

D. Turkoglu, I. Altun, B. Fisher

## FIXED POINT THEOREM FOR SEQUENCES OF MAPS

**Abstract.** In this paper, we prove a common fixed point theorem for sequences of maps under the condition of compatible mappings on complete metric space. We extend and generalize several fixed point theorems on complete metric space.

### 1. Introduction

In this paper  $(X, d)$  denotes a complete metric space and  $B(X)$  stands for the set of all bounded subsets of  $X$ . The function  $\delta$  of  $B(X) \times B(X)$  into  $[0, \infty)$  is defined as

$$\delta(A, B) = \sup\{d(a, b) : a \in A, b \in B\}$$

for all  $A, B$  in  $B(X)$ . If  $A = \{a\}$  is singleton, we write  $\delta(A, B) = \delta(a, B)$  and if  $B = \{b\}$ , then we put  $\delta(A, B) = \delta(a, b)$ . It is easily seen that

$$\begin{aligned}\delta(A, B) &= \delta(B, A) \geq 0, \\ \delta(A, B) &\leq \delta(A, C) + \delta(C, B), \\ \delta(A, A) &= \text{diam } A, \\ \delta(A, B) = 0 &\text{ implies } A = B = \{a\}\end{aligned}$$

for all  $A, B, C$  in  $B(X)$ . We recall some definitions and a basic lemmas of Fisher [2] and Imdad et al [3]. Let  $\{A_n : n = 1, 2, \dots\}$  be a sequence of subsets of  $X$ . We say that the sequence  $\{A_n\}$  converges to a subset  $A$  of  $X$  if each point  $a$  in  $A$  is the limit of a convergent sequence  $\{a_n\}$  with  $a_n$  in  $A_n$  for  $n = 1, 2, \dots$  and if for any  $\varepsilon > 0$ , there exists an integer  $N$  such that  $A_n \subseteq A_\varepsilon$  for  $n > N$ ,  $A_\varepsilon$  being the union of all open spheres with centers in  $A$  and radius  $\varepsilon$ . The following lemmas hold.

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LEMMA 1. [2] *If  $\{A_n\}$  and  $\{B_n\}$  are sequences of bounded subsets of  $(X, d)$  which converge to the bounded subsets  $A$  and  $B$  respectively then the sequence  $\{\delta(A_n, B_n)\}$  converges to  $\delta(A, B)$ .*

LEMMA 2. [3] *If  $\{A_n\}$  is a sequence of bounded sets in the complete metric space  $(X, d)$  and if  $\lim_{n \rightarrow \infty} \delta(A_n, \{y\}) = 0$  for some  $y \in X$  then  $\{A_n\} \rightarrow \{y\}$ .*

A set-valued mapping of  $F$  of  $X$  into  $B(X)$  is continuous at the point  $x$  in  $X$  if whenever  $\{x_n\}$  is a sequence of points of  $X$  converging to  $x$ , the sequence  $\{Fx_n\}$  in  $B(X)$  converges to  $Fx$ .  $F$  is said to be continuous in  $X$  if it is continuous at each point  $x$  in  $X$ . We say that  $z$  is a fixed point of  $F$  if  $z$  is in  $Fz$ .

DEFINITION 1. [4] Let  $(X, d)$  be a metric space. Let  $S : X \rightarrow X$  and  $F : X \rightarrow B(X)$ .  $F$  and  $S$  are compatible if and only if  $SFx \in B(X)$  for  $x \in X$  and  $\delta(SFx_n, FSx_n) \rightarrow 0$  whenever  $\{x_n\}$  is a sequence in  $X$  such that  $Sx_n \rightarrow t$  and  $Fx_n \rightarrow \{t\}$  for some  $t \in X$ .

PROPOSITION 3. [4] *Let  $(X, d)$  be a complete metric space. Suppose  $S : X \rightarrow X$ ,  $F : X \rightarrow B(X)$  and  $S$  and  $F$  are compatible. If  $\{Su\} = Fu$  for some  $u \in X$ , then  $FSu = SFu$ .*

## 2. Fixed point theorem

Let  $(X, d)$  be a metric space. Let  $\{S_r\}$  be a sequence of self maps on  $X$  and  $\{F_r\}$  be a sequence of maps on  $X$  into  $B(X)$  satisfying

$$(2.1) \quad F_r(X) \subseteq S_r(X).$$

We define a sequence of points  $\{x_n\}$  as follows. For  $x_0 \in X$  arbitrary, let  $x_1 \in X$ , guaranteed by (2.1), be such that  $S_r x_1 \in F_r x_0$ . Having defined  $x_n \in X$ , let  $x_{n+1} \in X$  be such that  $S_r x_{n+1} \in F_r x_n$ .

Letting  $F_r x_n = Y_n^r$  we denote by  $O(Y_k^r; n)$  the family of sets  $\{Y_k^r, Y_{k+1}^r, \dots, Y_{k+n}^r\}$ . Let us assume that  $S_r$  and  $F_r$  satisfy the following conditions for every  $x, y$  in  $X$

$$(2.2) \quad \delta(F_r x, F_r y) \leq h \max\{d(S_r x, S_r y), \delta(S_r x, F_r x), \delta(S_r y, F_r y), \\ \delta(S_r x, F_r y), \delta(S_r y, F_r x)\},$$

where  $0 < h < 1$  and for  $r \neq p$ ;

$$(2.3) \quad \delta(F_r x, F_p y) \leq \psi(\max\{d(S_r x, S_p y), \delta(S_r x, F_p y), \delta(S_p y, F_r x)\})$$

where  $\psi : [0, \infty) \rightarrow [0, \infty)$ , is nondecreasing, right continuous and satisfies  $\psi(t) < t$  for  $t > 0$ . We begin with some results about  $\delta(O(Y_k^r; n))$ , the diameter of  $O(Y_k^r; n)$  in the form lemmas. We can prove the following lemmas with the proof techniques of Das and Naik [1].

LEMMA 4. For  $k \geq 0$  and  $n \in N$  suppose that  $\delta(O(Y_k^r; n)) > 0$ . Then  $\delta(O(Y_k^r; n)) = \delta(Y_k^r, Y_j^r)$ , where  $j$  is such that  $k < j \leq k + n$ . Also for  $k \geq 1$

$$(2.4) \quad \delta(O(Y_k^r; n)) \leq h\delta(O(Y_{k-1}^r; n+1)).$$

Proof. For  $i, j$  such that  $1 \leq i < j$ ,

$$\begin{aligned} \delta(Y_i^r, Y_j^r) &= \delta(F_r x_i, F_r x_j) \\ &\leq h \max\{d(S_r x_i, S_r x_j), \delta(S_r x_i, F_r x_i), \delta(S_r x_j, F_r x_j), \\ &\quad \delta(S_r x_i, F_r x_j), \delta(S_r x_j, F_r x_i)\} \\ &\leq h \max\{\delta(F_r x_{i-1}, F_r x_{j-1}), \delta(F_r x_{i-1}, F_r x_i), \delta(F_r x_{j-1}, F_r x_j), \\ &\quad \delta(F_r x_{i-1}, F_r x_j), \delta(F_r x_{j-1}, F_r x_i)\} \\ &= h \max\{\delta(Y_{i-1}^r, Y_{j-1}^r), \delta(Y_{i-1}^r, Y_i^r), \delta(Y_{j-1}^r, Y_j^r), \\ &\quad \delta(Y_{i-1}^r, Y_j^r), \delta(Y_{j-1}^r, Y_i^r)\}. \end{aligned}$$

Thus

$$(2.5) \quad \delta(Y_i^r, Y_j^r) \leq h\delta(O(Y_{i-1}^r; j-i+1)).$$

Now  $\delta(O(Y_k^r; n)) = \delta(Y_i^r, Y_j^r)$ , for some  $i, j$  satisfying  $k \leq i < j \leq k + n$ , in view of the fact that the supremum of a finite number of distances is taken.

If  $i > k$ , then by (2.5)

$$\delta(O(Y_k^r; n)) \leq h\delta(O(Y_{i-1}^r; j-i+1))$$

with  $i-1 \geq k$  and  $j \leq k+n$ , whence

$$\delta(O(Y_k^r; n)) \leq h\delta(O(Y_k^r; n)),$$

a contradiction. This proves the first assertion.

Moreover,

$$\delta(O(Y_k^r; n)) = \delta(Y_k^r, Y_j^r) \leq h\delta(O(Y_{k-1}^r; j-k+1)) \leq h\delta(O(Y_{k-1}^r; n+1)).$$

LEMMA 5. Under the hypotheses of Lemma 4 we have

$$(2.6) \quad \delta(O(Y_k^r; n)) \leq \frac{h^k}{1-h} \delta(Y_0^r, Y_1^r).$$

Proof.

$$\begin{aligned} \delta(O(Y_s^r; m)) &= \delta(Y_s^r, Y_j^r) \\ &\leq \delta(Y_s^r, Y_{s+1}^r) + \delta(Y_{s+1}^r, Y_j^r) \\ &\leq \delta(Y_s^r, Y_{s+1}^r) + \delta(O(Y_{s+1}^r; m-1)), \end{aligned}$$

since  $j \leq s+m$ . Thus

$$\delta(O(Y_s^r; m)) \leq \delta(Y_s^r, Y_{s+1}^r) + h\delta(O(Y_s^r; m)),$$

in view of (2.5). This leads to

$$(2.7) \quad \delta(O(Y_s^r; m)) \leq \frac{1}{1-h} \delta(Y_s^r, Y_{s+1}^r).$$

By repeated application of (2.4) we have

$$\delta(O(Y_k^r; n)) \leq h^k \delta(O(Y_0^r; n+k)),$$

whence (2.6) follows in view of (2.7) with  $s = 0$ ,  $m = n+k$ .

**THEOREM 6.** *Let  $(X, d)$  be a complete metric space. Let sequences of maps  $S_r : X \rightarrow X$  and  $F_r : X \rightarrow B(X)$  satisfy (2.1), (2.2) and (2.3). Assume that:*

- a)  $F_r$  and  $S_r$  commute at the coincidence points,
- b)  $F_r$  and  $S_r$  are compatible,
- c)  $F_r$  or  $S_r$  is continuous.

*Then  $F_r$  and  $S_r$  have unique common fixed point  $z$  in  $X$ . Furthermore,  $F_r z = \{z\}$ .*

**Proof.** If for some  $n$  and  $k$ ,  $\delta(O(Y_k^r; n)) = 0$  we have

$$d(S_r x_{k+1}, S_r x_{k+2}) \leq \delta(F_r x_k, F_r x_{k+1}) = \delta(Y_k^r, Y_{k+1}^r) \leq \delta(O(Y_k^r; n)) = 0$$

and so  $S_r x_{k+1} = S_r x_{k+2} = F_r x_k = F_r x_{k+1} = \{y_r\}$ . Since  $F_r$  and  $S_r$  commute at the coincidence points and using inequality (2.2) then we have

$$\begin{aligned} \delta(F_r y_r, y_r) &\leq \delta(F_r S_r x_{k+1}, F_r x_{k+1}) \\ &\leq h \max\{d(S_r S_r x_{k+1}, S_r x_{k+1}), \delta(S_r S_r x_{k+1}, F_r S_r x_{k+1}), \delta(S_r x_{k+1}, F_r x_{k+1}), \\ &\quad \delta(S_r S_r x_{k+1}, F_r x_{k+1}), \delta(S_r x_{k+1}, F_r S_r x_{k+1})\} \\ &\leq h \max\{\delta(S_r F_r x_{k+1}, y_r), \delta(S_r F_r x_{k+1}, F_r S_r x_{k+1}), 0, \\ &\quad \delta(S_r F_r x_{k+1}, y_r), \delta(y_r, F_r y_r)\} \\ &\leq h \max\{\delta(F_r S_r x_{k+1}, y_r), \delta(S_r F_r x_{k+1}, S_r F_r x_{k+1}), 0, \\ &\quad \delta(F_r S_r x_{k+1}, y_r), \delta(y_r, F_r y_r)\} \\ &= h \delta(y_r, F_r y_r). \end{aligned}$$

This is possible only if  $\{y_r\} = F_r y_r$ , and therefore  $y_r$  is a fixed point of  $F_r$ . Also

$$d(y_r, S_r y_r) = \delta(y_r, S_r F_r x_{k+1}) = \delta(y_r, F_r S_r x_{k+1}) = \delta(y_r, F_r y_r) = 0.$$

In the present case, and so  $y_r$  is a fixed point of  $S_r$ , otherwise  $\delta(O(Y_k^r; n)) > 0$ . Now, passing to the general case, given  $\varepsilon > 0$ , let  $n_0 \in N$  be such that  $h^{n_0} \delta(Y_0^r, Y_1^r) < (1-h)\varepsilon$ . Thus for  $m > n \geq n_0$ ,

$$d(S_r x_{m+1}, S_r x_{n+1}) \leq \delta(Y_m^r, Y_n^r) \leq \delta(O(Y_{n_0}^r; m-n_0)) < \varepsilon,$$

in view of Lemma 5 and the choice of  $n_0$ . Hence  $\{S_r x_n\}$  is a Cauchy sequence in a complete metric space and has a limit, say  $\{z_r\}$ . Using (2.2) we proceed as follows

$$\begin{aligned}
\lim_{n \rightarrow \infty} \delta(F_r x_n, z_r) &= \lim_{n \rightarrow \infty} \delta(F_r x_n, S_r x_{n+1}) \leq \lim_{n \rightarrow \infty} \delta(F_r x_n, F_r x_n) \\
&\leq \lim_{n \rightarrow \infty} (h \max\{d(S_r x_n, S_r x_n), \delta(S_r x_n, F_r x_n), \\
&\quad \delta(S_r x_n, F_r x_n), \delta(S_r x_n, F_r x_n), \delta(S_r x_n, F_r x_n)\}) \\
&= h \lim_{n \rightarrow \infty} \delta(F_r x_n, z_r)
\end{aligned}$$

since  $0 < h < 1$ ,  $\lim_{n \rightarrow \infty} \delta(F_r x_n, z_r) = 0$ . From Lemma 2, the sequence of sets  $\{F_r x_n\}$  converges to the set  $\{z_r\}$ . Consequently, the compatibility implies that  $\delta(F_r S_r x_n, S_r F_r x_n) \rightarrow 0$  as  $n \rightarrow \infty$ .

Now we assume that  $F_r$  is a continuous in  $X$ . Then  $\{F_r S_r x_n\}$  converges to the set  $\{F_r z_r\}$  and with the use of (2.2), we have

$$\begin{aligned}
&\delta(F_r S_r x_{n+1}, F_r x_n) \\
&\leq h \max\{d(S_r S_r x_{n+1}, S_r x_n), \delta(S_r S_r x_{n+1}, F_r S_r x_{n+1}), \delta(S_r x_n, F_r x_n), \\
&\quad \delta(S_r S_r x_{n+1}, F_r x_n), \delta(S_r x_n, F_r S_r x_{n+1})\} \\
&\leq h \max\{\delta(S_r F_r x_n, S_r x_n), \delta(S_r F_r x_n, F_r S_r x_{n+1}), \delta(S_r x_n, F_r x_n), \\
&\quad \delta(S_r F_r x_n, F_r x_n), \delta(S_r x_n, F_r S_r x_{n+1})\} \\
&\leq h \max\{\delta(S_r F_r x_n, F_r S_r x_n) + \delta(F_r S_r x_n, F_r x_n) + \delta(F_r x_n, S_r x_n), \\
&\quad \delta(S_r F_r x_n, F_r S_r x_n) + \delta(F_r S_r x_n, F_r S_r x_{n+1}), \delta(S_r x_n, F_r x_{n+1})\},
\end{aligned}$$

since  $S_r S_r x_{n+1}$  is in  $S_r F_r x_n$ . Letting  $n \rightarrow \infty$ , using Lemma 1 and the compatibility, we obtain

$$(2.8) \quad \delta(F_r z_r, z_r) \leq h \max\{\delta(F_r z_r, z_r), \delta(F_r z_r, F_r z_r)\}.$$

But again using (2.2), we deduce that

$$\begin{aligned}
&\delta(F_r S_r x_{n+1}, F_r S_r x_{n+1}) \\
&\leq h \max\{d(S_r S_r x_{n+1}, S_r S_r x_{n+1}), \delta(S_r S_r x_{n+1}, F_r S_r x_{n+1})\} \\
&\leq h \max\{\delta(S_r F_r x_n, F_r S_r x_n) + \delta(F_r S_r x_n, F_r S_r x_{n+1})\},
\end{aligned}$$

which implies, as  $n \rightarrow \infty$ , by the compatibility that

$$\delta(F_r z_r, F_r z_r) \leq h \delta(F_r z_r, F_r z_r).$$

Hence  $\delta(F_r z_r, F_r z_r) = 0$  since  $h < 1$ . From (2.8), it follows that  $F_r z_r = \{z_r\}$ . Since (2.1) holds, there exists a point  $w_r$  in  $X$  such that  $S_r w_r = z_r$  and using inequality (2.2), we have

$$\begin{aligned}
\delta(F_r x_n, F_r w_r) &\leq h \max\{d(S_r x_n, z_r), \delta(S_r x_n, F_r x_n), \\
&\quad \delta(z_r, F_r w_r), \delta(S_r x_n, F_r w_r), \delta(z_r, F_r x_n)\},
\end{aligned}$$

which implies, as  $n \rightarrow \infty$ , that

$$\delta(z_r, F_r w_r) \leq h \delta(z_r, F_r w_r).$$

Thus  $\{z_r\} = F_r w_r$  and by Proposition 3 we have

$$d(F_r z_r, S_r z_r) = \delta(F_r S_r w_r, S_r F_r w_r) = 0.$$

It follows that  $\{z_r\} = F_r z_r = \{S_r z_r\}$  and thus  $z_r$  is also a fixed point of  $S_r$ .

Now we assume the continuity of  $S_r$  instead of  $F_r$ . Then the sequence  $\{S_r S_r x_n\}$  converges to the point  $S_r z_r$  and the sequence of the sets  $\{S_r F_r x_n\}$  converges to the set  $\{S_r z_r\}$ .

We have

$$\delta(F_r S_r x_n, S_r z_r) \leq \delta(F_r S_r x_n, S_r F_r x_n) + \delta(S_r F_r x_n, S_r z_r)$$

and, as  $n \rightarrow \infty$ , we deduce from the compatibility and Lemma 2 that the sequence of sets  $\{F_r S_r x_n\}$  also converges to the set  $\{S_r z_r\}$ .

Using the inequality (2.2) and since  $S_r S_r x_n$  is in  $S_r F_r x_n$ , we get

$$\begin{aligned} d(S_r S_r x_{n+1}, S_r x_{n+1}) \\ \leq \delta(S_r F_r x_n, F_r x_n) \\ \leq \delta(S_r F_r x_n, F_r S_r x_n) + \delta(F_r S_r x_n, F_r x_n) \\ \leq \delta(S_r F_r x_n, F_r S_r x_n) + h \max\{d(S_r S_r x_n, S_r x_n), \delta(S_r S_r x_n, F_r S_r x_n), \\ \delta(S_r x_n, F_r x_n), \delta(S_r S_r x_n, F_r x_n), \delta(S_r x_n, F_r S_r x_n)\}. \end{aligned}$$

As  $n \rightarrow \infty$ , it follows from the compatibility that

$$d(S_r z_r, z_r) \leq h d(S_r z_r, z_r),$$

which implies  $S_r z_r = z_r$ . Using again the inequality (2.2), we have

$$\begin{aligned} \delta(F_r z_r, F_r x_n) \leq h \max\{d(z_r, S_r x_n), \delta(z_r, F_r z_r), \delta(S_r x_n, F_r x_n), \\ \delta(z_r, F_r x_n), \delta(S_r x_n, F_r z_r)\} \end{aligned}$$

and this implies, as  $n \rightarrow \infty$ , that

$$\delta(z_r, F_r z_r) \leq h \delta(z_r, F_r z_r).$$

Then  $\{z_r\} = F_r z_r$  and hence  $z_r$  is also fixed point of  $F_r$ . In any case,  $z_r$  is a common fixed point of  $F_r$  and  $S_r$ . Suppose that  $F_r$  and  $S_r$  have another fixed point  $z'_r$ . Using the inequality (2.2), we have

$$d(z_r, z'_r) = \delta(F_r z_r, F_r z'_r) \leq h d(z_r, z'_r).$$

This means that  $z_r = z'_r$  and therefore  $z_r$  is the unique common fixed point of  $F_r$  and  $S_r$ .

Now for  $r \neq p$  we assume that  $z_r \neq z_p$ . Using the inequality (2.3) we have

$$\begin{aligned} d(z_r, z_p) &= \delta(F_r z_r, F_p z_p) \\ &\leq \psi(\max\{\delta(S_r z_r, S_p z_p), \delta(S_r z_r, F_p z_p), \delta(S_p z_p, F_r z_r)\}) \\ &= \psi(d(z_r, z_p)), \end{aligned}$$

which implies that  $d(z_r, z_p) = 0$ . This means that for every  $r \in N$ ,  $z_r = z$ . Thus  $z$  is the unique common fixed point of  $F_r$  and  $S_r$ .

Now, we give an example for Theorem 6.

EXAMPLE 1. Let  $X = [0, \infty)$  with the usual metric. Let  $S_r : X \rightarrow X$  and  $F_r : X \rightarrow B(X)$  be defined by  $S_r x = \frac{rx}{2}$  and  $F_r x = [0, \frac{rx}{3}]$  for  $x$  in  $X$ .  $S_r$  and  $F_r$  are continuous and  $F_r(X) = S_r(X) = X$ . If  $S_r x_n \rightarrow 0$  and  $F_r x_n \rightarrow 0$ , then  $\delta(S_r F_r x_n, F_r S_r x_n) \rightarrow 0$  and so  $F_r$  and  $S_r$  are compatible. 0 is the unique coincidence point of  $F_r$  and  $S_r$  and so  $F_r, S_r$  commute at 0. Also for  $x \geq y$

$$\delta(F_r x, F_r y) = \frac{rx}{3} = \frac{2}{3} \frac{rx}{2} = \frac{2}{3} \delta(S_r x, F_r x).$$

Thus we have condition (2.2) for  $\frac{2}{3} \leq h < 1$  and for  $r \neq p$

$$\delta(F_r x, F_p y) = \frac{rx}{3} \text{ or } \frac{py}{3}.$$

If  $\frac{rx}{3} \geq \frac{py}{3}$  we have

$$\delta(S_r x, F_p y) = \frac{rx}{2}$$

and if  $\frac{rx}{3} < \frac{py}{3}$  we have

$$\delta(S_p y, F_r x) = \frac{py}{2}.$$

Thus for  $\psi(t) = \frac{5t}{6}$  we have the condition (2.3). Thus  $F_r$  and  $S_r$  satisfy the inequality (2.2) and (2.3). Then the sequences of maps  $F_r$  and  $S_r$  have a unique common fixed point (0) in  $X$ .

REMARK 1. By setting  $F_r = F$  and  $S_r = I$  in Theorem 6, we get Theorem 3.2 of Jungck and Rhoades [4].

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D. Türkoglu

DEPARTMENT OF MATHEMATICS,  
FACULTY OF SCIENCE AND ARTS,  
UNIVERSITY OF GAZI,  
06500-TEKNIKOKULLAR, ANKARA, TURKEY  
E-mail: dturkoglu@gazi.edu.tr

I. Altun

DEPARTMENT OF MATHEMATICS,  
FACULTY OF SCIENCE AND ARTS,  
UNIVERSITY OF KIRIKKALE,  
71450-YAHŞIHAN KIRIKKALE, TURKEY  
E-mail: ıaltun@kku.edu.tr

B. Fisher

DEPARTMENT OF MATHEMATICS  
LEICESTER UNIVERSITY  
LEICESTER, LE1 7RH, ENGLAND

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