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## A COMMON FIXED POINT THEOREM FOR COMPATIBLE MAPPINGS

### 1. Introduction

In [1], the concept of compatible mappings was introduced as a generalization of commuting mappings. The utility of compatibility in the context of fixed point theory was demonstrated by extending a theorem of Park and Bae [9]. Popa [8] proved a common fixed point for four self-mappings of a complete metric space using the concept of weak commutativity of Sessa [10]. His result improves and extends the recent results of Xieping Ding [12]. In this paper we extend the result of Popa [8] by employing compatible mappings in lieu of weakly commuting mappings.

The following definition is given in [1]:

DEFINITION 1.1. Let  $f, g$  be mappings from a metric space  $(X, d)$  into itself. Then  $f$  and  $g$  are said to be *compatible* if  $\lim_{n \rightarrow \infty} d(fgx_n, gfx_n) = 0$  whenever  $\{x_n\}$  is a sequence in  $X$  such that

$$\lim_{n \rightarrow \infty} fx_n = \lim_{n \rightarrow \infty} gx_n = z \quad \text{for some } z \text{ in } X.$$

Thus, if  $d(fgx_n, gfx_n) \rightarrow 0$  as  $d(fx_n, gx_n) \rightarrow 0$ , then  $f$  and  $g$  are compatible.

S. Sessa [10] generalized commuting mappings by calling mappings  $A$  and  $B$  from a metric space  $(X, d)$  into itself a *weakly commuting pair* if  $d(ABx, BAx) \leq d(Ax, Bx)$  for all  $x \in X$ .

Clearly *commuting mappings* are *weakly commuting* and *weakly commuting pairs* are *compatible*, examples in [1], [10] show that neither converse is

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true. Several articles already in print, demonstrate that results can be generalized by using compatibility in lieu of commutativity or weak commutativity (see for example [1]–[5] and [11]).

For our main theorem we need the following Lemma 1.1, which was proved by G.Jungck [1].

LEMMA 1.1. *Let  $S$  and  $T$  be compatible mappings from a metric space  $(X, d)$  into itself. Suppose that*

$$\lim_{n \rightarrow \infty} Sx_n = \lim_{n \rightarrow \infty} Tx_n = t$$

*for some  $t \in X$ . Then  $\lim_{n \rightarrow \infty} TSx_n = St$  if  $S$  is continuous.*

Throughout this paper, the function  $\phi : [0, \infty)^5 \rightarrow [0, \infty)$  satisfies the following conditions:

(i)  $\phi$  is nondecreasing and upper semicontinuous in each coordinate variables,

(ii) For each  $t > 0$

$$\Psi(t) = \max\{\phi(t, 0, 0, t, t), \phi(t, t, t, 2t, 0), \phi(t, t, t, 0, 2t)\} < t.$$

LEMMA 1.2 [7]. *Suppose  $\Psi : [0, \infty) \rightarrow [0, \infty)$  is nondecreasing and upper semicontinuous from the right. If  $\Psi(t) < t$  for every  $t > 0$ , then  $\lim_{n \rightarrow \infty} \Psi^n(t) = 0$ , where  $\Psi^n(t)$  denotes the composition of  $\Psi(t)$  with  $n$ -times.*

Now, let  $S, T, I$  and  $J$  be mappings from a metric space  $(X, d)$  into itself satisfying the following conditions

$$(1.1) \quad SX \supset JX \quad \text{and} \quad TX \supset IX,$$

$$(1.2) \quad d(Sx, Ty) \leq \phi(d(Ix, Jy), d(Ix, Sx), d(Jy, Ty), d(Ix, Ty), d(Jy, Sx)),$$

for all  $x, y \in X$ , with  $\phi$  satisfying (i)–(iii). Then for an arbitrary point  $x_0 \in X$ , by the assumption (1.1), we may choose a point  $x_1 \in X$  such that  $y_1 = Tx_1 = Ix_0$ . For this point  $x_1$  there exists an  $x_2 \in X$  such that  $y_2 = Sx_2 = Jx_1$ . Continuing in this manner we get sequences  $\{x_n\}$  and  $\{y_n\}$  such that

$$(1.3) \quad y_{2n} = Sx_{2n} = Jx_{n-1}; \quad y_{2n+1} = Tx_{2n+1} = Ix_{2n}.$$

LEMMA 1.3. *Let  $S, T, I$  and  $J$  be mappings from a metric space  $(X, d)$  into itself satisfying the conditions (1.1) and (1.2). Then  $\{y_n\}$  defined by (1.3) is a Cauchy sequence in  $X$ .*

Proof. By (1.2) and (1.3), we have

$$\begin{aligned}
 d(y_{2n+1}, y_{2n+2}) &= d(Tx_{2n+1}, Sx_{2n+2}) \\
 &\leq \phi(d(Ix_{2n+2}, Jx_{2n+1}), d(Ix_{2n+2}, Sx_{2n+2}), d(Jx_{2n+1}, Tx_{2n+1}), \\
 &\quad d(Ix_{2n+2}, Tx_{2n+1}), d(Jx_{2n+1}, Sx_{2n+2})) \\
 &\leq \phi(d(y_{2n}, y_{2n+1}), d(y_{2n}, y_{2n+2}), d(y_{2n}, y_{2n+1}), \\
 &\quad d(y_{2n+1}, y_{2n+1}), d(y_{2n}, y_{2n+2})) \\
 &\leq \phi(d(y_{2n}, y_{2n+1}), d(y_{2n+1}, y_{2n+2}), d(y_{2n}, y_{2n+1}), \\
 &\quad 0, d(y_{2n}, y_{2n+1}) + d(y_{2n+1}, y_{2n+2})).
 \end{aligned}$$

If in the above inequality would be  $d(y_{2n+1}, y_{2n+2}) > d(y_{2n}, y_{2n+1})$ , then we would have

$$\begin{aligned}
 &d(y_{2n+1}, y_{2n+2}) \\
 &\leq \phi(d(y_{2n+1}, y_{2n+2}), d(y_{2n+1}, y_{2n+2}), d(y_{2n+1}, y_{2n+2}), 0, 2d(y_{2n+1}, y_{2n+2})) \\
 &\leq \Psi(d(y_{2n+1}, y_{2n+2})) < d(y_{2n+1}, y_{2n+2})
 \end{aligned}$$

which is a contradiction. Thus,

$$\begin{aligned}
 (1.4) \quad &d(y_{2n+1}, y_{2n+2}) \\
 &\leq \phi(d(y_{2n}, y_{2n+1}), d(y_{2n}, y_{2n+1}), d(y_{2n}, y_{2n+1}), 0, 2d(y_{2n}, y_{2n+1})) \\
 &\leq \Psi(d(y_{2n}, y_{2n+1})).
 \end{aligned}$$

Similarly, we have

$$(1.5) \quad d(y_{2n+2}, y_{2n+3}) \leq \Psi(d(y_{2n+1}, y_{2n+2})).$$

From (1.4) and (1.5) it follows that

$$(1.6) \quad d_n = d(y_n, y_{n+1}) \leq \Psi(d(y_{n-1}, y_n)) \leq \dots \leq \Psi^{n-1}(d(y_1, y_2)).$$

By (1.6) and Lemma 1.2 we obtain

$$(1.7) \quad \lim_{n \rightarrow \infty} d_n = 0.$$

In order to show that  $\{y_n\}$  is a Cauchy sequence, it is sufficient to show that  $\{y_{2n}\}$  has this property. Suppose that  $\{y_{2n}\}$  is not a Cauchy sequence. Then there is an  $\epsilon > 0$  such that, for each even integer  $2k$ , there exist even integers  $2m(k)$  and  $2n(k)$  such that

$$(1.8) \quad d(y_{2m(k)}, y_{2n(k)}) > \epsilon$$

for  $2m(k) > 2n(k) \geq 2k$ . For each even integer  $2k$ , let  $2m(k)$  be the least even integer exceeding  $2n(k)$  satisfying (1.8), that is

$$(1.9) \quad d(y_{2n(k)}, y_{2m(k)-2}) < \epsilon \quad \text{and} \quad d(y_{2n(k)}, y_{2m(k)}) > \epsilon.$$

Then for each even integer  $2k$ ,

$$\epsilon < d(y_{2n(k)}, y_{2m(k)}) \leq d(y_{2n(k)}, y_{2m(k)-2}) + d_{2m(k)-2} + d_{2m(k)-1}.$$

It follows from (1.7) and (1.8) that

$$(1.10) \quad \lim_{n \rightarrow \infty} d(y_{2n(k)}, y_{2m(k)}) = \epsilon.$$

By the triangle inequality,

$$|d(y_{2n(k)}, y_{2m(k)-1}) - d(y_{2n(k)}, y_{2m(k)})| \leq d_{2m(k)-1},$$

and

$$|d(y_{2n(k)+1}, y_{2m(k)-1}) - d(y_{2n(k)}, y_{2m(k)})| \leq d_{2m(k)-1} + d_{2n(k)}.$$

From (1.2) and (1.3), we have

$$\begin{aligned} d(y_{2n(k)}, y_{2m(k)}) &\leq d_{2n(k)} + d(y_{2n(k)+1}, y_{2m(k)}) \\ &\leq d_{2n(k)} + d(Sx_{2n(k)}, Tx_{2m(k)-1}) \\ &\leq d_{2n(k)} + \phi(d(y_{2n(k)}, y_{2m(k)-1}), d_{2n(k)}, d_{2m(k)-1}, \\ &\quad d(y_{2n(k)}, y_{2m(k)-1}), d(y_{2n(k)-1}, y_{2m(k)+1})). \end{aligned}$$

Since  $\phi$  is upper semicontinuous, then

$$\epsilon \leq \phi(\epsilon, 0, 0, \epsilon, \epsilon) < \epsilon \quad \text{as } k \rightarrow \infty,$$

which is a contradiction. Hence  $\{y_n\}$  is a Cauchy sequence.

## 2. A fixed point theorem

In a recent paper [8], the following theorem is proved:

**THEOREM 2.1.** *Let  $S$ ,  $T$ ,  $I$  and  $J$  be four self-mappings of  $X$  such that*

$$TX = IX \quad \text{and} \quad SX = JX,$$

$$d(Sx, Ty) \leq \phi(d(Ix, Jy), d(Ix, Sx), d(Jy, Ty), d(Ix, Ty), d(Jy, Sx)).$$

for all  $x, y \in X$ .

If one of  $S$ ,  $T$ ,  $I$  and  $J$  is continuous and  $S$  and  $T$  weakly commute respectively with  $I$  and  $J$ , then  $S$ ,  $T$ ,  $I$ ,  $J$  have a common fixed point  $z$ . Furthermore  $z$  is the unique common fixed point of  $S$  and  $I$  and of  $T$  and  $J$ .

Now, we prove a common fixed point theorem which improves and extends Theorem 2.1 for compatible mappings. Also our theorem improves Theorem 2.2 from [4].

**THEOREM 2.2.** *Let  $S$ ,  $T$ ,  $I$  and  $J$  be four self-mappings of  $X$  satisfying the conditions (1.1) and (1.2). If one of  $S$ ,  $T$ ,  $I$  and  $J$  is continuous and  $(S, I)$ ,  $(T, J)$  are compatible pairs of  $X$ , then  $S$ ,  $T$ ,  $I$  and  $J$  have a common fixed point  $z$ . Furthermore  $z$  is the unique common fixed point of  $S$  and  $I$  and of  $T$  and  $J$ .*

Proof. By Lemma 1.3,  $\{y_n\}$  defined by (1.3) is a Cauchy sequence and so it converges to a point  $z$  in  $X$ . Consequently, the subsequences

$$\{Sx_{2n}\}, \quad \{Jx_{2n+1}\}, \quad \{Tx_{2n+1}\}, \quad \text{and} \quad \{Ix_{2n}\}$$

converge to  $z$ .

Let us first of all suppose that  $I$  is continuous. Since  $(S, I)$  is compatible on  $X$ , then Lemma 1.1 gives

$$I^2x_{2n} \longrightarrow Iz \quad \text{and} \quad SIx_{2n} \longrightarrow Iz \quad \text{as} \quad n \longrightarrow \infty.$$

By (1.2), we obtain

$$\begin{aligned} d(SIx_{2n}, Tx_{2n+1}) &\leq \phi(d(I^2x_{2n}, Jx_{2n+1}), d(I^2x_{2n}, SIx_{2n}), \\ &\quad d(Jx_{2n+1}, Tx_{2n+1}), d(I^2x_{2n}, Tx_{2n+1}), d(Jx_{2n+1}, SIx_{2n})). \end{aligned}$$

Letting  $n \longrightarrow \infty$ , we have

$$d(Iz, z) \leq \phi(d(Iz, z), 0, 0, d(Iz, z), d(Iz, z)),$$

so that  $Iz = z$ .

By (1.2), we also have

$$\begin{aligned} d(Sz, Tx_{2n+1}) &\leq \phi(d(Iz, Jx_{2n+1}), d(Iz, Sz), \\ &\quad d(Jx_{2n+1}, Tx_{2n+1}), d(Iz, Tx_{2n+1}), d(Jx_{2n+1}, Sz)). \end{aligned}$$

Letting  $n \longrightarrow \infty$ , we have

$$d(Sz, z) \leq \phi(0, d(Sz, z), 0, 0, d(z, Sz)),$$

so that  $Sz = z$ . Since  $SX = JX$ ,  $z \in JX$  and hence there exists a point  $u$  in  $X$  such that  $z = Sz = Ju$ ,

$$\begin{aligned} d(z, Tu) &= d(Sz, Tu) \\ &\leq \phi(d(Iz, Ju), d(Iz, Sz), d(Ju, Tu), d(Iz, Tu), d(Ju, Sz)) \\ &\leq \phi(0, 0, d(z, Tu), d(z, Tu), 0). \end{aligned}$$

which implies that  $Tu = z$ . Since  $(T, J)$  is compatible on  $X$  and  $Tu = Ju = z$ , then  $d(JTu, TJu) = 0$  and hence

$$Tz = TJu = JTu = Jz.$$

Moreover, by (1.2), we obtain

$$d(z, Tz) = d(Sz, Tz) \leq \phi(d(z, Tz), 0, 0, d(z, Tz), d(z, Tz)),$$

so that  $Tz = z$ . Therefore  $z$  is a common fixed point of  $S$ ,  $T$ ,  $J$  and  $I$ . Similarly we can complete the proof when  $J$  is continuous.

Next, suppose that  $S$  is continuous. Since  $(S, I)$  is continuous on  $X$ , it follows from Lemma 1.1 that

$$S^2x_{2n} \longrightarrow Sz, \quad ISx_{2n} \longrightarrow Sz \quad \text{as} \quad n \longrightarrow \infty.$$

By (1.2), we have

$$d(S^2x_{2n}, Tx_{2n+1}) \leq \phi(d(ISx_{2n}, Jx_{2n+1}), d(ISx_{2n}, S^2x_{2n}), \\ d(Jx_{2n+1}, Tx_{2n+1}), d(ISx_{2n}, Tx_{2n+1}), d(Jx_{2n+1}, S^2x_{2n})).$$

Letting  $n \rightarrow \infty$ , we have

$$d(Sz, z) \leq \phi(d(Sz, z), 0, 0, d(Sz, z), d(Sz, z)),$$

so that  $Sz = z$ . Hence there exists a point  $v$  in  $X$  such that  $z = Sz = Jv$ .

$$d(S^2x_{2n}, Tv) \leq \phi(d(ISx_{2n}, Jv), d(ISx_{2n}, S^2x_{2n}), d(Jv, Tv), \\ d(ISx_{2n}, Tv), d(Jv, S^2x_{2n})).$$

By letting  $n \rightarrow \infty$ , we have

$$d(z, Tv) \leq \phi(0, 0, d(z, Tv), d(z, Tv), 0),$$

so that  $Tv = z$ . Since  $(T, J)$  is compatible on  $X$  and

$$Tv = Jv = z, \quad d(JTv, TJv) = 0$$

and hence

$$Tz = TJv = JTv = Jz, \\ d(Sx_{2n}, Tz) \leq \phi(d(Ix_{2n}, Jz), d(Ix_{2n}, Sx_{2n}), d(Jz, Tz), \\ d(Ix_{2n}, Tz), d(Jz, Sx_{2n})).$$

By letting  $n \rightarrow \infty$ , we have

$$d(z, Tz) \leq \phi(d(z, Tz), 0, 0, d(z, Tz), d(z, Tz)),$$

so that  $Tz = z$ . Since  $TX = IX$ , there exists a point  $w$  in  $X$  such that  $z = Tz = Iw$ .

By (1.2), we have

$$d(Sw, z) = d(Sw, Tz) \leq \phi(0, d(Sw, z), 0, 0, d(Sw, z)),$$

so that  $Iw = Sw$ ,  $d(ISw, SIw) = 0$  and hence

$$Iz = ISw = SIw = Sz.$$

Therefore  $z$  is a common fixed point of  $S$ ,  $T$ ,  $I$  and  $J$ . Similarly we can complete the proof when  $T$  is continuous.

Finally we prove the uniqueness of  $z$ . Indeed let  $z$  and  $w$ , are common fixed points of  $S$ ,  $T$ ,  $I$  and  $J$ . Therefore

$$d(z, w) = d(Sz, Tw) \leq \phi(d(z, w), 0, 0, d(z, w), d(z, w)),$$

which implies that  $z = w$ .

In conclusion, we wish to present an example which shows that our Theorem 2.2 is indeed a generalization of Theorem 2.1.

EXAMPLE. Let  $X = [1, \infty)$  with the Euclidean metric  $d$ . Define  $S, T, I$  and  $J : X \rightarrow X$  by

$$\begin{aligned} Sx &= x^2, & Tx &= x^4 \\ Ix &= 2x^4 - 1, & Jx &= 2x^8 - 1, x \geq 1. \end{aligned}$$

Now

$$SX = TX = IX = JX = X$$

and  $S, T, I$  and  $J$  are continuous. Moreover, since

$$\begin{aligned} d(Sx_n, Ix_n) &= |x_n^2 - 2x_n^4 + 1| \rightarrow 0 \quad \text{iff } x_n \rightarrow 1, \\ d(SIx_n, ISx_n) &= |(2x_n^4 - 1)^2 - 2(2x_n^4 - 1)^4 + 1| \rightarrow 0 \quad \text{as } x_n \rightarrow 1. \end{aligned}$$

Thus  $S$  and  $I$  are compatible on  $X$ . Likewise

$$\begin{aligned} d(Tx_n, Jx_n) &= |x_n^4 - 2x_n^8 + 1| \rightarrow 0 \quad \text{iff } x_n \rightarrow 1, \\ d(TJx_n, JTx_n) &= |(2x_n^8 - 1)^4 - 2(x_n^4)^8 + 1| \rightarrow 0 \quad \text{as } x_n \rightarrow 1 \end{aligned}$$

and so  $T$  and  $J$  are compatible on  $X$ .

Take

$$\phi(t_1, t_2, t_3, t_4, t_5) = \frac{t_1}{2}$$

for every  $t_i \in R^5, i=1,2,3,4,5$ .

For any  $x, y \in X$  we have

$$\begin{aligned} d(Sx, Ty) &= |x^2 - y^4| \leq |x^2 - y^4| |x^2 + y^4| \\ &= |x^4 - y^8| = 2 \frac{|x^4 - y^8|}{2} \\ &\leq \phi(d(Ix, Jy), d(Ix, Sx), d(Jy, Ty), d(Ix, Ty), d(Jy, Sx)). \end{aligned}$$

Since  $\phi$  obviously satisfies the conditions (i) and (ii) then all the assumptions of Theorem 2.2 are verified and 1 is the unique common fixed point of  $S, T, I$  and  $J$ .

Note Theorem 2.1 is not applicable even if  $S = T$  and  $I = J$  because  $S$  and  $I$  are not weakly commuting mappings at  $x = 2$ .

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