

Yaşar Bolat

**OSCILLATION CRITERIA FOR SECOND-ORDER
FUNCTIONAL DIFFERENCE EQUATION
WITH NEUTRAL TERMS**

Abstract. In this manuscript, two type of new oscillation criteria are obtained respect to coefficient a_k in the following Eq. (1.1). In the subsection 2.1 considered as $a_k \geq 0$. In the subsection 2.2 allowed it to be an oscillating sequence. There are no results for the oscillation of second order difference equations with oscillating coefficients up to now.

1. Introduction

Recently, the oscillation and nonoscillation problems of second order difference equations have received a great amount of attention. This is probably due to the closeness of such phenomenon to those of the analogous differential equations. In addition, these equations have many applications in physics and in other fields (see [1-5]). Particularly, including neutral and delay terms equations find numerous applications in natural science and technology [29-34]. For instance, they are frequently used for the study of distributed networks containing lossless transmission lines. In this paper we consider a class of general second order nonlinear difference equation with general nonlinear neutral terms of the form

$$(1.1) \quad \Delta(p_k F(\Delta(y_k + a_k y_{k-\tau}))) + q_k G(\Delta(y_k + a_k y_{k-\tau})) + H(k, y_k, y_{k-r_1}, \dots, y_{k-r_n}) = 0$$

where $k \in \mathbb{N}$, and obtain two type new oscillation criteria respect to sequence $a_k \geq 0$ in the subsection 2.1 and it is even an oscillating sequence in the subsection 2.2. There are no results for the oscillation of second order difference equations with oscillating coefficients up to now.

The following conditions are always assumed to hold:

1991 *Mathematics Subject Classification*: 39A10, 39A11.

Key words and phrases: Oscillation; Second order difference equation; Neutral terms.

- i) $p_k > 0$ and $q_k > 0$ for every $k \in \mathbb{N}(k_0)$ where $\mathbb{N}(k_0) = \{k_0, k_0 + 1, \dots\}$ and $k_0 \in \mathbb{N}$,
- ii) $F : \mathbb{R} \rightarrow \mathbb{R}$ is a continuous increasing function such that $uF(u) > 0$ for $u \neq 0$,
- iii) $G : \mathbb{R} \rightarrow \mathbb{R}^+$ is a continuous function such that $0 < m_1 \leq G(u) \leq m_2$ where m_1 and m_2 are constants,
- iv) $H : \mathbb{N}(k_0) \times \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ is a continuous increasing function with respect to v_0, v_1, \dots, v_n , further $H(k, v_0, v_1, v_2, \dots, v_n)$ has same sign with respect to $v_0, v_1, v_2, \dots, v_n$,
- v) $\tau, r_1, r_2, \dots, r_n \in \mathbb{N}(1)$ and $(k - \tau) \rightarrow +\infty$, $(k - r_i) \rightarrow +\infty$ as $k \rightarrow \infty$ for every $i = 1, 2, \dots, n$.

Choosing Eq. (1.1) for this study is motivated by the numerous research on the oscillatory properties of several particular cases of Eq. (1.1). For example, the linear difference equation

$$\Delta(r_n \Delta x_{n-1}) + q_n x_n = 0$$

has been studied by [9-11, 15, 26 and the references cited therein] which is a special case of Eq. (1.1). The discrete Emden-Fowler equation

$$\Delta^2 x_{n-1} + q_n |x_n|^{v-1} x_n = 0, \quad v > 1$$

and its generalizations

$\Delta(r_n \Delta x_{n-1}) + q_n \phi(x_n) = 0$, where ϕ has the same properties as H and F ,
 $\Delta(r_n \Delta x_{n-1}) + g(n, x_n) = 0$, where g has the same properties as H and F ,
have been investigated by [12, 13, 20-24 and the references cited therein].
Another very important special case of Eq. (1.1), which arises in the theory of radial solutions for p -Laplacian equation on an annular domain (see [8] and the references cited therein), is the half- linear equation

$$\Delta(r_n |\Delta x_{n-1}|^{p-2} \Delta x_{n-1}) + q_n |x_n|^{p-2} x_n = 0, \quad p > 1,$$

and its more genaral form

$$\Delta(r_n |\Delta x_{n-1}|^{p-2} \Delta x_{n-1}) + g(n, x_n) = 0, \quad p > 1,$$

have been studied by [14, 16-19, 27 and the references cited therein] which are also special cases of Eq. (1.1). The delayed or advanced versions of the above equations have been study by [25 and the references cited therein]. Finally, the particular cases of Eq. (1.1), the equations

$$\Delta(r_n f(\Delta x_{n-1})) + g(n, x_n) = 0$$

and

$$\Delta(r_n f(\Delta x_{n-1})) + g(n, x_{\tau_n}) = 0$$

have been investigated by [28].

Recall that Δ is a forward difference operator which is defined by $\Delta y(k) = y(k+1) - y(k)$. Throughout this work we imply $y(k) = y_k$.

Let $\sigma = \max\{\tau, r_i\}$, $i = 1, 2, \dots, n$, and \mathbb{N}_0 be a fixed nonnegative integer. By a solution of Eq. (1.1), we mean a real sequence $\{y_k\}$ which is defined for all $k \geq \mathbb{N}_0 - \sigma$ and satisfies Eq. (1.1) for $k \geq \mathbb{N}_0$. A solution $\{y_k\}$ of Eq. (1.1) is said to be nonoscillatory if all the terms y_k are eventually of fixed sign. Otherwise, the solution $\{y_k\}$ is called oscillatory. In this paper, we shall be concerned only with the nontrivial solutions of Eq. (1.1).

2. Main results

2.1. Oscillation criteria for the case of $0 \leq a_k < 1$. We consider the coefficient a_k as $0 \leq a_k < 1$ in the following Lemma 1, Theorem 1, Theorem 2 and Theorem 3.

LEMMA 1. *Assume that y_k is nonoscillatory solution of Eq. (1.1). If the condition*

$$(C_1) \quad \sum^{\infty} F^{-1}\left(\frac{-c}{p_k}\right) = -\infty \quad (c > 0)$$

is satisfied, then there exists $k_1 \in \mathbb{N}(k_0)$ such that

$$(y_k + a_k y_{k-\tau})\Delta(y_k + a_k y_{k-\tau}) > 0$$

for all $k \in \mathbb{N}(k_1)$.

Proof. Suppose that there exists a $k_1 \in \mathbb{N}(k_0)$ such that $y_k > 0$ for all $k \in \mathbb{N}(k_1)$. Since $(k - \tau) \rightarrow \infty$ and $(k - r_i) \rightarrow \infty$ as $k \rightarrow \infty$ for $i = 1, 2, \dots, n$, one can find $k_2 \in \mathbb{N}(k_1)$ such that $y_{k-\tau} > 0$ and $y_{k-r_i} > 0$ for every $i = 1, 2, \dots, n$ and all $k \in \mathbb{N}(k_2)$. Define

$$z_k = y_k + a_k y_{k-\tau}.$$

Since $0 \leq a_k < 1$, there exist a $k_3 \geq k_2$ and a constant λ ($0 < \lambda < 1$) such that

$$y_k = z_k - a_k y_{k-\tau} \geq \lambda z_k > 0 \quad \text{for } k \in \mathbb{N}(k_3).$$

Therefore we can find a $k_4 \geq k_3$ such that

$$y_{k-r_1} \geq \lambda z_{k-r_1}, y_{k-r_2} \geq \lambda z_{k-r_2}, \dots, y_{k-r_n} \geq \lambda z_{k-r_n} > 0 \quad \text{for all } k \in \mathbb{N}(k_4).$$

Then from Eq. (1.1) we have

$$(2.1) \quad \begin{aligned} \Delta(p_k F(\Delta z_k)) \\ \leq -q_k G(\Delta z_k) - H(k, \lambda z_k, \lambda z_{k-r_1}, \lambda z_{k-r_2}, \dots, \lambda z_{k-r_n}) < 0 \end{aligned}$$

for all $k \in \mathbb{N}(k_4)$. From (2.1) it is clear that $p_k F(\Delta z_k)$ is decreasing. Therefore there are two cases. Either $\Delta z_k < 0$ or $\Delta z_k > 0$.

Assume that $\Delta z_k < 0$ for all $k \in N(k_4)$. Summing up (2.1) from k_4 to $k-1$ we get

$$(2.2) \quad p_k F(\Delta z_k) \leq p_{k_4} F(\Delta z_{k_4}) = -c < 0 \quad (c > 0) \text{ for all } k \in N(k_4).$$

Then from (2.2) we have

$$(2.3) \quad F(\Delta z_k) \leq \frac{-c}{p_k} \text{ for all } k \in N(k_4).$$

Then from (2.3) we obtain

$$(2.4) \quad \Delta z_k \leq F^{-1}\left(\frac{-c}{p_k}\right) \text{ for all } k \in N(k_4).$$

Summing up (2.4) from k_4 to $k-1$, we obtain

$$(2.5) \quad z_k \leq z_{k_4} + \sum_{j=k_4}^{k-1} F^{-1}\left(\frac{-c}{p_j}\right).$$

But, according to (C_1) , inequality (2.5) implies that $z_k < 0$ as $k \rightarrow \infty$, which contradicts to $z_k = y_k + a_k y_{k-\tau} > 0$. Hence $\Delta z_k = \Delta(y_k + a_k y_{k-\tau}) > 0$.

If $y_k < 0$ for all $k \in N(k_1)$, then similar reasoning implies a contradiction. We omit the details to avoid repetition. \square

THEOREM 1. *Let (C_1) hold and the condition*

$$(C_2) \quad \sum_{j=1}^{\infty} F^{-1}\left(\frac{\phi_j}{p_j}\right) = -\infty$$

is satisfied, where $\phi_j = p_{k_5} F(\Delta z_{k_5}) - \sum_{s=j_5}^{j-1} H(s, c, c, c, \dots, c)$ with a positive constant c . Then every solution of Eq. (1.1) is oscillatory.

P r o o f. Suppose that there exists a $k_1 \in N(k_0)$ such that $y_k > 0$ for all $k \in N(k_1)$. Since $(k-\tau) \rightarrow \infty$ and $(k-r_i) \rightarrow \infty$ as $k \rightarrow \infty$ for $i = 1, 2, \dots, n$, one can find $k_2 \in N(k_1)$ such that $y_{k-\tau} > 0$ and $y_{k-r_i} > 0$ for every $i = 1, 2, \dots, n$ and all $k \in N(k_2)$. Define

$$z_k = y_k + a_k y_{k-\tau}.$$

Since $0 \leq a_k < 1$, there exist a $k_3 \geq k_2$ and a constant λ ($0 < \lambda < 1$) such that

$$y_k = z_k - a_k y_{k-\tau} \geq \lambda z_k > 0 \quad \text{for } k \in N(k_3).$$

Therefore we can find a $k_4 \geq k_3$ such that

$$y_{k-r_1} \geq \lambda z_{k-r_1}, y_{k-r_2} \geq \lambda z_{k-r_2}, \dots, y_{k-r_n} \geq \lambda z_{k-r_n} > 0 \quad \text{for } k \in N(k_4).$$

Then from Eq. (1.1) we have

$$\Delta(p_k F(\Delta z_k)) \leq -q_k G(\Delta z_k) - H(k, \lambda z_k, \lambda z_{k-r_1}, \lambda z_{k-r_2}, \dots, \lambda z_{k-r_n}) < 0$$

for all $k \in \mathbb{N}(k_4)$. By Lemma 1 since $\Delta z_k > 0$, z_k is increasing. Therefore there exists a constant $c > 0$ and a $k_5 \geq k_4$ such that $z_k > c > 0$, $z_{k-r_1} > c > 0$, $z_{k-r_2} > c > 0, \dots, z_{k-r_n} > c > 0$ for all $k \in \mathbb{N}(k_5)$. Hence we have from last inequality

$$(2.6) \quad \Delta(p_k F(\Delta z_k)) \leq -H(k, c, c, c, \dots, c)$$

for all $k \in \mathbb{N}(k_5)$. Summing up (2.6) from k_5 to $k-1$, we obtain

$$(2.7) \quad p_k F(\Delta(y_k + a_k y_{k-\tau})) \leq p_{k_5} F(\Delta z_{k_5}) - \sum_{s=k_5}^{k-1} H(s, c, c, c, \dots, c).$$

Let us take $\phi_k = p_{k_5} F(\Delta z_{k_5}) - \sum_{s=k_5}^{k-1} H(s, c, c, c, \dots, c)$. Then from (2.7) we have

$$(2.8) \quad \Delta z_k < F^{-1}\left(\frac{\phi_k}{p_k}\right).$$

Summing up (2.8) from k_5 to $k-1$, we have

$$(2.9) \quad z_k < z_{k_5} + \sum_{j=k_5}^{k-1} F^{-1}\left(\frac{\phi_j}{p_j}\right).$$

But, according to the condition (C_2) , inequality (2.9) implies that $z_k = y_k + a_k y_{k-\tau} = -\infty$ as $k \rightarrow \infty$, which contradicts to the fact that $y_k > 0$ and $y_k + a_k y_{k-\tau} > 0$. If $y_k < 0$ for all $k \in N(k_1)$, then similar reasoning implies a contradiction. This completes the proof. \square

THEOREM 2. *Let (C_1) hold. Moreover, suppose that following conditions are satisfied:*

$$(C_3) \quad p_k \Delta s_k \leq -M,$$

where s_k is a positive sequence with $\Delta s_k \leq 0$, and M is a nonnegative number, and

$$(C_4) \quad \sum_{\sigma}^{\infty} F^{-1}\left(\frac{\varphi_{\sigma}}{s_{\sigma} p_{\sigma}}\right) = -\infty$$

where φ_k is any negative sequence for all sufficiently large k . Then every solutions of Eq. (1.1) is oscillatory.

P r o o f. Whithout repeating the same assumption, let us consider in here the part of the proof of Theorem 1 untill (2.6). Let s_k be a positive sequence which satisfies condition (C_3) . If we multiply the inequality (2.6) with s_k

and later take its sum from k_5 to $k - 1$, we obtain

$$(2.10) \quad s_k p_k F(\Delta z_k) - s_{k_5} p_{k_5} F(\Delta z_{k_5}) - \sum_{j=k_5}^{k-1} F(\Delta z_j) p_j \Delta s_j \leq - \sum_{j=k_5}^{k-1} s_j H(j, c, c, c, \dots, c).$$

Applying the condition (C_3) to (2.10) we have

$$(2.11) \quad s_k p_k F(\Delta z_k) - s_{k_5} p_{k_5} F(\Delta z_{k_5}) \leq -M \sum_{j=k_5}^{k-1} F(\Delta z_j) - \sum_{j=k_5}^{k-1} s_j H(j, c, c, c, \dots, c) \leq - \sum_{j=k_5}^{k-1} s_j H(j, c, c, c, \dots, c).$$

Let us take $\varphi_k = s_{k_5} p_{k_5} F(\Delta z_{k_5}) - \sum_{j=k_5}^{k-1} s_j H(j, c, c, c, \dots, c)$ in the inequality (2.11). Then from (2.11) we have

$$(2.12) \quad \Delta z_k \leq F^{-1} \left(\frac{\varphi_k}{s_k p_k} \right).$$

Summing up (2.12) from k_5 to $k - 1$, we obtain

$$(2.13) \quad y_k + a_k y_{k-\tau} \leq y_{k_5} + a_{k_5} y_{k_5-\tau} + \sum_{\sigma=k_5}^{k-1} F^{-1} \left(\frac{\varphi_{\sigma}}{s_{\sigma} p_{\sigma}} \right).$$

By condition (C_4) inequality (2.13) implies that $\lim_{k \rightarrow \infty} (y_k + a_k y_{k-\tau}) = -\infty$. This is a contradiction. If $y_k < 0$ for all $k \in N(k_1)$, then similar reasoning implies a contradiction. Hence the proof is complete. \square

THEOREM 3. *Let conditions (C_1) and (C_3) hold. In addition, assume that following conditions are satisfied:*

$$(C_5) \quad \frac{H(k, v_0, v_1, \dots, v_n)}{H_1(v_0, v_1, \dots, v_n)} \geq \beta_k > 0,$$

where the function $H_1(v_0, v_1, \dots, v_n)$ is a continuous function and has the same sign with respect to v_0, v_1, \dots, v_n , and

$$(C_6) \quad \sum_{u=k_3}^{\infty} F^{-1} \left(\frac{\psi_u}{s_u p_u} \right) = -\infty,$$

where $\psi_k = s_{k_5} p_{k_5} F(\Delta z_{k_5}) - \sum_{j=k_3}^{k-1} \mu \beta_j s_j$, where s_k is a positive sequence with $\Delta s_k \leq 0$ and μ is a positive constant. Then every solution of Eq. (1.1) is oscillatory.

Proof. Suppose that there exists a $k_1 \in \mathbb{N}(k_0)$ such that $y_k > 0$ for all $k \in \mathbb{N}(k_1)$. Since $(k - \tau) \rightarrow \infty$ and $(k - r_i) \rightarrow \infty$ as $k \rightarrow \infty$ for $i = 1, 2, \dots, n$, one can find $k_2 \in \mathbb{N}(k_1)$ such that $y_{k-\tau} > 0$ and $y_{k-r_i} > 0$ for every $i = 1, 2, \dots, n$ and all $k \in \mathbb{N}(k_2)$. Hence, we can find any function $H_1(y_k, y_{k-r_1}, y_{k-r_2}, \dots, y_{k-r_n})$ such that

$$(2.14) \quad \begin{aligned} H(k, y_k, y_{k-r_1}, y_{k-r_2}, \dots, y_{k-r_n}) \\ \geq \beta_k H_1(y_k, y_{k-r_1}, y_{k-r_2}, \dots, y_{k-r_n}) > 0 \end{aligned}$$

for all $k \in \mathbb{N}(k_2)$. Define $z_k = y_k + a_k y_{k-\tau}$. Since $0 \leq a_k < 1$, there exist a $k_3 \geq k_2$ and a constant λ ($0 < \lambda < 1$) such that

$$y_k = z_k - a_k y_{k-\tau} \geq \lambda z_k > 0 \text{ for } k \in \mathbb{N}(k_3).$$

Therefore we can find a $k_4 \geq k_3$ such that

$$y_{k-r_1} \geq \lambda z_{k-r_1}, y_{k-r_2} \geq \lambda z_{k-r_2}, \dots, y_{k-r_n} \geq \lambda z_{k-r_n} > 0 \text{ for } k \in \mathbb{N}(k_4).$$

Then we can rewrite (2.14) in the form

$$\begin{aligned} H(k, \lambda z_k, \lambda z_{k-r_1}, \lambda z_{k-r_2}, \dots, \lambda z_{k-r_n}) \\ \geq \beta_k H_1(\lambda z_k, \lambda z_{k-r_1}, \lambda z_{k-r_2}, \dots, \lambda z_{k-r_n}) > 0. \end{aligned}$$

Therefore considering continuity of $H_1(v_0, v_1, \dots, v_2)$ and since $z_k > 0$ is increasing, we have

$$\liminf_{k \rightarrow \infty} H_1(\lambda z_k, \lambda z_{k-r_1}, \lambda z_{k-r_2}, \dots, \lambda z_{k-r_n}) = H_1(\delta, \delta, \dots, \delta).$$

Thus, we obtain $0 < H_1(\delta, \delta, \dots, \delta) < +\infty$. Choose μ such that $0 < \mu < H_1(\delta, \delta, \dots, \delta) < +\infty$. Then there exists $k_5 \geq k_4$ such that

$$(2.15) \quad H_1(\lambda z_k, \lambda z_{k-r_1}, \lambda z_{k-r_2}, \dots, \lambda z_{k-r_n}) > \mu$$

for all $k \in \mathbb{N}(k_5)$. Therefore from Eq. (1.1), (2.14) and (2.15) we obtain

$$(2.16) \quad \Delta(p_k F(\Delta z_k)) + \mu \beta_k \leq 0.$$

If we treat (2.16) as we treat (2.6) in the proof of Theorem 3,

$$(2.17) \quad s_k p_k F(\Delta z_k) - s_{k_5} p_{k_5} F(\Delta z_{k_5}) \leq \sum_{j=k_5}^{k-1} F(\Delta z_j) p_j \Delta s_j - \sum_{j=k_5}^{k-1} \mu \beta_j s_j.$$

Applying the condition (C_3) to (2.17) we have

$$\begin{aligned} (2.18) \quad s_k p_k F(\Delta z_k) - s_{k_5} p_{k_5} F(\Delta z_{k_5}) \\ \leq -M \sum_{j=k_5}^{k-1} F(\Delta z_j) - \sum_{j=k_5}^{k-1} \mu \beta_j s_j \leq - \sum_{j=k_5}^{k-1} \mu \beta_j s_j. \end{aligned}$$

Let us take $\psi_k = s_{k_5} p_{k_5} F(\Delta z_{k_5}) - \sum_{j=k_3}^{k-1} \mu \beta_j s_j$ in (2.18). Then summing up (2.18) from k_5 to $k-1$ and considering condition (C_6) from (2.18) we

have

$$y_k + a_k y_{k-\tau} < y_{k_5} + a_{k_5} y_{k_5-\tau} + \sum_{u=k_5}^{k-1} F^{-1} \left(\frac{\psi_u}{sup_u} \right) \rightarrow -\infty$$

as $k \rightarrow \infty$. This is a contradiction. If $y_k < 0$ for all $k \in \mathbb{N}(k_1)$, then similar reasoning implies a contradiction. Hence the proof is complete. \square

2.2. Oscillation criteria for the case of oscillating coefficient a_k

We consider coefficient a_k as an oscillating sequence in the following Lemma 2, Theorem 4, Theorem 5 and Theorem 6.

LEMMA 2. *Assume that y_k is nonoscillatory bounded solution of Eq. (1.1) and it does not tend to zero as $k \rightarrow \infty$. If the condition (C_1) and*

$$(C_7) \quad \liminf_{k \rightarrow \infty} a_k = 0$$

is satisfied, then there exists a $k_ \in \mathbb{N}(k_0)$ such that*

$$(y_k + a_k y_{k-\tau}) \Delta (y_k + a_k y_{k-\tau}) > 0$$

for all $k \in \mathbb{N}(k_)$.*

P r o o f. Suppose that y_k is nonoscillatory bounded solution of Eq. (1.1) and without generality it is positive. Then Since $(k - \tau) \rightarrow \infty$ and $(k - r_i) \rightarrow \infty$ as $k \rightarrow \infty$ for $i = 1, 2, \dots, n$, one can find $k_1 \in \mathbb{N}(k_0)$ such that $y_{k-\tau} > c > 0$ and $y_{k-r_i} > c > 0$ for every $i = 1, 2, \dots, n$ and all $k \in \mathbb{N}(k_1)$. Define

$$z_k = y_k + a_k y_{k-\tau}.$$

Since y_k does not tend to zero as $k \rightarrow \infty$ and it is bounded, $\liminf_{k \rightarrow \infty} a_k y_{k-\tau} = 0$. Therefore $z_k \downarrow c > 0$ as $k \rightarrow \infty$. Hence we find a sufficiently large $k_2 \geq k_1$ and a constant λ ($0 < \lambda < 1$) such that

$$y_k = z_k - a_k y_{k-\tau} \geq \lambda z_k > 0 \text{ for } k \in \mathbb{N}(k_2).$$

Therefore we can find a $k_3 \geq k_2$ such that

$$y_{k-r_1} \geq \lambda z_{k-r_1}, y_{k-r_2} \geq \lambda z_{k-r_2}, \dots, y_{k-r_n} \geq \lambda z_{k-r_n} > 0$$

for $k \in \mathbb{N}(k_3)$. Rest of the proof is similar to the proof of Lemma 1 in the section 2.1. \square

THEOREM 4. *Assume that conditions (C_1) , (C_2) and (C_7) are satisfied. Then every bounded solution of Eq. (1.1) is either oscillatory or tends to zero as $k \rightarrow \infty$.*

P r o o f. Suppose that y_k is nonoscillatory bounded solutions of Eq. (1.1) and without generality it is positive. Furthermore assume that y_k does not tend to zero if $k \rightarrow \infty$. Then, since $(k - \tau) \rightarrow \infty$ and $(k - r_i) \rightarrow \infty$ as

$k \rightarrow \infty$ for $i = 1, 2, \dots, n$, one can find $k_1 \in \mathbb{N}(k_0)$ such that $y_{k-\tau} > c > 0$ and $y_{k-r_i} > c > 0$ for every $i = 1, 2, \dots, n$ and all $k \in \mathbb{N}(k_1)$. Define

$$z_k = y_k + a_k y_{k-\tau}.$$

By Lemma 2 $z_k = y_k + a_k y_{k-\tau} > 0$ and $\Delta z_k > 0$. Since y_k does not tend to zero as $k \rightarrow \infty$ and it is bounded, $\liminf_{k \rightarrow \infty} a_k y_{k-\tau} = 0$. Therefore there exist a $k_2 \geq k_1$ and a constant λ ($0 < \lambda < 1$) such that

$$y_k = z_k - a_k y_{k-\tau} \geq \lambda z_k > 0 \text{ for sufficiently large all } k \in \mathbb{N}(k_2).$$

Therefore we can find a $k_3 \geq k_2$ such that

$$y_{k-r_1} \geq \lambda z_{k-r_1}, y_{k-r_2} \geq \lambda z_{k-r_2}, \dots, y_{k-r_n} \geq \lambda z_{k-r_n} > 0 \text{ for all } k \in \mathbb{N}(k_3).$$

Rest of the proof is all similar to the proof of Theorem 1 in the section 2.1. \square

THEOREM 5. *Assume that conditions (C_1) , (C_3) , (C_6) and (C_7) are satisfied. Then every bounded solution of Eq. (1.1) is either oscillatory or tends to zero as $k \rightarrow \infty$.*

Proof. The proof is similar to proofs of Theorem 2 in Section 2.1, so we omit it. \square

THEOREM 6. *Assume that conditions (C_1) , (C_3) , (C_5) , (C_6) and (C_7) are satisfied. Then every bounded solution of Eq. (1.1) is either oscillatory or tends to zero as $k \rightarrow \infty$.*

Proof. The proof is all similar to the proofs of Theorem 3 in the section 2.1. Therefore we omit the details to avoid repetition. \square

References

- [1] Ravi P. Agarwal, *Difference Equation and Inequalities*, Marcel Dekker. New York, 2000.
- [2] Ravi P. Agarwal, *Advanced Topics in Difference Equations*, Kluwer Academic Publishers, London, 1997.
- [3] Ravi P. Agarwal, S. R. Grace, D. O'Regan, *Oscillatory Theory for Difference and Functional Differential Equations*, Kluwer Academic, Dordrecht, 2000.
- [4] I. Györi, G. Ladas, *Oscillation Theory of Delay Differential Equations with Applications*, Clarendon, Oxford, 1991.
- [5] R. E. Mickens, *Difference Equations: Theory and Applications*, Van Nostrand-Reinhold, New York, 1990.
- [6] G. H. Hardy, J. E. Littlewood, G. Pólya, *Inequalities*, Cambridge Univ. Press, 1964.
- [7] J. J. A. M. Brants, *Oscillation theorems for second-order functional differential equations*, J. Math. Anal. Appl. 63 (1978) 54–64.
- [8] A. Cabada, *Extremal solutions for the difference ϕ -Laplacian problem with nonlinear functional boundary conditions*, Comput. Math. Appl. 42 (2001) 593–601.

- [9] S. Chen, L. H. Erbe, *Riccati techniques and discrete oscillations*, J. Math. Anal. Appl. 142 (1989) 468–487.
- [10] J. W. Hooker, M. K. Kwong, W. T. Patula, *Oscillatory second order linear difference equations*, SIAM J. Math. Anal. 18 (1987) 54–63.
- [11] J. W. Hooker, W. T. Patula, *Riccati type transformations for second-order linear difference equations*, J. Math. Anal. Appl. 82 (1981) 451–462.
- [12] J. W. Hooker, W. T. Patula, *A second-order nonlinear difference equation: Oscillation and asymptotic behaviour*, J. Math. Anal. Appl. 91 (1983) 9–29.
- [13] H. J. Li, S. S. Cheng, *An oscillation theorem for a second order nonlinear difference equation*, Utilitas Math. 43 (1993) 155–159.
- [14] W. T. Li, S. S. Cheng, *Oscillation criteria for a nonlinear difference equation*, Comput. Math. Appl. 36 (1998) 87–94.
- [15] W. T. Patula, *Growth and oscillation properties of second order linear difference equations*, SIAM J. Math. Anal. 10 (1979) 55–61.
- [16] P. Rehák, *Hartman–Wintner type lemma, oscillation, and conjugacy criteria for half-linear difference equations*, J. Math. Anal. Appl. 252 (2000) 813–827.
- [17] P. Rehák, *Oscillatory criteria for second order half-linear difference equations*, J. Differ. Equations Appl. 7 (2001) 483–505.
- [18] P. Rehák, *Generalized discrete Riccati equation and oscillation of half-linear difference equations*, Math. Comput. Modelling 34 (2001) 257–269.
- [19] P. Rehák, *Oscillatory properties of second order half-linear difference equations*, Czechoslovak Math. J. 51 (2001) 303–321.
- [20] B. Szmanda, *Oscillation of solutions of second order difference equations*, Portugal. Math. 37 (1978) 251–54.
- [21] B. Szmanda, *Characterization of oscillation of second order nonlinear difference equations*, Bull. Polish Acad. Sci. Math. 34 (1986) 133–141.
- [22] E. Thandapani, I. Györi, B. S. Lalli, *An application of discrete inequality to second order nonlinear oscillation*, J. Math. Anal. Appl. 186 (1994) 200–208.
- [23] E. Thandapani, S. Pandian, *On the oscillatory behaviour of solutions of second order nonlinear difference equations*, Z. Anal. Anwendungen 13 (1994) 347–358.
- [24] B. G. Zhang, G. D. Chen, *Oscillation of certain second order nonlinear difference equations*, J. Math. Anal. Appl. 199 (1996) 827–841.
- [25] Z. Zhang, J. Zhang, *Oscillation criteria for second-order functional difference equations with “summation small” coefficient*, Comput. Math. Appl. 38 (1999) 25–31.
- [26] B. G. Zhang, Y. Zhou, *Oscillation and nonoscillation for second-order linear difference equations*, Comput. Math. Appl. 39 (2000) 1–7.
- [27] R. P. Agarwal, S. R. Grace, D. O'Regan, *On the oscillation of certain second order difference equations*, J. Differ. Equations Appl. 9 (2003) 109–119.
- [28] H. A. El-Morshedy and S. R. Grace, *Comparison theorems for second order nonlinear difference equations*, J. Math. Anal. Appl. 306 (2005) 106–121.
- [29] Hong Li, Hou-biao Li and Shou-ming Zhong, *Stability of neutral type descriptor systems with mixed delays*, Chaos, Solitons & Fractals, Volume 33, Issue 5, August 2007, Pages 1796–1800.
- [30] Ker-Wei Yu and Chang-Hua Lien, *Stability criteria for uncertain neutral systems with interval time-varying delays*, Chaos, Solitons & Fractals, In Press, Corrected Proof, Available online 20 February 2007,
- [31] Yongkun Li, *Positive periodic solutions of periodic neutral Lotka–Volterra system with distributed delays*, Chaos, Solitons & Fractals, In Press, Corrected Proof, Available online 23 October 2006,

- [32] Ju H. Park and O. M. Kwon, *Stability analysis of certain nonlinear differential equation* Chaos, Solitons & Fractals, In Press, Corrected Proof, Available online 19 October 2006.
- [33] Ju H. Park and O. Kwon, *Controlling uncertain neutral dynamic systems with delay in control input*, Chaos, Solitons & Fractals, Volume 26, Issue 3, November 2005, Pages 805-812.
- [34] Ju H. Park, *Design of dynamic controller for neutral differential systems with delay in control input*, Chaos, Solitons & Fractals, Volume 23, Issue 2, January 2005, Pages 503-509.

AFYON KOCATEPE UNIVERSITY
FACULTY OF SCIENCE AND LITERATURES
DEPARTMENT OF MATHEMATICS, ANS CAMPUS
03200 - AFYONKARAHISAR, TURKEY
e-mail: yasarbolat@aku.edu.tr

Received September 5, 2007; revised version January 13, 2008.

