g))$, $t_2((l', e'e, g)) = (\delta(l')e'e, g)$, and $t_2((e'l, e'e, g)) = (e'\delta(l)e, g)$. The horizontal composition “ $\#_1$ ” of 3-cells is given by

$$(l', e', \partial(e)g) \#_1 (l, e, g) = (l'e'l, e'e, g).$$



$$s_2((l', e', \partial(e)g) \#_1 (l, e, g)) = s_2((l'e'l, e'e, g)) = (e'e, g)$$

and

$$\begin{aligned}
 t_2((l', e', \partial(e)g) \#_1 (l, e, g)) &= t_2((l' e' l, e' e, g)) \\
 &= (\delta(l' e' l) e' e, g) \\
 &= (\delta(l') \delta(l' e' l) e' e, g) \\
 &= (\delta(l') \delta(l' \{\delta(l)^{-1}, e'\}) e' e, g) \\
 &= (\delta(l') \delta(l) \delta(\{\delta(e)^{-1}, g'\}) e' e, g) \\
 &= (\delta(l') \delta(l) (\delta(l)^{-1}, e') e' e, g) \\
 &= (\delta(l') \delta(l) \delta(l)^{-1} e' (\delta(l)^{-1})^{-1} \partial(\delta(l)^{-1}) e'^{-1} e' e, g) \\
 &= (\delta(l') e' \delta(l) e, g).
 \end{aligned}$$

In the last calculations, we used $2\mathcal{XMOD}$ -1,2 in Definition 3.4 and Remark 3.5.

The compositions $\#_2$ and $\#_1$ of 3-cells are compatibles

$$\begin{aligned}
 &((l'_2, \delta(l'_1) e', \partial(e)g) \#_1 (l_2, \delta(l_1) e, g)) \#_2 ((l'_1, e', \partial(e)g) \#_1 (l, e, g)) \\
 &= (l'_2 (\delta(l'_1) e') l_2, \delta(l_1) e' \delta(l_1) e, g) \#_2 (l'_1 e' l_1, e' e, g) \\
 &= (l'_2 (\delta(l'_1) e') l'_2 l_2 l_1 l'_1, e' e, g) \\
 &= (l'_2 l'_1 e' l_2 l_1^{-1} l'_1 l_1, e' e, g) \\
 &= (l'_2 l'_1 e' l_2 l_1, e' e, g) \\
 &= (l'_2 l'_1 (l_2 l_1), e' e, g) \\
 &= (l'_2 l'_1, e', \partial(e)g) \#_1 (l_2 l_1, e, g) \\
 &= ((l'_2, \delta(l'_1) e', \partial(e)g) \#_2 (l'_1, e', \partial(e)g)) \#_1 ((l_2, \delta(l_1) e, g) \#_2 (l, e, g)).
 \end{aligned}$$

Diagrammatically,

As it can be seen, this equality is satisfied because $(L \xrightarrow{\delta} E)$ is a crossed module, see Remark 3.5. Interchange law,

$$\begin{aligned}
 &((l'_2, \delta(l'_1) e', \partial(e)g) \#_1 (l_2, \delta(l_1) e, g)) \#_2 ((l'_1, e', \partial(e)g) \#_1 (l, e, g)) \\
 &= ((l'_2, \delta(l'_1) e', \partial(e)g) \#_2 (l'_1, e', \partial(e)g)) \#_1 ((l_2, \delta(l_1) e, g) \#_2 (l, e, g))
 \end{aligned}$$

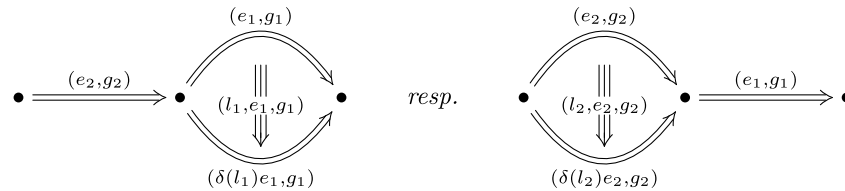
is satisfied for vertical $\#_2$ and horizontal $\#_1$ compositions of 3-cells.

3.2.3 0-Horizontal composition of 3-cells

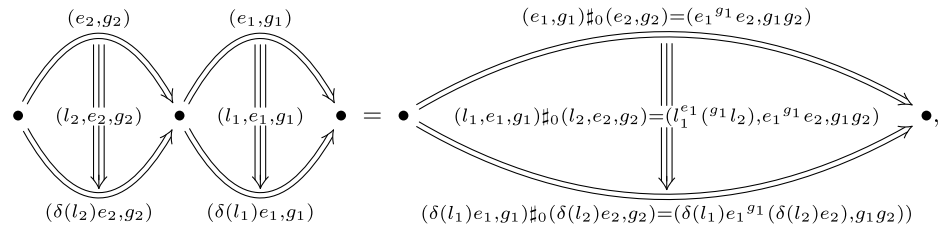
Furthermore, it is necessary to specify the 0-horizontal composition between the *Hom*-sets of 1-cells whose 0-sources and 0-targets are compatible. The 0-horizontal composition “ $\#_0$ ” of 3-cells is given by

$$(l_1, e_1, g_1) \#_0 (l_2, e_2, g_2) = (l_1^{e_1} (g_1 l_2), e_1 g_1 e_2, g_1 g_2).$$

Whiskering as



gives $(l_1, e_1^{g_1}e_2, g_1g_2)$ and $(e_1^{g_1}l_2, e_1^{g_1}e_2, g_1g_2)$, respectively. The composition “ $\#_0$ ” of 3-cells from a 3-categorical perspective is as follows:

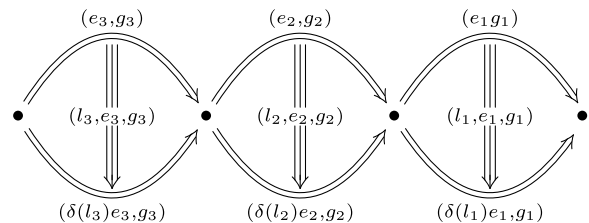


$$s_2((l_1, e_1, g_1)\#_0(l_2, e_2, g_2)) = s_2((l_1^{e_1}l_2, e_1^{g_1}e_2, g_1g_2)) = (e_1^{g_1}e_2, g_1g_2) = (e_1, g_1)\#_0(e_2, g_2)$$

and

$$\begin{aligned} t_2((l_1, e_1, g_1)\#_0(l_2, e_2, g_2)) &= t_2((l_1^{e_1}l_2, e_1^{g_1}e_2, g_1g_2)) \\ &= (\delta(l_1)^{e_1}(g_1l_2), e_1^{g_1}e_2, g_1g_2) \\ &= (\delta(l_1)\delta(e_1^{g_1}l_2), e_1^{g_1}e_2, g_1g_2) \\ &= (\delta(l_1)\delta(g_1l_2\{\delta(g_1l_2)^{-1}, e_1\}), e_1^{g_1}e_2, g_1g_2) \\ &= (\delta(l_1)\delta(g_1l_2)\delta(\{\delta(g_1l_2)^{-1}, e_1\}), e_1^{g_1}e_2, g_1g_2) \\ &= (\delta(l_1)\delta(g_1l_2)\delta(g_1l_2)^{-1}e_1(\delta(g_1l_2)^{-1})^{-1}\partial(\delta(g_1l_2)^{-1}), e_1^{-1}e_1^{g_1}e_2, g_1g_2) \\ &= (\delta(l_1)e_1\delta(g_1l_2)^{g_1}e_2, g_1g_2) \\ &= (\delta(l_1)e_1^{g_1}(\delta(l_2)e_2), g_1g_2) \\ &= (\delta(l_1)e_1, g_1)\#_0(\delta(l_2)e_2, g_2). \end{aligned}$$

In the last calculations, we used $2XMOD$ -1,-2 in Definition 3.4 and Remark 3.5. Furthermore, for 3-cells in the following diagram:



the composition $\#_0$ is associative as follows:

$$\begin{aligned} (l_1, e_1, g_1)\#_0((l_2, e_2, g_2)\#_0(l_3, e_3, g_3)) &= (l_1, e_1, g_1)\#_0(l_2^{e_2}(g_2l_3), e_2^{g_2}e_3, g_2g_3) \\ &= (l_1^{e_1}(l_2^{e_2}(g_2l_3)), e_1^{g_1}(e_2^{g_2}e_3), g_1g_2g_3) \\ &= (l_1^{e_1}(g_1l_2)^{e_1}(g_1e_2(g_2l_3)), e_1^{g_1}e_2g_1(g_2e_3), g_1g_2g_3) \\ &= (l_1^{e_1}(g_1l_2)^{e_1}e_2(g_1g_2l_3), e_1^{g_1}e_2^{g_1}e_3, g_1g_2g_3) \\ &= (l_1^{e_1}(g_1l_2), e_1^{g_1}e_2, g_1g_2)\#_0(l_3, e_3, g_3) \\ &= ((l_1, e_1, g_1)\#_0(l_2, e_2, g_2))\#_0(l_3, e_3, g_3). \end{aligned}$$

We used Lemma 3.6 to show that the composition $\#_0$ is associative.

The interchange law between compositions $\#_1$ and $\#_0$ is not satisfied as follows:

$$\begin{aligned} & ((l'_1, e'_1, \partial(e_1)g_1)\#_0(l'_2, e'_2, \partial(e_2)g_2))\#_1((l_1, e_1, g_1)\#_0(l_2, e_2, g_2)) \\ & \neq ((l'_1, e'_1, \partial(e_1)g_1)\#_1(l_1, e_1, g_1))\#_0((l'_2, e'_2, \partial(e_2)g_2)\#_1(l_2, e_2, g_2)). \end{aligned}$$

Because the tail of the 2-crossed module $\mathcal{G}_2, (E \xrightarrow{\partial} G)$, is just a pre-crossed module, see Remark 3.5. Therefore, the following structure is not a strict 3-groupoid with a single object. We have sestertius category (sestertius groupoid):

$$\mathfrak{G}(\mathcal{G}_2) = \left(L \rtimes E \rtimes G \begin{array}{c} \xrightarrow{s_2} \\ \xleftarrow{t_2} \end{array} E \rtimes G \begin{array}{c} \xrightarrow{s_1} \\ \xleftarrow{t_1} \end{array} G \begin{array}{c} \xrightarrow{s_0} \\ \xleftarrow{t_0} \end{array} \{\bullet\} \right).$$

$i_2 \qquad i_1 \qquad i_0$

Also, this structure is 3-globular (globularity means $s_n s_{n+1} = s_n t_{n+1}, t_n s_{n+1} = t_n t_{n+1}$.)

$$s_1 s_2((l, e, g)) = s_1((e, g)) = g = s_1((\delta(l)e, g)) = s_1 t_2((l, e, g))$$

and

$$\begin{aligned} t_1 s_2((l, e, g)) &= t_1((e, g)) \\ &= \partial(e)g \\ &= \partial \delta(l) \partial(e)g \\ &= \partial(\delta(l)e)g \\ &= t_1((\delta(l)e, g)) \\ &= t_1 t_2((l, e, g)), \end{aligned}$$

and reflexive (reflexive means $Id = s_n i_n = t_n i_n$.)

$$s_2 i_2((e, g)) = s_2((1_L, e, g)) = (e, g) = (\delta(1_L)e, g) = t_2((1_L, e, g)) = t_2 i_2((e, g)) = Id((e, g))$$

for each $g \in G, e \in E$, and $l \in L$.

It is also possible to proceed the other way for similar construction. Let us have a globular, reflexive, and strict sestertius category with one object as follows:

$$\mathfrak{G} = \left(G_3 \begin{array}{c} \xrightarrow{s_2} \\ \xleftarrow{t_2} \end{array} G_2 \begin{array}{c} \xrightarrow{s_1} \\ \xleftarrow{t_1} \end{array} G_1 \begin{array}{c} \xrightarrow{s_0} \\ \xleftarrow{t_0} \end{array} \{\bullet\} \right).$$

$i_2 \qquad i_1 \qquad i_0$

Then, the following left actions exist

$$\begin{aligned} G_1 \times G_2 &\longrightarrow G_2 \\ (a, b) &\longmapsto {}^a b = i_1(a)\#_0 b\#_0 i_1(a)^{-1}, \\ G_2 \times G_3 &\longrightarrow G_3 \\ (b, c) &\longmapsto {}^b c = i_2(b)\#_0 c\#_0 i_2(b)^{-1}, \\ G_1 \times G_3 &\longrightarrow G_3 \\ (a, c) &\longmapsto {}^a c = i_2 i_1(a)\#_0 c\#_0 i_2 i_1(a)^{-1}, \end{aligned}$$

for each $a \in G_1, b \in G_2$, and $c \in G_3$. With the help of these left actions, the following isomorphisms are defined:

$$\begin{aligned} G_2 &\longleftarrow \longrightarrow Kers_1 \rtimes G_1 \\ b &\longmapsto (b\#_1 i_1 s_1(b^{-1}), s_1(b)) \\ b\#_1 i_1(a) &\longleftarrow \dashv (b, a), \end{aligned}$$

For each $b \in G_2$,

$$b \mapsto (b\#_1 i_1 s_1(b^{-1}), s_1(b)) \mapsto b\#_1 i_1 s_1(b^{-1})\#_1 i_1 s_1(b) = b.$$

Similarly, for each $b \in \text{Kers}_1$ and $a \in G_1$,

$$(b, a) \mapsto b\#_1 i_1(a) \mapsto (b\#_1 i_1(a))\#_1 i_1 s_1(b\#_1 i_1(a))^{-1}, s_1(b\#_1 i_1(a)) = (b, a).$$

As a result, $G_2 \cong \text{Kers}_1 \rtimes G_1$. In the same way,

$$\begin{aligned} G_3 &\longleftarrow \text{Kers}_2 \rtimes \text{Kers}_1 \rtimes G_1 \\ c &\longmapsto (c\#_2 i_2 s_2(c^{-1}), s_2(c)\#_1 i_1 s_1(s_2(c)^{-1}), s_1 s_2(c)) \\ c\#_2 i_2(b)\#_2 i_2 i_1(a) &\longleftarrow (c, b, a), \end{aligned}$$

for each $c \in G_3$,

$$c \mapsto (c\#_2 i_2 s_2(c^{-1}), s_2(c)\#_1 i_1 s_1(s_2(c)^{-1}), s_1 s_2(c)) \mapsto c\#_2 i_2 s_2(c^{-1})\#_2 i_2(s_2(c)\#_1 i_1 s_1(s_2(c)^{-1}))\#_2 i_2 i_1(s_1 s_2(c)) = c,$$

and for $c \in \text{Kers}_2$, $b \in \text{Kers}_1$, and $a \in G_1$,

$$\begin{aligned} (c, b, a) &\mapsto c\#_2 i_2(b)\#_2 i_2 i_1(a) \mapsto (c\#_2 i_2(b)\#_2 i_2 i_1(a)\#_2 i_2 s_2(c\#_2 i_2(b)\#_2 i_2 i_1(a)))^{-1}, s_2(c\#_2 i_2(b)\#_2 i_2 i_1(a)) \\ &\#_1 i_1 s_1(s_2(c\#_2 i_2(b)\#_2 i_2 i_1(a)))^{-1}, s_1 s_2(c\#_2 i_2(b)\#_2 i_2 i_1(a)) = (c\#_2 i_2(b)\#_2 i_2 i_1(a)\#_2 i_2 i_1(a)^{-1}\#_2 i_2(b)^{-1} \\ &\#_2 i_2 s_2(c)^{-1}, s_2(c)\#_1 i_1 s_1(b)\#_1 i_1(a)\#_1 i_1 s_1 s_2 i_2 i_1(a)^{-1}\#_1 i_1 s_1 s_2 i_2(b)^{-1}\#_1 i_1 s_1 s_2(c)^{-1}, s_1 s_2(c) \\ &\#_0 s_1 s_2 i_2(b)\#_0 s_1 s_2 i_2 i_1(a)) = (c, b, a). \end{aligned}$$

Consequently, $G_3 \cong \text{Kers}_2 \rtimes \text{Kers}_1 \rtimes G_1$. Therefore, $L = \text{Kers}_2 \subseteq G_3$, $E = \text{Kers}_1 \subseteq G_2$, $G = G_1$, and target transformations have the following restrictions:

$$\mathcal{G}_2(\mathfrak{G}) = \left(\text{Kers}_2 \xrightarrow{\bar{i}_2} \text{Kers}_1 \xrightarrow{\bar{i}_1} G_1 \right).$$

$\mathcal{G}_2(\mathfrak{G})$ is a semi-exact sequence of G -groups. $(\text{Kers}_1 \xrightarrow{\bar{i}_1} G_1)$ is a pre-crossed module of groups with left group action. In more detail, the axiom $\mathcal{XMOD}$ -1 in Definition 3.1 is satisfied:

$$\bar{i}_1(a b) = \bar{i}_1(i_1(a)\#_0 b\#_0 i_1(a)^{-1}) = \bar{i}_1 i_1(a)\#_0 \bar{i}_1(b)\#_0 \bar{i}_1 i_1(a)^{-1} = a\#_0 \bar{i}_1(b)\#_0 a^{-1},$$

for each $a \in G_1$ and $b \in \text{Kers}_1$. Note that the reflexivity feature ($\bar{i}_1 i_1 = Id$) is used in the above steps. Similarly, $(\text{Kers}_2 \xrightarrow{\bar{i}_2} \text{Kers}_1)$ is a crossed module of groups with left group action. Because the interchange law is satisfied between the $\#_2$ and $\#_1$ compositions of the sestertius category $\mathfrak{G}$, the $\mathcal{XMOD}$ -2 axiom in Definition 3.1 is satisfied. Refer also [6].

There is also the Pfeifer lifting map $\{-, -\}_*$, defined as follows:

$$\begin{aligned} \{-, -\}_* &: \text{Kers}_1 \times \text{Kers}_1 \longrightarrow \text{Kers}_2 \\ (b_1, b_2) &\longmapsto \{b_1, b_2\}_* = i_2(b_1\#_0 b_2\#_0 b_1^{-1}\#_1 \bar{i}_1(b_1)b_2^{-1}). \end{aligned}$$

Additionally, for each $a \in G_1$, $b_1, b_2 \in \text{Kers}_1$;

$$\begin{aligned} {}^a\{b_1, b_2\}_* &= {}^a i_2(b_1\#_0 b_2\#_0 b_1^{-1}\#_1 \bar{i}_1(b_1)b_2^{-1}) \\ &= {}^a i_2(b_1)\#_0 {}^a i_2(b_2)\#_0 {}^a i_2(b_1)^{-1}\#_1 {}^a i_2(\bar{i}_1(b_1)b_2^{-1}) \\ &= i_2 i_1(a)\#_0 i_2(b_1)\#_0 i_2 i_1(a)^{-1}\#_1 i_2 i_1(a)\#_0 i_2(b_2)\#_0 i_2 i_1(a)^{-1} \\ &\quad \#_0 i_2 i_1(a)\#_0 i_2(b_1^{-1})\#_0 i_2 i_1(a)^{-1}\#_1 i_2 i_1(a)\#_0 i_2 i_1 \bar{i}_1(b_1)\#_0 i_2(b_2^{-1})\#_0 i_2 i_1 \bar{i}_1(b_1)^{-1}\#_0 i_2 i_1(a)^{-1} \\ &= i_2(i_1(a)\#_0 b_1\#_0 i_1(a)^{-1}\#_0 i_1(a)\#_0 b_2\#_0 i_1(a)^{-1}\#_0 i_1(a)\#_0 b_1^{-1} \\ &\quad \#_0 i_1(a)^{-1}\#_1 i_1(a)\#_0 i_1 \bar{i}_1(b_1)\#_0 b_2^{-1}\#_0 i_1 \bar{i}_1(b_1)^{-1}\#_0 i_1(a)^{-1}) \\ &= i_2({}^a b_1\#_0 {}^a b_2\#_0 {}^a b_1^{-1}\#_1 {}^{a\#_0 \bar{i}_1(b_1)} b_2^{-1}) \\ &= i_2({}^a b_1\#_0 {}^a b_2\#_0 {}^a b_1^{-1}\#_1 {}^{a\#_0 \bar{i}_1(b_1)\#_0 a^{-1}} ({}^a b_2^{-1})) \\ &= i_2({}^a b_1\#_0 {}^a b_2\#_0 {}^a b_1^{-1}\#_1 \bar{i}_1({}^a b_1)({}^a b_2^{-1})) \\ &= \{{}^a b_1, {}^a b_2\}_*. \end{aligned}$$

Moreover, there exist the left action equality ${}^a(b, a)_c = {}^b(i_1(a)_c)$ and

$$\begin{aligned}
 {}^a(b)_c &= {}^a(i_2(b) \#_0 c \#_0 i_2(b)^{-1}) \\
 &= {}^a i_2(b) \#_0 {}^a c \#_0 {}^a i_2(b)^{-1} \\
 &= i_2 i_1(a) \#_0 i_2(b) \#_0 i_2 i_1(a)^{-1} \#_0 {}^a c \#_0 i_2 i_1(a) \#_0 i_2(b)^{-1} \#_0 i_2 i_1(a)^{-1} \\
 &= i_2(i_1(a) \#_0 b \#_0 i_1(a)^{-1}) \#_0 {}^a c \#_0 i_2(i_1(a) \#_0 b^{-1} \#_0 i_1(a)^{-1}) \\
 &= i_2({}^a b) \#_0 {}^a c \#_0 i_2({}^a b)^{-1} \\
 &= {}^a b({}^a c),
 \end{aligned}$$

for each $a \in G_1$, $b \in \text{Ker}s_1$, and $c \in \text{Ker}s_2$. These definitions satisfy the axioms given in Definition 3.4. Now we will only satisfy axioms 2XMOD-1 and 2XMOD-2. We leave the remaining axioms to the readers. It is pretty fun to prove.

2XMOD-1 for each $c \in \text{Ker}s_2$, $\bar{t}_1 \bar{t}_2(c) = \bar{t}_1 s_2(c) = 1$, ($\bar{\cdot}$: the globularity),

2XMOD-2 we have

$$\begin{aligned}
 \bar{t}_2(\{b_1, b_2\}_*) &= \bar{t}_2 i_2(b_1 \#_0 b_2 \#_0 b_1^{-1} \#_1 \bar{t}_1(b_1) b_2^{-1}) \\
 &= \bar{t}_2(i_2(b_1) \#_0 i_2(b_2) \#_0 i_2(b_1^{-1}) \#_1 i_2(\bar{t}_1(b_1) b_2^{-1})) \\
 &= (\bar{t}_2 i_2)(b_1) \#_0 (\bar{t}_2 i_2)(b_2) \#_0 (\bar{t}_2 i_2)(b_1^{-1}) \#_1 (\bar{t}_2 i_2)(\bar{t}_1(b_1) b_2^{-1}) \\
 &= b_1 \#_0 b_2 \#_0 b_1^{-1} \#_1 \bar{t}_1(b_1) b_2^{-1}
 \end{aligned}$$

for each $b_1, b_2 \in \text{Ker}s_1$, ($\bar{\cdot}$: the reflexivity $t_n i_n = Id_n$).

Along with these definitions and constructions, the following theorem is given.

Theorem 3.9. *A 2-crossed module of groups is a globular, reflexive, and strict sestertius groupoid with one object (sestertius group).*

Now, we will obtain a tricategory in light of these knowledges.

3.2.4 From 2-crossed modules of groups to tricategories

In this section, we will construct tricategory from a 2-crossed module. Let $\mathcal{G}_2 = (L \xrightarrow{\delta} E \xrightarrow{\partial} G, \{--\})$ be a 2-crossed module of groups. We construct the $\mathfrak{T}(\mathcal{G}_2)$ tricategory as follows:

DATA:

- (1) $Ob \mathfrak{T}(\mathcal{G}_2) = \{\bullet\}$
- (2) For $\bullet \in Ob \mathfrak{T}(\mathcal{G}_2)$. $\mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet)$ is a bicategory as follows:

$$\mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) = \left(\begin{array}{ccc} & g & \\ \nearrow & & \searrow \\ \bullet & (e, g) & \bullet \\ \nwarrow & & \nearrow \\ & \partial(e)g & \end{array} \right)$$

$\begin{array}{ccc} & \text{---} & \\ & \text{---} & \\ & \text{---} & \\ & \text{---} & \\ & \text{---} & \end{array}$

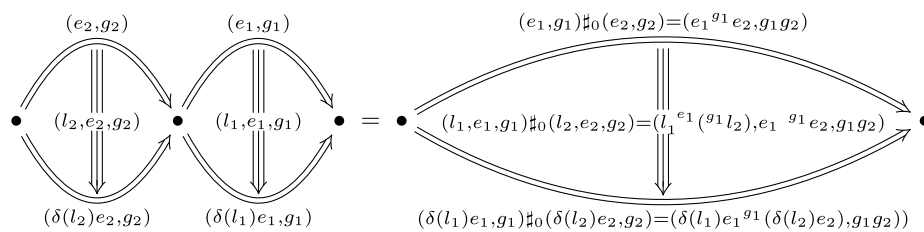
- **Objects:** Every 1-cell, $g : \bullet \rightarrow \bullet \in G$, is an object.
- **1-Morphisms:** Every 2-cell, $(e, g) : g \Rightarrow \partial(e)g \in E \rtimes G$, is a 1-morphism.
- **2-Morphisms:** Every 3-cell, $(l, e, g) : (e, g) \Rightarrow (\delta(l)e, g) \in L \rtimes E \rtimes G$, is a 2-morphism.

The vertical composition of $\mathfrak{T}(\mathcal{G}_2)$ category is $\#_2$, and the horizontal composition is $\#_1$. Note that $\mathfrak{T}(\mathcal{G}_2)$ is a strict 2-category (see in Remark 2.3).

(3) The functor

$$\begin{aligned} \otimes : \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) &\longrightarrow \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \\ ((l_1, e_1, g_1), (l_2, e_2, g_2)) &\longmapsto (l_1, e_1, g_1) \otimes (l_2, e_2, g_2) = (l_1, e_1, g_1) \#_0 (l_2, e_2, g_2) \\ &= (l_1^{e_1(g_1 l_2)}, e_1^{g_1} e_2, g_1 g_2) \end{aligned}$$

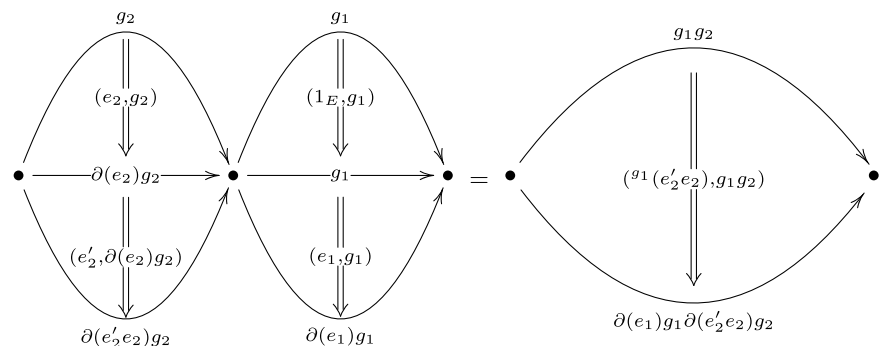
is called composition:



For composable 2-morphisms of $\mathfrak{T}(\mathcal{G}_2)$, the functor $\otimes$ is cubical [17, page 38, Definition 3.1]. Therefore, we have either

$$\begin{aligned} &((e_1, g_1) \#_0 (e'_2, \partial(e_2)g_2)) \#_1 ((1_E, g_1) \#_0 (e_2, g_2)) \\ &= (e_1^{g_1} e'_2, g_1 \partial(e_2)g_2) \#_1 (e_1^{g_1} e_2, g_1 g_2) \\ &= (e_1^{g_1} e'_2 e_2, g_1 g_2) \\ &= (e_1^{g_1} (e'_2 e_2), g_1 g_2) \\ &= (e_1, g_1) \#_0 (e'_2 e_2, g_2) \\ &= ((e_1, g_1) \#_1 (1_E, g_1)) \#_0 ((e'_2, \partial(e_2)g_2) \#_1 (e_2, g_2)), \end{aligned}$$

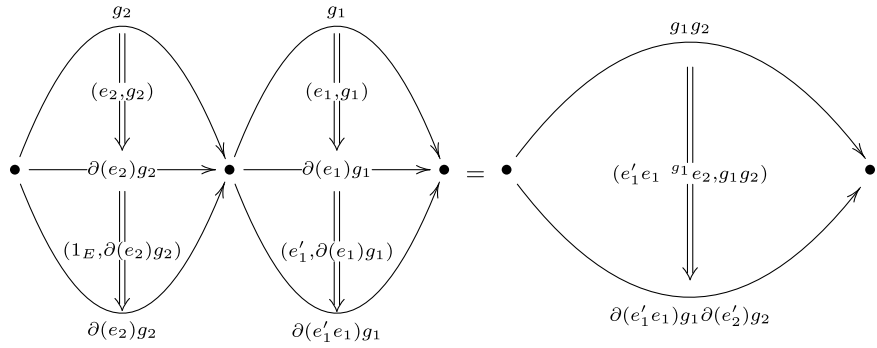
diagrammatically,



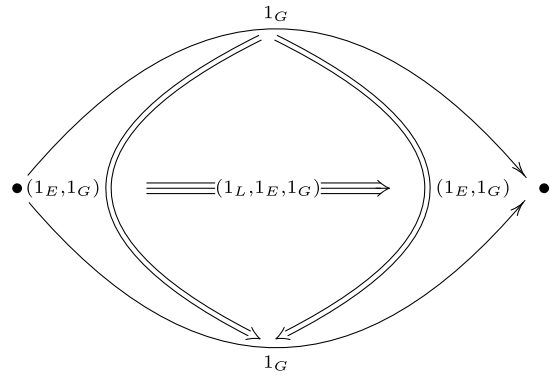
or

$$\begin{aligned} &((e'_1, \partial(e_1)g_1) \#_0 (1_E, \partial(e_2)g_2)) \#_1 ((e_1, g_1) \#_0 (e_2, g_2)) \\ &= (e'_1, \partial(e_1)g_1 \partial(e_2)g_2) \#_1 (e_1^{g_1} e_2, g_1 g_2) \\ &= (e'_1 e_1^{g_1} e_2, g_1 g_2) \\ &= (e'_1 e_1, g_1) \#_0 (e_2, g_2) \\ &= ((e'_1, \partial(e_1)g_1) \#_1 (e_1, g_1)) \#_0 ((1_E, \partial(e_2)g_2) \#_1 (e_2, g_2)), \end{aligned}$$

diagrammatically,

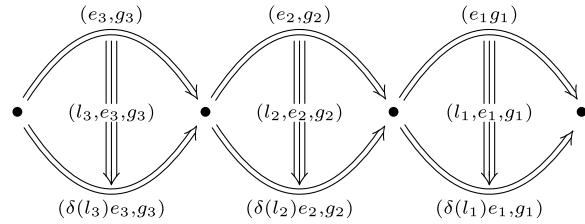


(4) The functor $I : \mathbf{1} \longrightarrow \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet)$, where $\mathbf{1}$ denotes the unit bicategory:



I is also cubical.

(5) For object $\bullet$ of $Ob\mathfrak{T}(\mathcal{G}_2)$ as follows:



an adjoint equivalence α ;

$$\alpha : (l_1, e_1, g_1) \otimes ((l_2, e_2, g_2) \otimes (l_3, e_3, g_3)) \rightarrow ((l_1, e_1, g_1) \otimes (l_2, e_2, g_2)) \otimes (l_3, e_3, g_3).$$

Since every $\mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet)$ is a strict 2-category, we have

$$(l_1, e_1, g_1) \otimes ((l_2, e_2, g_2) \otimes (l_3, e_3, g_3)) = ((l_1, e_1, g_1) \otimes (l_2, e_2, g_2)) \otimes (l_3, e_3, g_3).$$

Note that $\otimes$ is associative

$$\begin{array}{ccc} \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) & \xrightarrow{\otimes \times 1} & \mathfrak{T}(\mathcal{G}_2)(x, z) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \\ \downarrow 1 \times \otimes & \Downarrow \alpha & \downarrow \otimes \\ \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) & \xrightarrow{\otimes} & \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet); \end{array}$$

$$\begin{array}{ccc}
 (l_1, e_1, g_1) \#_0 ((l_2, e_2, g_2) \#_0 (l_3, e_3, g_3)) & \xrightarrow{\otimes \times 1} & (l_1 \ e_1 (g_1 l_2), e_1 \ g_1 e_2, g_1 g_2) \#_0 (l_3, e_3, g_3) \\
 \downarrow 1 \times \otimes & \Downarrow \alpha & \downarrow \otimes \\
 (l_1, e_1, g_1) \#_0 (l_2 \ e_2 (g_2 l_3), e_2 \ g_2 e_3, g_2 g_3) & \xrightarrow[\otimes]{} & (l_1 \ e_1 (g_1 l_2) \ e_1 \ g_1 e_2 (g_1 g_2 l_3), e_1 \ g_1 e_2 \ g_1 g_2 e_3, g_1 g_2 g_3);
 \end{array}$$

in $\mathbf{Bicat}(\mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet), \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet))$.

(6) For each $g \in G$, $e \in E$, and $l \in L$, adjoint equivalences $\mathfrak{l}$ and $\mathfrak{r}$

$$\begin{array}{ccc}
 & \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) & \\
 I_\bullet \times 1 \nearrow & \Downarrow \mathfrak{l} & \searrow \otimes \\
 \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) & \xrightarrow{1} & \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet);
 \end{array}$$

$$\begin{array}{ccc}
 & (1_L, 1_E, 1_G) \otimes (l, e, g) & \\
 I_\bullet \times 1 \nearrow & \Downarrow \mathfrak{l} & \searrow \otimes \\
 (l, e, g) & \xrightarrow{1} & (l, e, g),
 \end{array}$$

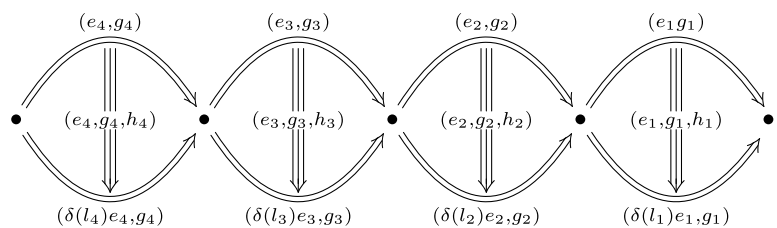
and

$$\begin{array}{ccc}
 & \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) & \\
 1 \times I_\bullet \nearrow & \Downarrow \mathfrak{r} & \searrow \otimes \\
 \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) & \xrightarrow{1} & \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet);
 \end{array}$$

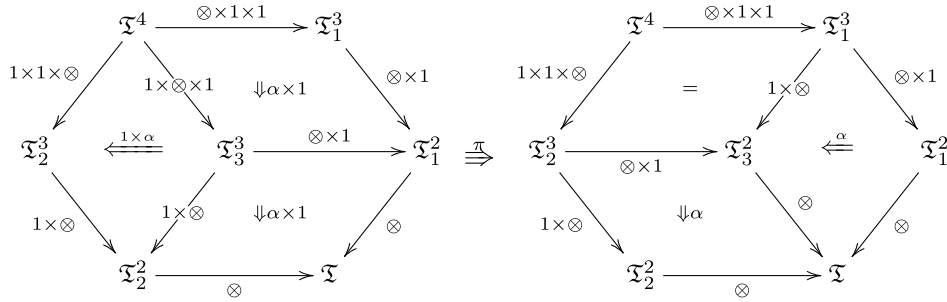
$$\begin{array}{ccc}
 & (l, e, g) \otimes (1_L, 1_E, 1_G) & \\
 1 \times I_\bullet \nearrow & \Downarrow \mathfrak{r} & \searrow \otimes \\
 (l, e, g) & \xrightarrow{1} & (l, e, g).
 \end{array}$$

in $\mathbf{BiCat}(\mathfrak{T}(\mathcal{G})(\bullet, \bullet), \mathfrak{T}(\mathcal{G})(\bullet, \bullet))$.

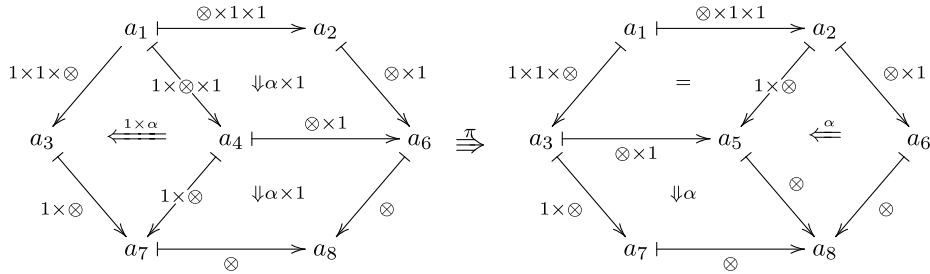
(7) For $\bullet \in \text{Ob} \mathfrak{T}(\mathcal{G})$ as follows:



and a 2-cell isomorphism π (Instead of $\mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet)$, we use $\mathfrak{T}^4(\mathcal{G}_2)$ as its abbreviation):

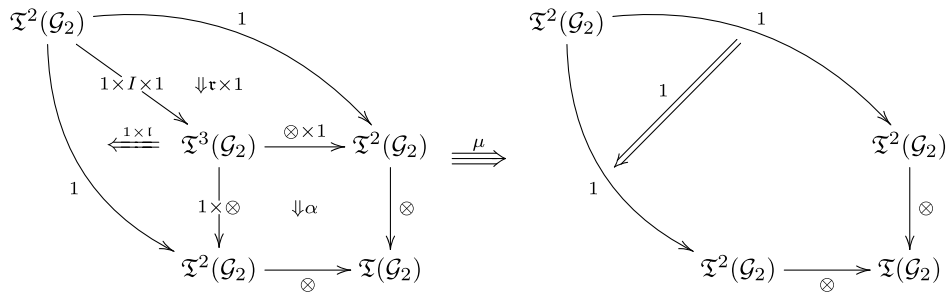


$$\begin{aligned}
 a_1 &= (l_1, e_1, g_1) \otimes (l_2, e_2, g_2) \otimes (l_3, e_3, g_3) \otimes (l_4, e_4, g_4) \\
 a_2 &= (l_1^{e_1}(g_1 l_2), e_1^{g_1} e_2, g_1 g_2) \otimes (l_3, e_3, g_3) \otimes (l_4, e_4, g_4) \\
 a_3 &= (l_1, e_1, g_1) \otimes (l_2, e_2, g_2) \otimes (l_3^{e_3}(g_3 l_4), e_3^{g_3} e_4, g_3 g_4) \\
 a_4 &= (l_1, e_1, g_1) \otimes (l_2^{e_2}(g_2 l_3), e_2^{g_2} e_3, g_2 g_3) \otimes (l_4, e_4, g_4) \\
 a_5 &= (l_1^{e_1}(g_1 l_2), e_1^{g_1} e_2, g_1 g_2) \otimes (l_3^{e_3}(g_3 l_4), e_3^{g_3} e_4, g_3 g_4) \\
 a_6 &= (l_1^{e_1}(g_1 l_2)^{e_1 g_1 e_2}(g_1 g_2 l_3), e_1^{g_1} e_2^{(g_1 g_2)} e_3, g_1 g_2 g_3) \otimes (l_4, e_4, g_4) \\
 a_7 &= (l_1, e_1, g_1) \otimes (l_2^{e_2}(g_2 l_3) e_2^{g_2} e_3(g_3 l_4), e_2^{g_2} e_3^{(g_2 g_3)} e_4, g_2 g_3 g_4) \\
 a_8 &= (l_1^{e_1}(g_1 l_2)^{e_1 g_1 e_2}(g_1 g_2 l_3)^{e_1 g_1 e_2 g_1 g_2 g_3}(g_1 g_2 g_3 l_4), e_1^{g_1} e_2^{(g_1 g_2)} g_3^{(g_1 g_2 g_3)} e_4, g_1 g_2 g_3 g_4) \\
 &= (l_1^{e_1}(g_1(l_2^{e_2}(g_2 l_3)^{e_2 g_2 e_3}(g_3 l_4))), e_1^{g_1}(e_2^{g_2} e_3^{(g_2 g_3)} e_4), g_1 g_2 g_3 g_4).
 \end{aligned}$$



in the bicategory $\mathbf{Bicat}(\mathfrak{T}^4(\mathcal{G}_2), \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet))$

(8) For invertible modifications,



$$a_1 = (l_1, e_1, g_1) \otimes (l_2, e_2, g_2), \quad a_2 = (l_1, e_1, g_1) \otimes (1_L, 1_E, 1_G) \otimes (l_2, e_2, g_2), \quad a_3 = (l_1^{e_1}(g_1 l_2), e_1^{g_1} e_2, g_1 g_2);$$

$$\begin{array}{ccc}
 \begin{array}{c}
 a_1 \xrightarrow{1} a_1 \\
 \downarrow 1 \times I \times 1 \Downarrow \tau \times 1 \\
 a_2 \xrightarrow{1 \times I} a_1 \\
 \downarrow 1 \times \otimes \quad \downarrow \alpha \\
 a_1 \xrightarrow{1 \times \otimes} a_3
 \end{array}
 & \xRightarrow{\mu} &
 \begin{array}{c}
 a_1 \xrightarrow{1} a_1 \\
 \downarrow 1 \\
 a_1 \xrightarrow{1} a_3
 \end{array}
 \end{array}$$

$$\begin{array}{ccc}
 \begin{array}{ccc}
 \mathfrak{T}^2(\mathcal{G}_2) & \xrightarrow{I \times 1 \times 1} & \mathfrak{T}^3(\mathcal{G}_2) \\
 \downarrow \otimes & & \downarrow \otimes \\
 \mathfrak{T}(\mathcal{G}_2) & \xrightarrow{1} & \mathfrak{T}(\mathcal{G}_2)
 \end{array}
 & \xRightarrow{\lambda} &
 \begin{array}{ccc}
 \mathfrak{T}^2(\mathcal{G}_2) & \xrightarrow{I \times 1 \times 1} & \mathfrak{T}^3(\mathcal{G}_2) \\
 \downarrow \otimes & & \downarrow \otimes \\
 \mathfrak{T}(\mathcal{G}_2) & \xrightarrow{1} & \mathfrak{T}(\mathcal{G}_2)
 \end{array}
 \end{array}$$

$$\begin{array}{ccc}
 (l_1, e_1, g_1) \otimes (l_2, e_2, g_2) & \xrightarrow{I \times 1 \times 1} & (1_L, 1_E, 1_G) \otimes (l_1, e_1, g_1) \otimes (l_2, e_2, g_2) \\
 \downarrow \otimes & & \downarrow \otimes \\
 (l_1 \cdot e_1(g_1 l_2), e_1 \cdot g_1 e_2, g_1 g_2) & \xrightarrow{1} & (l_1 \cdot e_1(g_1 l_2), e_1 \cdot g_1 e_2, g_1 g_2)
 \end{array}$$

$$\Downarrow \lambda$$

$$\begin{array}{ccc}
 (l_1, e_1, g_1) \otimes (l_2, e_2, g_2) & \xrightarrow{I \times 1 \times 1} & (1_L, 1_E, 1_G) \otimes (l_1, e_1, g_1) \otimes (l_2, e_2, g_2) \\
 \downarrow \otimes & & \downarrow \otimes \\
 (l_1 \cdot e_1(g_1 l_2), e_1 \cdot g_1 e_2, g_1 g_2) & \xrightarrow{1} & (l_1 \cdot e_1(g_1 l_2), e_1 \cdot g_1 e_2, g_1 g_2)
 \end{array}$$

$$\begin{array}{ccc}
\begin{array}{ccc}
\mathfrak{T}(\mathcal{G}_2) & \xrightarrow{1} & \mathfrak{T}(\mathcal{G}_2) \\
\uparrow \otimes & & \uparrow \otimes \\
\mathfrak{T}^2(\mathcal{G}_2) & \xrightarrow{1} & \mathfrak{T}^2(\mathcal{G}_2) \\
\searrow 1 \times 1 \times I & \Downarrow 1 \times r & \nearrow 1 \times \otimes \\
& \mathfrak{T}^3(\mathcal{G}_2) &
\end{array} & \xRightarrow{\rho} &
\begin{array}{ccc}
\mathfrak{T}(\mathcal{G}_2) & \xrightarrow{1} & \mathfrak{T}(\mathcal{G}_2) \\
\uparrow \otimes & \searrow 1 \times I & \nearrow r \\
& \mathfrak{T}^2(\mathcal{G}_2) & \\
\uparrow \otimes & & \uparrow \otimes \\
\mathfrak{T}^2(\mathcal{G}_2) & \xrightarrow{1} & \mathfrak{T}^2(\mathcal{G}_2) \\
\searrow 1 \times 1 \times I & \Downarrow \otimes \times 1 & \nearrow 1 \times \otimes \\
& \mathfrak{T}^3(\mathcal{G}_2) &
\end{array}
\end{array}$$

$$\begin{array}{ccc}
(l_1 \ e_1(g_1 l_2), e_1 \ g_1 e_2, g_1 g_2) & \xrightarrow{1} & (l_1 \ e_1(g_1 l_2), e_1 \ g_1 e_2, g_1 g_2) \\
\uparrow \otimes & & \uparrow \otimes \\
(l_1, e_1, g_1) \otimes (l_2, e_2, g_2) & \xrightarrow{1} & (l_1, e_1, g_1) \otimes (l_2, e_2, g_2) \\
\searrow 1 \times 1 \times I & \Downarrow 1 \times r & \nearrow 1 \times \otimes \\
& (l_1, e_1, g_1) \otimes (l_2, e_2, g_2) \otimes (1_L, 1_E, 1_G) &
\end{array}$$

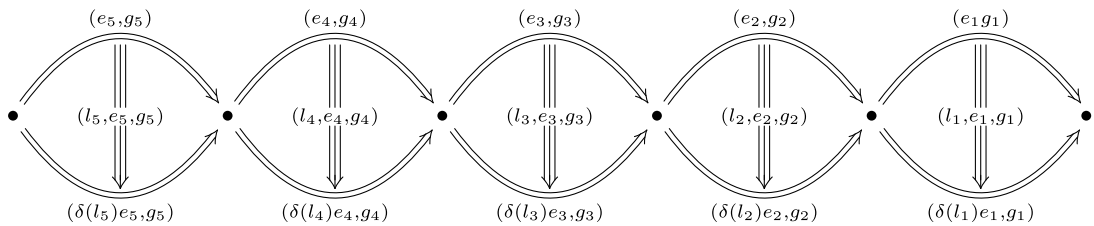
$$\Downarrow \rho$$

$$\begin{array}{ccc}
(l_1 \ e_1(g_1 l_2), e_1 \ g_1 e_2, g_1 g_2) & \xrightarrow{1} & (l_1 \ e_1(g_1 l_2), e_1 \ g_1 e_2, g_1 g_2) \\
\uparrow \otimes & \searrow 1 \times l & \nearrow r \\
& (l_1 \ e_1(g_1 l_2), e_1 \ g_1 e_2, g_1 g_2) \otimes (1_L, 1_E, 1_G) & \\
\uparrow \otimes & & \uparrow \otimes \\
(l_1, e_1, g_1) \otimes (l_2, e_2, g_2) & \xrightarrow{1} & (l_1, e_1, g_1) \otimes (l_2, e_2, g_2) \\
\searrow 1 \times 1 \times I & \Downarrow \otimes \times 1 & \nearrow 1 \times \otimes \\
& (l_1, e_1, g_1) \otimes (l_2, e_2, g_2) \otimes (1_L, 1_E, 1_G) &
\end{array}$$

Note that the tricategory $\mathfrak{T}(\mathcal{G}_2)$ we have defined provides Remark 2.3; that is why it is strict.

AXIOMS:

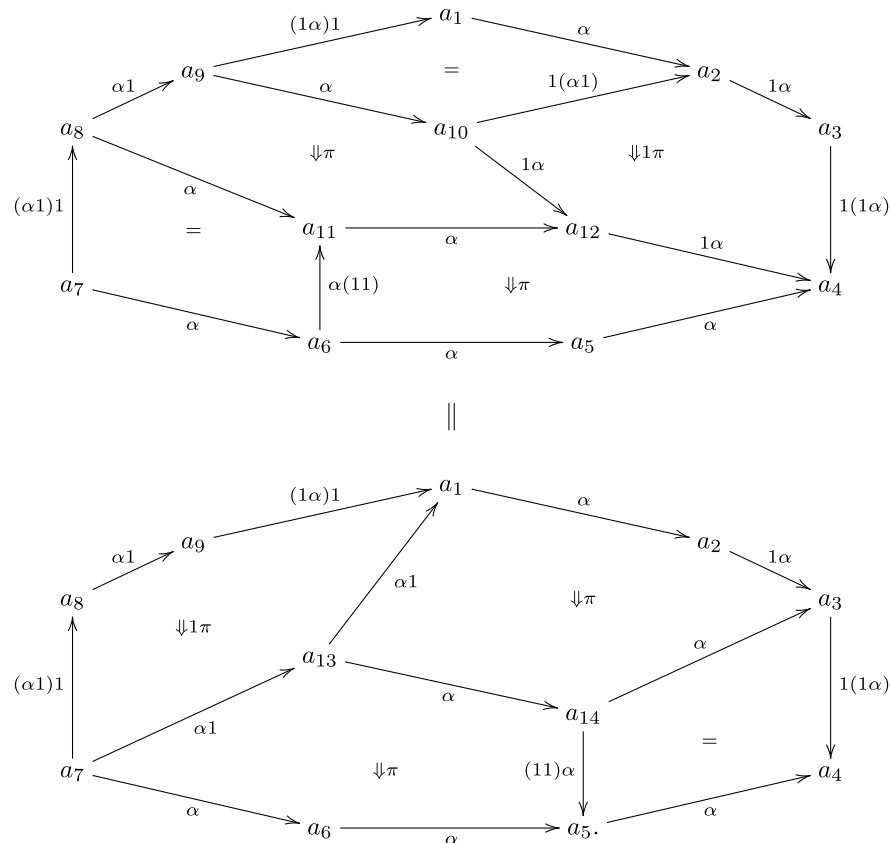
(1) [Non-abelian 4-cocycle condition] For any strict 2-category $\mathfrak{T}(\mathcal{G}_2)(-, -)$, the following 2-cells equation diagram preserves the natural isomorphism of α . We have 2-cells elements as follows:



We will use the following elements as abbreviations for the objects of $\mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet)$;

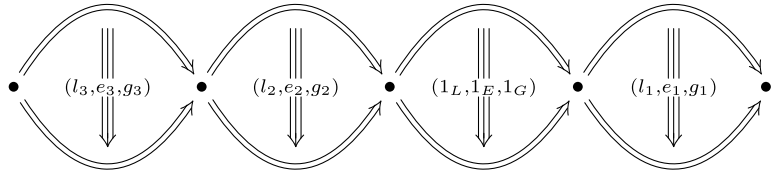
$$\begin{aligned}
 a_1 &= ((l_1, e_1, g_1) \otimes ((l_2, e_2, g_2) \otimes (l_3^{e_3}(g_3 l_4), e_3^{g_3} e_4, g_3 g_4))) \otimes (l_5, e_5, g_5) \\
 a_2 &= (l_1, e_1, g_1) \otimes (((l_2, e_2, g_2) \otimes (l_3^{e_3}(g_3 l_4), e_3^{g_3} e_4, g_3 g_4)) \otimes (l_5, e_5, g_5)) \\
 a_3 &= (l_1, e_1, g_1) \otimes ((l_2, e_2, g_2) \otimes ((l_3^{e_3}(g_3 l_4), e_3^{g_3} e_4, g_3 g_4) \otimes (l_5, e_5, g_5))) \\
 a_4 &= (l_1, e_1, g_1) \otimes ((l_2, e_2, g_2) \otimes ((l_3, e_3, g_3) \otimes (l_4^{e_4}(g_4 l_5), e_4^{g_4} e_5, g_4 g_5))) \\
 a_5 &= (l_1^{e_1}(g_1 l_2), e_1^{g_1} e_2, g_1 g_2) \otimes (l_3, e_3, g_3) \otimes (l_4^{e_4}(g_4 l_5), e_4^{g_4} e_5, g_4 g_5) \\
 a_6 &= ((l_1^{e_1}(g_1 l_2), e_1^{g_1} e_2, g_1 g_2) \otimes (l_3, e_3, g_3)) \otimes (l_4^{e_4}(g_4 l_5), e_4^{g_4} e_5, g_4 g_5) \\
 a_7 &= (((l_1^{e_1}(g_1 l_2), e_1^{g_1} e_2, g_1 g_2) \otimes (l_3, e_3, g_3)) \otimes (l_4, e_4, g_4)) \otimes (l_5, e_5, g_5) \\
 a_8 &= (((l_1, e_1, g_1) \otimes (l_2^{e_2}(g_2 l_3), e_2^{g_2} e_3, g_2 g_3)) \otimes (l_4, e_4, g_4)) \otimes (l_5, e_5, g_5) \\
 a_9 &= ((l_1, e_1, g_1) \otimes ((l_2^{e_2}(g_2 l_3), e_2^{g_2} e_3, g_2 g_3) \otimes (l_4, e_4, g_4))) \otimes (l_5, e_5, g_5) \\
 a_{10} &= (l_1, e_1, g_1) \otimes (((l_2^{e_2}(g_2 l_3), e_2^{g_2} e_3, g_2 g_3) \otimes (l_4, e_4, g_4))(l_5, e_5, g_5)) \\
 a_{11} &= ((l_1, e_1, g_1) \otimes (l_2^{e_2}(g_2 l_3), e_2^{g_2} e_3, g_2 g_3)) \otimes (l_4^{e_4}(g_4 l_5), e_4^{g_4} e_5, g_4 g_5) \\
 a_{12} &= (l_1, e_1, g_1) \otimes ((l_2^{e_2}(g_2 l_3), e_2^{g_2} e_3, g_2 g_3) \otimes (l_4^{e_4}(g_4 l_5), e_4^{g_4} e_5, g_4 g_5)) \\
 a_{13} &= ((l_1^{e_1}(g_1 l_2), e_1^{g_1} e_2, g_1 g_2) \otimes (l_3^{e_3}(g_3 l_4), e_3^{g_3} e_4, g_3 g_4)) \otimes (l_5, e_5, g_5) \\
 a_{14} &= (l_1^{e_1}(g_1 l_2), e_1^{g_1} e_2, g_1 g_2) \otimes ((l_3^{e_3}(g_3 l_4), e_3^{g_3} e_4, g_3 g_4) \otimes (l_5, e_5, g_5)).
 \end{aligned}$$

Thus, we have the following commutative diagrams:



(2) [Left normalization] The following equation of 2-cells in any strict 2-category $\mathfrak{T}(\mathcal{G}_2)(-, -)$, where the unmarked isomorphisms are either naturality isomorphisms for α or unique coherence isomorphisms

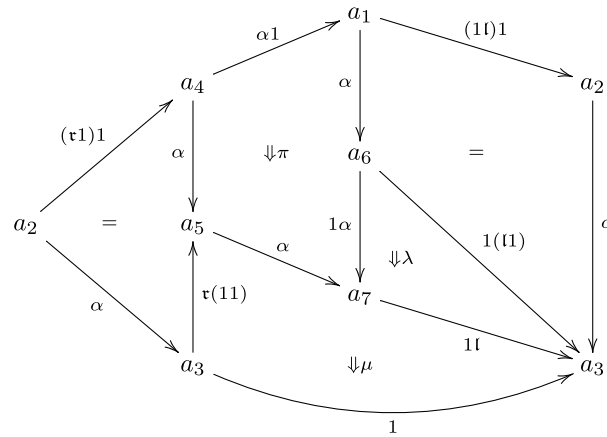
from the hom-strict 2-category. The 2-cell elements are as follows:



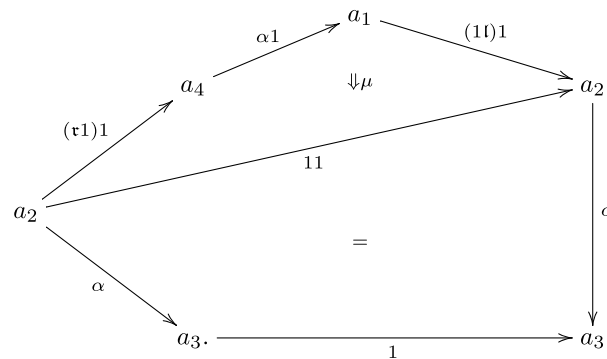
We will use the following elements as abbreviations for the objects of $\mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet)$:

$$\begin{aligned}
 a_1 &= ((l_1, e_1, g_1) \otimes ((1_L, 1_E, 1_G) \otimes (l_2, e_2, g_2))) \otimes (l_3, e_3, g_3) \\
 &= ((l_1, e_1, g_1) \otimes (l_2, e_2, g_2)) \otimes (l_3, e_3, g_3) \\
 a_2 &= (l_1^{e_1}(g_1 l_2), e_1^{g_1} e_2, g_1 g_2) \otimes (l_3, e_3, g_3) \\
 a_3 &= (l_1, e_1, g_1) \otimes (l_2^{e_2}(g_2 l_3), e_2^{g_2} e_3, g_2 g_3) \\
 a_4 &= ((l_1, e_1, g_1) \otimes ((1_L, 1_E, 1_G) \otimes (l_2, e_2, g_2))) \otimes (l_3, e_3, g_3) \\
 &= ((l_1, e_1, g_1) \otimes (l_2, e_2, g_2)) \otimes (l_3, e_3, g_3) \\
 a_5 &= ((l_1, e_1, g_1) \otimes (1_L, 1_E, 1_G)) \otimes (l_2, e_2, g_2) \otimes (l_3, e_3, g_3) \\
 &= (l_1, e_1, g_1) \otimes (l_2^{e_2}(g_2 l_3), e_2^{g_2} e_3, g_2 g_3) \\
 a_6 &= (l_1, e_1, g_1) \otimes (((1_L, 1_E, 1_G) \otimes (l_2, e_2, g_2)) \otimes (l_3, e_3, g_3)) \\
 &= (l_1, e_1, g_1) \otimes ((l_2, e_2, g_2) \otimes (l_3, e_3, g_3)) \\
 a_7 &= (l_1, e_1, g_1) \otimes ((1_L, 1_E, 1_G) \otimes (l_2^{e_2}(g_2 l_3), e_2^{g_2} e_3, g_2 g_3)).
 \end{aligned}$$

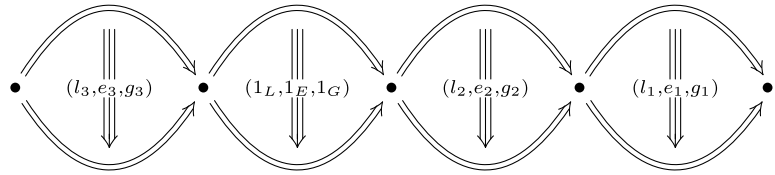
Thus, we have the following commutative diagrams:



||



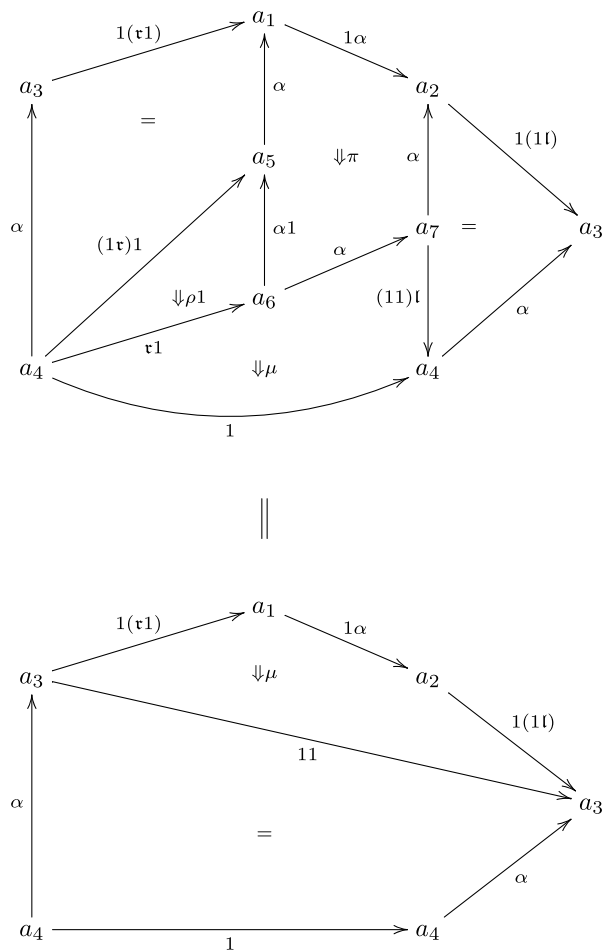
(3) [Right normalization] Similarly, the following equation of 2-cells holds in any strict 2-category $\mathfrak{T}(\mathcal{G}_2)(-, -)$. The 2-cell elements are as follows:



We will use the following elements as abbreviations for the objects of $\mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet)$:

$$\begin{aligned}
 a_1 &= (l_1, e_1, g_1) \otimes (((l_2, e_2, g_2) \otimes (1_L, 1_E, 1_G)) \otimes (l_3, e_3, g_3)) \\
 &= (l_1, e_1, g_1) \otimes ((l_2, e_2, g_2) \otimes (l_3, e_3, g_3)) \\
 a_2 &= (l_1, e_1, g_1) \otimes ((l_2, e_2, g_2) \otimes ((1_L, 1_E, 1_G) \otimes (l_3, e_3, g_3))) \\
 &= (l_1, e_1, g_1) \otimes ((l_2, e_2, g_2) \otimes (l_3, e_3, g_3)) \\
 a_3 &= (l_1, e_1, g_1) \otimes (l_2^{e_2(g_2 l_3)}, e_2^{g_2} e_3, g_2 g_3) \\
 a_4 &= (l_1^{e_1(g_1 l_2)}, e_1^{g_1} e_2, g_1 g_2) \otimes (l_3, e_3, g_3) \\
 a_5 &= ((l_1, e_1, g_1) \otimes ((l_2, e_2, g_2) \otimes (1_L, 1_E, 1_G))) \otimes (l_3, e_3, g_3) \\
 &= ((l_1, e_1, g_1) \otimes (l_2, e_2, g_2)) \otimes (l_3, e_3, g_3) \\
 a_6 &= ((l_1^{e_1(g_1 l_2)}, e_1^{g_1} e_2, g_1 g_2) \otimes (1_L, 1_E, 1_G)) \otimes (e_3, g_3, h_3) \\
 a_7 &= ((l_1, e_1, g_1) \otimes (l_2, e_2, g_2)) \otimes ((1_L, 1_E, 1_G) \otimes (l_3, e_3, g_3)) \\
 &= (l_1^{e_1(g_1 l_2)}, e_1^{g_1} e_2, g_1 g_2) \otimes (l_3, e_3, g_3).
 \end{aligned}$$

Thus, we have the following commutative diagrams:



Note that this structure is a strict cubical tricategory with a single object, as it satisfies Remark 2.3. and Lemma 2.4. We can also obtain reverse construction; we can derive a 2-crossed module from any strict cubical tricategory with a single object (sestertius groupoid with one object). See how to obtain a 2-crossed module of groups from a sestertius category with one object in Section 3.2.

In this way, we can construct the morphism of 2-crossed modules in the form of trihomomorphism. Let f be a 2-crossed module morphism between $\mathcal{G}_2$ and $\mathcal{G}'_2$ as shown below:

$$\begin{array}{ccccc} L & \xrightarrow{\delta} & E & \xrightarrow{\partial} & G \\ f_2 \downarrow & & f_1 \downarrow & & f_0 \downarrow \\ L' & \xrightarrow{\delta'} & E' & \xrightarrow{\partial'} & G' \end{array}$$

Roughly speaking, trihomomorphism consists of the following data and provides the axioms in Definition 2.5:

$$\begin{array}{c} \mathfrak{T}(\mathcal{G}_2) \\ \downarrow \mathfrak{F} = (\mathfrak{F}_2, \mathfrak{F}_1, \mathfrak{F}_0, \mathfrak{F}_{Ob}) \\ \mathfrak{T}(\mathcal{G}'_2) \end{array} = \begin{array}{ccccccc} L \rtimes E \rtimes G & \xrightleftharpoons[t_2]{s_2} & E \rtimes G & \xrightleftharpoons[t_1]{s_1} & G & \xrightleftharpoons[t_0]{s_0} & \{\bullet\} \\ \downarrow \mathfrak{F}_2 & \searrow i_2 & \downarrow \mathfrak{F}_1 & \searrow i_1 & \downarrow \mathfrak{F}_0 & \searrow i_0 & \downarrow \mathfrak{F}_{Ob} \\ L' \rtimes E' \rtimes G' & \xrightleftharpoons[t'_2]{s'_2} & E' \rtimes G' & \xrightleftharpoons[t'_1]{s'_1} & G' & \xrightleftharpoons[t'_0]{s'_0} & \{\bullet'\} \end{array}$$

- (1) $\{\bullet\} \xrightarrow{\mathfrak{F}_{Ob}} \mathfrak{F}_{Ob}(\{\bullet\}) = \{\bullet'\},$
- (2) For $\bullet \in Ob\mathfrak{T}(\mathcal{G}_2)$, the following diagram represents

$$\begin{array}{c} \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \xrightarrow{\mathfrak{F}} \mathfrak{T}(\mathcal{G}'_2)(\mathfrak{F}_{Ob}(\bullet), \mathfrak{F}_{Ob}(\bullet)) : \\ \begin{array}{ccc} & g & \\ \bullet & \begin{array}{c} \curvearrowright \\ (e, g) \rightleftarrows (l, e, g) \rightleftarrows (\delta(l)e, g) \\ \curvearrowleft \end{array} & \bullet \\ & \partial(e)g & \\ \mathfrak{F} \downarrow & & \\ f_0(g) & & \end{array} \\ \begin{array}{ccc} \mathfrak{F}_{Ob}(\bullet) = \bullet' & \begin{array}{c} \curvearrowright \\ (f_1(e), f_0(g)) \rightleftarrows (f_2(l), f_1(e), f_0(g)) \rightleftarrows (f_1(\delta(l)e), f_0(g)) \end{array} & \mathfrak{F}_{Ob}(\bullet) = \bullet' \\ & f_0(\partial(e)g) & \end{array} \end{array}$$

For each $g \in G$, $e \in E$, and $l \in L$;

$$\begin{aligned}\mathfrak{F}_0(g) &= f_0(g), \\ \mathfrak{F}_0(\partial(e)g) &= f_0(\partial(e)g), \\ \mathfrak{F}_1((e, g)) &= (f_1(e), f_0(g)), \\ \mathfrak{F}_1((\delta(l)e, g)) &= (f_1(\delta(l)e), f_0(g)), \\ \mathfrak{F}_2((l, e, g)) &= (f_2(l), f_1(e), f_0(g)).\end{aligned}$$

The morphisms $\mathfrak{F}_n$ are compatible with n -source and n -target morphisms for $0 \leq n \leq 2$.

$$\begin{aligned}s'_0(\mathfrak{F}_0(g)) &= t'_0(\mathfrak{F}_0(g)) = s'_0(\mathfrak{F}_0(\partial(e)g)) = t'_0(\mathfrak{F}_0(\partial(e)g)) = \mathfrak{F}_{Ob}(\bullet) = \bullet', \\ s'_1(\mathfrak{F}_1((e, g))) &= s'_1((f_1(e), f_0(g))) = f_0(g), \\ t'_1(\mathfrak{F}_1((e, g))) &= t'_1((f_1(e), f_0(g))) = \partial'(f_1(e))f_0(g) = \partial'f_1(e)f_0(g) = f_0\partial(e)f_0(g), \\ s'_1(\mathfrak{F}_1((\delta(l)e, g))) &= s'_1((f_1(\delta(l)e), f_0(g))) = f_0(g), \\ t'_1(\mathfrak{F}_1((\delta(l)e, g))) &= t'_1((f_1(\delta(l)e), f_0(g))) \\ &= \partial'(f_1(\delta(l)e))f_0(g) \\ &= \partial'(f_1(\delta(l)))\partial'(f_1(e))f_0(g) \\ &= \partial'\delta'(f_2(l))\partial'f_1(e)f_0(g) \\ &= \partial'f_1(e)f_0(g) \\ &= f_0\partial(e)f_0(g),\end{aligned}$$

and

$$\begin{aligned}s'_2(\mathfrak{F}_2((l, e, g))) &= s'_2((f_2(l), f_1(e), f_0(g))) = (f_1(e), f_0(g)), \\ t'_2(\mathfrak{F}_2((l, e, g))) &= t'_2((f_2(l), f_1(e), f_0(g))) \\ &= (\delta'(f_2(l))f_1(e), f_0(g)) \\ &= (f_1\delta(l)f_1(e), f_0(g)) \\ &= (f_1(\delta(l)e), f_0(g)).\end{aligned}$$

(3) For $\bullet \in Ob\mathfrak{T}(\mathcal{G}_2)$, an adjoint equivalence $\xi : \otimes' \circ (\mathfrak{F} \times \mathfrak{F}) \Rightarrow \mathfrak{F} \circ \otimes$ with left adjoint is illustrated in the following diagram:

$$\begin{array}{ccc}\mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) \times \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) & \xrightarrow{\mathfrak{F} \times \mathfrak{F}} & \mathfrak{T}'(\mathcal{G}'_2)(\mathfrak{F}(\bullet), \mathfrak{F}(\bullet)) \\ \downarrow \otimes & \swarrow \xi & \downarrow \otimes' \\ \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) & \xrightarrow{\mathfrak{F}} & \mathfrak{T}'(\mathcal{G}'_2)(\mathfrak{F}(\bullet), \mathfrak{F}(\bullet));\end{array}$$

$$\begin{array}{ccc}(l_1, e_1, g_1) \otimes (l_2, e_2, g_2) & \xrightarrow{\mathfrak{F} \times \mathfrak{F}} & (f_2(l_1), f_1(e_1), f_0(g_1)) \otimes (f_2(l_2), f_1(e_2), f_0(g_2)) \\ \downarrow \otimes & \swarrow \xi & \downarrow \otimes' \\ (l_1 \quad e_1 \quad g_1 l_2), e_1 \quad g_1 e_2, g_1 g_2 & \xrightarrow{\mathfrak{F}} & (f_2(l_1) \quad f_1(e_1) \quad f_0(g_1) f_2(l_2)), f_1(e_1) \quad f_0(g_1) f_1(e_2), f_0(g_1) f_0(g_2),\end{array}$$

(4) For $\bullet \in \text{Ob} \mathfrak{T}(\mathcal{G}_2)$, an adjoint equivalence $\iota : I'_{\mathfrak{T}(\bullet)} \Rightarrow \mathfrak{F} \circ I$ with left adjoint illustrated in the following diagram:

$$\begin{array}{ccc}
 1 & \xrightarrow{I'_{\mathfrak{T}(\bullet)}} & \mathfrak{T}'(\mathcal{G}_2)(\mathfrak{F}_{\text{Ob}}(\bullet), \mathfrak{F}_{\text{Ob}}(\bullet)) \\
 & \searrow I_{\bullet} & \uparrow \mathfrak{F} \\
 & \mathfrak{T}(\mathcal{G}_2)(\bullet, \bullet) &
 \end{array}$$

Since f_n s are group homomorphisms, unit elements are preserved.

Other data (invertible modifications) and axioms in Definition 2.5 are easily provided, because $\otimes$ is associative and I is preserved under $\mathfrak{F}$.

4 Conclusion

In this study, we obtained a strict cubical tricategory with a single object by looking at the 2-crossed module from a higher-dimensional perspective, and we also defined the reverse construction. With this type of definition, non-abelian objects and other algebraic 3-type models can be defined. The important point here is the difference in understanding between the crossed module and the 2-crossed module.

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