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ON TYPICALLY REAL FUNCTIONS
WHICH OMIT TWO CONJUGATED VALUES

Abstract. In this paper we discuss the class $T_{\rho,\theta}$ consisting of typically real functions which do not admit values $w_0 = \rho e^{i\theta}$ and $\overline{w_0}$. We estimate the second and the third coefficients of a function $f \in T_{\rho,\theta}$ and we determine the Koebe domain for the class of typically real functions with fixed second coefficient.

Let T denote the class of analytic functions f in the unit disk $\Delta \equiv \{z \in \mathbb{C} : |z| < 1\}$ and normalized by $f(0) = f'(0) - 1 = 0$ for which the condition

$$\operatorname{Im} z \cdot \operatorname{Im} f(z) \geq 0 \quad \text{for } z \in \Delta$$

is satisfied. The class T is called the class of typically real functions. Rogosinski [5] gave the explicit relation between a function $f \in T$ and a probability measure μ defined on $[-1, 1]$. Namely,

$$f \in T \iff f(z) = \int_{-1}^1 \frac{z}{1 - 2zt + z^2} d\mu(t).$$

In 1977 Goodman [1] defined the universal typically real function

$$(1) \quad G(z) = \frac{1}{\pi} \tan \frac{\pi z}{1 + z^2}$$

and determined the Koebe domain for T .

THEOREM A [1]. *The Koebe domain for the class T is symmetric with respect to the real axis and the boundary of this domain in the upper half plane is given by the polar equation $\rho(\theta)e^{i\theta}$, where*

$$(2) \quad \rho(\theta) = \begin{cases} \frac{\pi \sin \theta}{4\theta(\pi - \theta)}, & \theta \in (0, \pi) \\ \frac{1}{4}, & \theta = 0 \text{ or } \theta = \pi. \end{cases}$$

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In this paper we study a subclass of the class T , consisting of functions, which do not admit values $w_0 = \rho e^{i\theta}$ and $\overline{w_0}$. This class we denote by $T_{\rho,\theta}$. The class $T_{\rho,\theta}$ is defined as follows

$$T_{\rho,\theta} = \{f \in T : f \neq \rho e^{\pm i\theta}\}, \quad 0 \leq \theta \leq \pi, \quad \rho \geq \rho(\theta),$$

where $\rho(\theta)$ is given by (2).

In our paper we will use the class T_M which was investigated by Koczan [2]. The class T_M consists of typically real bounded functions, i.e

$$T_M = \{f \in T : |f(z)| < M, z \in \Delta\}, \quad M > 1.$$

For $\theta \in (0, \pi)$ let

$$(3) \quad H_\theta(z) = 2\theta + \frac{az}{1 - 2tz + z^2},$$

where

$$a = 8(\pi - \theta) \frac{\theta}{\pi},$$

and

$$(4) \quad t = 1 - \frac{2\theta}{\pi}.$$

Let

$$(5) \quad G_\theta(z) = \rho(\theta) \frac{e^{i\theta} - e^{-i\theta} e^{iH_\theta(z)}}{1 - e^{iH_\theta(z)}}.$$

Moreover, denote by

$$(6) \quad M = \frac{\rho}{\rho(\theta)},$$

where $\rho(\theta)$ is given by (2).

THEOREM 1. *The class $T_{\rho,\theta}$ can be written as follows*

$$T_{\rho,\theta} = \left\{ M \cdot \left(G_\theta \circ \frac{g}{M} \right) : g \in T_M \right\}, \quad \theta \in (0, \pi), \quad \rho \geq \rho(\theta),$$

where M , $\rho(\theta)$ and G_θ are defined by (2), (5), (6), respectively.

P r o o f. In the proof of this theorem we use the method which was presented in [4].

Let $f \in T$ and $f(z) \neq \rho e^{\pm i\theta}$, $\theta \in (0, \pi)$, $\rho \geq \rho(\theta)$. We consider a function of the form

$$\frac{f(z) - \rho e^{i\theta}}{f(z) - \rho e^{-i\theta}}.$$

This function is analytic in Δ and omits 0. Therefore, the function

$$h(z) = \frac{1}{i} \log \frac{f(z) - \rho e^{i\theta}}{f(z) - \rho e^{-i\theta}}$$

is analytic in Δ , too. The branch of the logarithm is such that $h(0) = 2\theta$.

Hence

$$f(z) = \rho \frac{e^{i\theta} - e^{-i\theta} e^{ih(z)}}{1 - e^{ih(z)}}.$$

Moreover, $h(z) \neq 2k\pi$, $k \in \mathbb{Z}$, because $1 - e^{ih(z)} \neq 0$. From this fact and from the equality

$$\operatorname{Im} f(z) = \frac{\rho}{|1 - e^{ih(z)}|^2} (1 - e^{-2i \operatorname{Im} h(z)}) \sin \theta,$$

we have $\operatorname{Im} z \operatorname{Im} h(z) \geq 0$, $z \in \Delta$.

Furthermore, $h(0) = 2\theta$ and for real x there is $h(x) \neq 2k\pi$, $k \in \mathbb{Z}$. The function h is typically real, so we get $0 < h(x) < 2\pi$, $x \in (-1, 1)$.

From these properties of h we conclude that h is subordinated to the univalent function H_θ , which is given by (3). For H_θ we have $H_\theta(0) = 2\theta$, $H_\theta(\Delta) = \mathbb{C} \setminus \{p \in \mathbb{R} : p \in (-\infty, 0) \cup (2\pi, \infty)\}$. Hence $h(z) = H_\theta(\omega(z))$ where $\omega(z) = H_\theta^{-1}(h(z))$. From this fact and $h, H_\theta \in T$ we get $\operatorname{Im} z \operatorname{Im} \omega(z) \geq 0$.

We have

$$\frac{2 \sin \theta}{\rho} = h'(0) = H_\theta'(0) \cdot \omega'(0) = a \cdot \omega'(0),$$

therefore,

$$\omega'(0) = \frac{2 \sin \theta}{\rho \cdot a} = \frac{\rho(\theta)}{\rho}.$$

Hence

$$\frac{\rho}{\rho(\theta)} \cdot \omega(z) \in T_{\frac{\rho}{\rho(\theta)}}.$$

Let

$$g(z) = \frac{\rho}{\rho(\theta)} \cdot \omega(z), \quad g \in T_M,$$

where M is given by (6). We have

$$f(z) = \rho \frac{e^{i\theta} - e^{-i\theta} e^{ih(z)}}{1 - e^{ih(z)}} = \rho \frac{e^{i\theta} - e^{-i\theta} e^{iH_\theta\left(\frac{g(z)}{M}\right)}}{1 - e^{iH_\theta\left(\frac{g(z)}{M}\right)}} = M \cdot G_\theta\left(\frac{g(z)}{M}\right),$$

where G_θ is given by (5). \square

Observe that the function (5) we can extend onto limiting cases $\theta = 0$ and $\theta = \pi$. When $\theta = 0$ we have

$$H_0(z) \equiv 0 \quad \text{and} \quad G_0(z) = \lim_{\theta \rightarrow 0} G_\theta(z) = \frac{z}{(1+z)^2}.$$

If $\theta = \pi$ then we get

$$H_\pi(z) \equiv 2\pi \quad \text{and} \quad G_\pi(z) = \lim_{\theta \rightarrow \pi} G_\theta(z) = \frac{z}{(1-z)^2}.$$

One can prove that the function (5) could be written in the form

$$(7) \quad G_\theta(z) = \frac{G\left(\frac{z+c}{1+cz}\right) - G(c)}{(1-c^2)G'(c)},$$

where G is given by (1) and $c = c(\theta) = \frac{2\theta-\pi}{2\sqrt{\pi\theta-\theta^2+\pi}}$.

LEMMA 1. *Let*

$$(8) \quad \rho_1(\theta) = \frac{1}{2} \left(\frac{\sin \theta}{\pi - \theta} + \cos \theta \right), \theta \in \left[0, \frac{\pi}{2} \right]$$

and

$$(9) \quad \rho^*(\theta) = \rho_1 \left(\frac{\pi}{2} - \left| \frac{\pi}{2} - \theta \right| \right), \theta \in [0, \pi].$$

Then

$$(10) \quad \rho(\theta) < \rho^*(\theta),$$

where $\rho(\theta)$ is given by (2) and $\rho^*(\theta)$ is described in (9), $\theta \in [0, \pi]$.

Proof. We shall prove the inequality (10). Observe that for $\theta = 0$ this inequality is obvious. Let $\theta \in (0, \frac{\pi}{2})$. Then (10) is equivalent to

$$(2\theta - \pi) \sin \theta + 2\theta(\pi - \theta) \cos \theta > 0.$$

Let us denote

$$l(\theta) = (2\theta - \pi) \sin \theta + 2\theta(\pi - \theta) \cos \theta, \theta \in \left(0, \frac{\pi}{2} \right).$$

Because

$$l''(\theta) = -3(\pi - 2\theta) \sin \theta - 2\theta(\pi - \theta) \cos \theta < 0, \theta \in (0, \frac{\pi}{2}),$$

so the function $l(\theta)$ attains its lowest value in 0 or in $\frac{\pi}{2}$. Hence

$$l(\theta) > \min \left\{ \lim_{\theta \rightarrow 0} l(\theta), \lim_{\theta \rightarrow \frac{\pi}{2}} l(\theta) \right\} = 0,$$

and consequently (10) is true. Moreover,

$$\rho(\theta) = \rho(\pi - \theta) \leq \rho_1(\pi - \theta), \theta \in \left[\frac{\pi}{2}, \pi \right].$$

Therefore,

$$\rho(\theta) < \rho^*(\theta), \theta \in [0, \pi]. \quad \square$$

In the next theorem we estimate the second and third coefficients of a function from the class $T_{\rho, \theta}$.

THEOREM 2. *If $f \in T_{\rho, \theta}$ and $f(z) = z + a_2 z^2 + a_3 z^3 + \dots$ then*

$$(11) \quad \frac{1}{\rho} \left(\frac{\sin \theta}{\theta} - \cos \theta \right) - 2 \leq a_2 \leq -\frac{1}{\rho} \left(\frac{\sin \theta}{\pi - \theta} + \cos \theta \right) + 2, \theta \in [0, \pi],$$

and

$$(12) \quad a_3 \geq \begin{cases} \frac{\sin^2 \theta}{3\rho^2} - 1, & (\rho, \theta) \in A \\ 3 - \frac{4}{\rho} \left(\frac{\sin \theta}{\pi - \theta} + \cos \theta \right) + \frac{1}{\rho^2} \left(\frac{\sin^2 \theta}{(\pi - \theta)^2} + \frac{\sin 2\theta}{\pi - \theta} + \frac{2\cos^2 \theta + 1}{3} \right), & (\rho, \theta) \in B \\ 3 - \frac{4}{\rho} \left(\frac{\sin \theta}{\theta} - \cos \theta \right) + \frac{1}{\rho^2} \left(\frac{\sin^2 \theta}{\theta^2} - \frac{\sin 2\theta}{\theta} + \frac{2\cos^2 \theta + 1}{3} \right), & (\rho, \theta) \in C \end{cases}$$

and

$$(13) \quad a_3 \leq 3 + \frac{4}{\rho} \left[\frac{\theta(\pi - \theta) \cos^2 \theta}{\pi \sin \theta} - \frac{\sin \theta}{\pi} - \left(1 - \frac{2\theta}{\pi}\right) \cos \theta \right] + \frac{\sin^2 \theta}{3\rho^2}.$$

The sets A , B , C are described as follows:

$$A = \{(\rho, \theta), \rho \geq \rho^*(\theta), \theta \in [0, \pi]\},$$

$$B = \{(\rho, \theta), \rho(\theta) \leq \rho \leq \rho_1(\theta), \theta \in [0, \frac{\pi}{2}]\},$$

$$C = \{(\rho, \theta), \rho(\theta) \leq \rho \leq \rho_1(\pi - \theta), \theta \in [\frac{\pi}{2}, \pi]\},$$

where $\rho_1(\theta)$, $\rho^*(\theta)$ are defined by (8) and (9).

Proof. Let $f(z) = z + a_2 z^2 + a_3 z^3 + \dots \in T_{\rho, \theta}$, $\theta \in [0, \pi]$, $\rho \geq \rho(\theta)$, $\rho(\theta)$ is given by (2), and let $G_\theta(z) = z + A_2(\theta)z^2 + A_3(\theta)z^3 + \dots$. From Theorem 1 $f(z) = M \cdot G_\theta(\frac{g(z)}{M})$, where G_θ is given by (7) and $g(z) = z + c_2 z + c_3 z^3 + \dots \in T_M$, M is defined by (6). Hence

$$(14) \quad a_2 = c_2 + \frac{1}{2M} \cdot G_\theta''(0)$$

and

$$(15) \quad a_3 = c_3 + c_2 \frac{1}{M} \cdot G_\theta''(0) + \frac{1}{6M^2} G_\theta'''(0),$$

where M is defined by (6). We have

$$(16) \quad G_\theta'''(0) = \frac{G''(c)}{G'(c)} \cdot (1 - c^2) - 2c$$

and

$$(17) \quad G_\theta'''(0) = \frac{(1 - c^2)^2 G'''(c)}{G'(c)} - 6c \frac{(1 - c^2) G''(c)}{G'(c)} + 6c^2.$$

From

$$(18) \quad \frac{G''(c)}{G'(c)} = \frac{-2c(3 - c^2)}{1 - c^4} + \frac{2\pi(1 - c^2)}{(1 + c^2)^2} \tan \frac{\pi c}{1 + c^2},$$

and

$$(19) \quad c + \frac{1}{c} = \frac{2\pi}{2\theta - \pi}, \quad \left(\frac{1 - c^2}{1 + c^2} \right)^2 = \frac{4}{\pi^2} (\pi\theta - \theta^2)$$

and (16) we get

$$(20) \quad A_2(\theta) = \frac{G_\theta''(0)}{2} = \frac{2}{\pi} (\pi - 2\theta - 2\theta(\pi - \theta) \cot \theta).$$

Using (6) and (20) in the formula (14) we have

$$a_2 = c_2 + \frac{\sin \theta}{2\theta(\pi - \theta)\rho} \cdot (\pi - 2\theta - 2\theta(\pi - \theta) \cot \theta)$$

and, consequently,

$$(21) \quad a_2 = c_2 + \frac{(\pi - 2\theta) \sin \theta}{2\theta(\pi - \theta)\rho} - \frac{\cos \theta}{\rho}.$$

Taking advantage of the precise estimation of the second coefficient for functions in T_M (see [2])

$$-2 \left(1 - \frac{1}{M}\right) \leq c_2 \leq 2 \left(1 - \frac{1}{M}\right)$$

and equality (21) we have

$$\begin{aligned} -2 \left(1 - \frac{\pi \sin \theta}{4\theta(\pi - \theta)\rho}\right) + \frac{\sin \theta(\pi - 2\theta)}{2\theta(\pi - \theta)\rho} - \frac{\cos \theta}{\rho} &\leq a_2 \\ &\leq 2 \left(1 - \frac{\pi \sin \theta}{4\theta(\pi - \theta)\rho}\right) + \frac{\sin \theta(\pi - 2\theta)}{2\theta(\pi - \theta)\rho} - \frac{\cos \theta}{\rho}. \end{aligned}$$

The above inequality is equivalent to (11).

Now we are going to estimate the third coefficient of $f \in T_{\rho, \theta}$. Using

$$\begin{aligned} (1 - c^2)^2 \frac{G'''(c)}{G'(c)} &= \frac{-6(1 - c^2)(c^4 - 6c^2 + 1)}{(1 + c^2)^2} + 2\pi^2 \frac{(1 - c^2)^4}{(1 + c^2)^4} \\ &+ \frac{12\pi c(1 - c^2)^2(c^2 - 3)}{(1 + c^2)^3} \tan \frac{\pi c}{1 + c^2} + 6 \frac{(1 - c^2)^4}{(1 + c^2)^4} \pi^2 \tan^2 \frac{\pi c}{1 + c^2}, \end{aligned}$$

(18) and (19) in the formula (17), we get

$$\begin{aligned} A_3(\theta) &= \frac{G'''(0)}{6} = -1 + 4 \left(\frac{2\theta - \pi}{\pi}\right)^2 \\ &+ \frac{16(2\theta - \pi)\theta(\pi - \theta)}{\pi^2} \cot \theta + \left(\frac{4\theta(\pi - \theta)}{\pi} \cot \theta\right)^2 + \frac{16(\pi - \theta)^2\theta^2}{3\pi^2}. \end{aligned}$$

From the fact and equalities (15) and (20), we have

$$\begin{aligned} a_3 &= c_3 + \frac{c_2}{\rho} \left(\frac{(\pi - 2\theta) \sin \theta}{\theta(\pi - \theta)} - 2 \cos \theta \right) - \frac{\sin^2 \theta}{4\rho^2\theta(\pi - \theta)} \\ &\quad + \frac{2 \cos^2 \theta + 1}{3\rho^2} - \frac{(\pi - 2\theta) \sin 2\theta}{2\rho^2(\pi - \theta)\theta}. \end{aligned}$$

Applying (2) and (4) we get

$$a_3 = c_3 + \frac{c_2}{\rho} (4t\rho(\theta) - 2 \cos \theta) + (4t^2 - 1) \frac{\rho^2(\theta)}{\rho^2} - \frac{4t\rho(\theta) \cos \theta}{\rho^2} + \frac{1 + 2 \cos^2 \theta}{3\rho^2}.$$

From now on to the end of this proof we take M, t as in the formulae (6) and (4), respectively. In order to estimate the coefficient a_3 we shall use the

region of values (c_2, c_3) , where $g(z) = z + c_2 z^2 + c_3 z^3 + \dots \in T_M$. This region is of the form [3]

$$A_{2,3}(T_M) = \left\{ (c_2, c_3) : \begin{aligned} -2 \left(1 - \frac{1}{M}\right) &\leq c_2 \leq 2 \left(1 - \frac{1}{M}\right), \\ c_2^2 - 1 + \frac{1}{M^2} &\leq c_3 \leq 3 - \frac{4}{M} + \frac{1}{M^2} - \frac{c_2^2}{M-1} \end{aligned} \right\}.$$

Let $c_2 = x$, $c_3 = y$. We consider a function

$$k(x, y) = y + \frac{x}{\rho} (4t\rho(\theta) - 2\cos\theta) + (4t^2 - 1) \frac{\rho^2(\theta)}{\rho^2} - \frac{4t\rho(\theta)\cos\theta}{\rho^2} + \frac{1 + 2\cos^2\theta}{3\rho^2}.$$

From the inequalities, given in the description of the set $A_{2,3}(T_M)$, we have

$$(22) \quad k(x, y) \leq 3 - \frac{4}{M} + \frac{1}{M^2} - \frac{x^2}{M-1} + \frac{2x}{\rho} (2t\rho(\theta) - \cos\theta) + (4t^2 - 1) \frac{\rho^2(\theta)}{\rho^2} - \frac{4t\rho(\theta)\cos\theta}{\rho^2} + \frac{1 + 2\cos^2\theta}{3\rho^2}$$

and

$$(23) \quad k(x, y) \geq x^2 - 1 + \frac{1}{M^2} + \frac{2x}{\rho} (2t\rho(\theta) - \cos\theta) + (4t^2 - 1) \frac{\rho^2(\theta)}{\rho^2} - \frac{4t\rho(\theta)\cos\theta}{\rho^2} + \frac{1 + 2\cos^2\theta}{3\rho^2}.$$

If we want to determine the upper estimate of a_3 , we shall find the maximum of the function

$$K(x) = -\frac{x^2}{M-1} + \frac{2x}{\rho} (2t\rho(\theta) - \cos\theta) + 3 - \frac{4}{M} + \frac{1}{M^2} + (4t^2 - 1) \frac{\rho^2(\theta)}{\rho^2} - \frac{4t\rho(\theta)\cos\theta}{\rho^2} + \frac{1 + 2\cos^2\theta}{3\rho^2},$$

when $x \in [-2(1 - \frac{1}{M}), 2(1 - \frac{1}{M})]$. Observe that K is a quadratic function of the form

$$K(x) = -\frac{\rho(\theta)}{\rho - \rho(\theta)} x^2 + \frac{2x}{\rho} (2t\rho(\theta) - \cos\theta) + 3 - 4 \frac{\rho(\theta)}{\rho} + 4t^2 \frac{\rho^2(\theta)}{\rho^2} - \frac{4t\rho(\theta)\cos\theta}{\rho^2} + \frac{1 + 2\cos^2\theta}{3\rho^2},$$

which attains its local maximum in the point

$$x_w = \frac{(2t\rho(\theta) - \cos\theta)(\rho - \rho(\theta))}{\rho\rho(\theta)}.$$

It is easy to check that $x_w \in [-2(1 - \frac{1}{M}), 2(1 - \frac{1}{M})]$ for $\rho \geq \rho(\theta)$ and $\theta \in [0, \pi]$. The maximum of K is equal to

$$K_{max} = \frac{(\rho - \rho(\theta))(2t\rho(\theta) - \cos^2 \theta)}{\rho^2 \rho(\theta)} + 3 - 4 \frac{\rho(\theta)}{\rho} + 4t^2 \frac{\rho^2(\theta)}{\rho^2} - \frac{4t\rho(\theta) \cos \theta}{\rho^2} + \frac{1 + 2 \cos^2 \theta}{3\rho^2},$$

or equivalently

$$K_{max} = 3 + \frac{1}{\rho} \left(\frac{4\theta(\pi - \theta) \cos^2 \theta}{\pi \sin \theta} + \frac{\sin^2 \theta}{3\rho} - \frac{4 \sin \theta}{\pi} - 4t \cos \theta \right).$$

From (22) we have $k(x, y) \leq K_{max}$ and consequently $a_3 \leq K_{max}$, $\rho \geq \rho(\theta)$, $\theta \in [0, \pi]$. Hence (13) is true.

Let us denote

$$\mathcal{K}(x) = x^2 - 1 + \frac{1}{M^2} + \frac{2x}{\rho}(2t\rho(\theta) - \cos \theta) + (4t^2 - 1) \frac{\rho^2(\theta)}{\rho^2} - \frac{4t\rho(\theta) \cos \theta}{\rho^2} + \frac{1 + 2 \cos^2 \theta}{3\rho^2}.$$

Now, we shall find the minimum of the function \mathcal{K} . The function \mathcal{K} is quadratic function having its local minimum in the point

$$x_w = \frac{\cos \theta - 2t\rho(\theta)}{\rho}.$$

There are three possible cases: I. $x_w \in [-2(1 - \frac{1}{M}), 2(1 - \frac{1}{M})]$, II. $x_w > 2(1 - \frac{1}{M})$, III. $x_w < -2(1 - \frac{1}{M})$.

I. The case $x_w \in [-2(1 - \frac{1}{M}), 2(1 - \frac{1}{M})]$ holds only if the inequality $-2(\rho - \rho(\theta)) \leq \cos \theta - 2t\rho(\theta) \leq 2(\rho - \rho(\theta))$

is satisfied. From the inequality

$$\cos \theta - 2t\rho(\theta) \leq 2(\rho - \rho(\theta))$$

we get

$$\rho \geq \frac{1}{2} \left[\cos \theta + \frac{\sin \theta}{\pi - \theta} \right].$$

Similarly, from the inequality

$$-2(\rho - \rho(\theta)) \leq \cos \theta - 2t\rho(\theta)$$

we have

$$\rho \geq \frac{1}{2} \left[\frac{\sin \theta}{\theta} - \cos \theta \right].$$

Hence $x_w \in [-2(1 - \frac{1}{M}), 2(1 - \frac{1}{M})]$ when $(\rho, \theta) \in A = \{(\rho, \theta) : \rho \geq \rho^*(\theta), \theta \in [0, \pi]\}$ and ρ^* given by (9).

For $(\rho, \theta) \in A$ the function \mathcal{K} attains the minimum in the point x_w and it is equal to

$$\mathcal{K}_{min} = \frac{\sin^2 \theta}{3\rho^2} - 1.$$

From (23) it follows that $\mathcal{K}_{min} \leq k(x, y)$ and consequently $a_3 \geq \mathcal{K}_{min}$ for $(\rho, \theta) \in A$.

II. Let now $x_w > 2(1 - \frac{1}{M})$. This inequality, conditions (2) and (4), and Lemma 1 give us $\rho < \rho_1(\theta)$. Hence the minimum of \mathcal{K} for $(\rho, \theta) \in B = \{(\rho, \theta) : \rho(\theta) \leq \rho < \rho_1(\theta), \theta \in [0, \frac{\pi}{2}]\}$ is attained in the point $x = 2(1 - \frac{1}{M})$. This minimum is equal to

$$\mathcal{K}_{min} = 3 - \frac{4}{\rho} \left(\frac{\sin \theta}{\pi - \theta} + \cos \theta \right) + \frac{1}{\rho^2} \left(\frac{\sin^2 \theta}{(\pi - \theta)^2} + \frac{\sin 2\theta}{\pi - \theta} + \frac{2 \cos^2 \theta + 1}{3} \right).$$

Therefore, from (23) we conclude that $k(x, y) \leq \mathcal{K}_{min}$ and consequently $a_3 \geq \mathcal{K}_{min}$ for $(\rho, \theta) \in B$.

III. Consider the case $x_w < -2(1 - \frac{1}{M})$. This condition is equivalent to $\rho < \rho_1(\pi - \theta)$. From this fact it follows that for $(\rho, \theta) \in C = \{(\rho, \theta) : \rho(\theta) \leq \rho < \rho_1(\pi - \theta), \theta \in (\frac{\pi}{2}, \pi]\}$ the function \mathcal{K} attains its minimum in the point $x = -2(1 - \frac{1}{M})$. The minimum is equal to

$$\mathcal{K}_{min} = 3 - \frac{4}{\rho} \left(\frac{\sin \theta}{\theta} - \cos \theta \right) + \frac{1}{\rho^2} \left(\frac{\sin^2 \theta}{\theta^2} - \frac{\sin 2\theta}{\theta} + \frac{2 \cos^2 \theta + 1}{3} \right).$$

From (23) we get $k(x, y) \leq \mathcal{K}_{min}$ and consequently $a_3 \geq \mathcal{K}_{min}$ for $(\rho, \theta) \in C$. So we have proved (12). \square

In the two following figures there are the regions of values (ρ, a_2) and (ρ, a_3) for $\theta = \frac{\pi}{3}$.

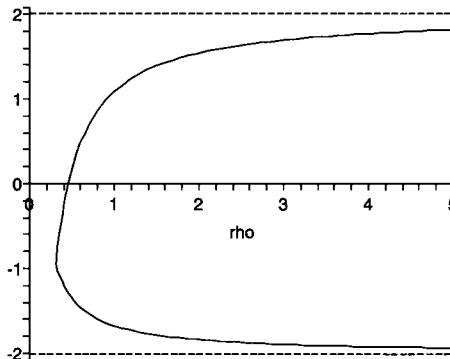


Fig. 1. The region of values of the point (ρ, a_2) (rightward of the curve)

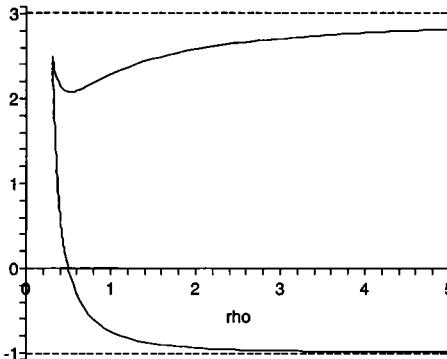


Fig. 2. The region of values of the point (ρ, a_3) (rightward of the curve)

Let b denote the fixed second coefficient of a function $f \in T_{\rho, \theta}$. Verifying $\rho, \theta, \rho \in [0, \pi]$, $\rho > \rho(\theta)$, we obtain $b \in [-2, 2]$. If $b = 2$, then the class $T_{\rho, \theta}$ consists of only one function $f(z) = \frac{z}{(1-z)^2}$. Analogously, if $b = -2$, then in this class there is only function $f(z) = \frac{z}{(1+z)^2}$. Therefore, we can restrict our research to the case $b \in (-2, 2)$.

THEOREM 3. *The Koebe domain for the class of typically real functions with a fixed second coefficient b is bounded and symmetric with respect to the real axis. Its boundary in the upper half plane is given by the polar equation $w = r(\theta)e^{i\theta}$, where*

$$r(\theta) = \begin{cases} \frac{1}{2-b} \left(\frac{\sin \theta}{\pi - \theta} + \cos \theta \right), & \theta \in [0, \theta_0) \\ \frac{1}{2+b} \left(\frac{\sin \theta}{\theta} - \cos \theta \right), & \theta \in [\theta_0, \pi] \end{cases},$$

and θ_0 is the only solution of the equation

$$(24) \quad \frac{1}{2-b} \left(\frac{\sin \theta}{\pi - \theta} + \cos \theta \right) = \frac{1}{2+b} \left(\frac{\sin \theta}{\theta} - \cos \theta \right),$$

in $[0, \pi]$.

Proof. From (11) for fixed $a_2 = b$, we get

$$\begin{cases} \frac{1}{\rho} \left(\frac{\sin \theta}{\pi - \theta} + \cos \theta \right) \leq 2 - b, & \theta \in [0, \pi] \\ \frac{1}{\rho} \left(\frac{\sin \theta}{\theta} - \cos \theta \right) \leq 2 + b \end{cases}$$

and consequently

$$\begin{cases} \rho \geq \frac{1}{2-b} \left(\frac{\sin \theta}{\pi - \theta} + \cos \theta \right), & \theta \in [0, \pi] \\ \rho \geq \frac{1}{2+b} \left(\frac{\sin \theta}{\theta} - \cos \theta \right) \end{cases}$$

Then

$$\rho \geq \max\left\{\frac{1}{2-b}\left(\frac{\sin \theta}{\pi-\theta} + \cos \theta\right), \frac{1}{2+b}\left(\frac{\sin \theta}{\theta} - \cos \theta\right)\right\}, \quad \theta \in [0, \pi].$$

Hence, the boundary of the Koebe domain is given by the following equation

$$r(\theta) = \max\left\{\frac{1}{2-b}\left(\frac{\sin \theta}{\pi-\theta} + \cos \theta\right), \frac{1}{2+b}\left(\frac{\sin \theta}{\theta} - \cos \theta\right)\right\}, \quad \theta \in [0, \pi].$$

Observe that the equation (24) can be written as

$$b\left(\frac{\sin \theta}{\pi-\theta} + \frac{\sin \theta}{\theta}\right) = 2\left(\frac{\sin \theta}{\theta} - \frac{\sin \theta}{\pi-\theta} - 2\cos \theta\right).$$

The above condition is equivalent to

$$\frac{b\pi \sin \theta}{\theta(\pi-\theta)} = \frac{2(\pi-2\theta)\sin \theta}{\theta(\pi-\theta)} - 4\cos \theta.$$

Hence we have

$$b = \frac{2}{\pi}(\pi-2\theta-\theta(\pi-\theta)\cot \theta).$$

From (20) we get

$$b = A_2(\theta).$$

We are going to prove that $A_2(\theta)$ is increasing function for $\theta \in (0, \pi)$. We have

$$(25) \quad A_2'(\theta) = -\frac{4}{\pi}\left(1 + (\pi-2\theta)\cot \theta - \theta(\pi-\theta)\frac{1}{\sin^2 \theta}\right).$$

But for $\theta \in (0, \frac{\pi}{2}]$

$$\sin^2 \theta + (\pi-2\theta)\sin \theta \cos \theta - \theta(\pi-\theta) \leq \theta^2 + (\pi-2\theta)\theta - \theta(\pi-\theta) = 0.$$

Hence $A_2'(\theta) > 0$, $\theta \in (0, \frac{\pi}{2}]$ and $A_2(\theta)$ is the increasing function in this range. Moreover, $A_2(\pi-\theta) = -A_2(\theta)$. Then $A_2'(\theta) > 0$, $\theta \in (\frac{\pi}{2}, \pi)$. From these facts, we conclude that the function (20) is increasing in $(0, \pi)$. The monotonicity of (20) and the fact

$$\lim_{\theta \rightarrow 0} A_2(\theta) = -2 \quad \text{and} \quad \lim_{\theta \rightarrow \pi} A_2(\theta) = 2$$

assure the existence of the only solution of the equation (24). This solution is denoted by θ_0 . Finally, we get

$$r(\theta) = \begin{cases} \frac{1}{2-b}\left(\frac{\sin \theta}{\pi-\theta} + \cos \theta\right), & \theta \in [0, \theta_0) \\ \frac{1}{2+b}\left(\frac{\sin \theta}{\theta} - \cos \theta\right), & \theta \in [\theta_0, \pi] \end{cases}.$$

■

From Theorem 3 we conclude

COROLLARY 1. *The Koebe domain for the class of typically real functions with a fixed second coefficient $b = 0$ is bounded and symmetric with respect*

to both axes, whose boundary in the first quadrant of the complex plane is given by the polar equation $w = r(\theta)e^{i\theta}$, where

$$r(\theta) = \frac{1}{2} \left(\frac{\sin \theta}{\pi - \theta} + \cos \theta \right).$$

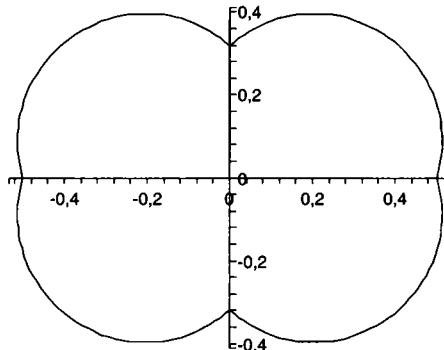


Fig. 3. The Koebe domain for the class of typically real function with fixed second coefficient $b = 0$

This set is the superdomain of the Koebe domain for the class of all typically real odd functions, which is still unknown.

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