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SOME FIXED POINT THEOREMS  
 IN TOPOLOGICAL VECTOR SPACES

1. A fixed point theorem for nonself mappings

Let  $A$  be a subset of a sequentially complete Hausdorff locally convex topological vector space  $E$  (over the field  $\mathfrak{R}$ ) with calibration  $\Gamma$ . By the terminology of R.T. Moore [6], a calibration  $\Gamma$  for  $E$  means a collection of continuous seminorms  $p$  on  $E$  which induce the topology of  $E$ . Let  $f, g$  be nonself mappings from  $A$  into  $E$ . Let  $a_p, b_p, c_p, d_p$  and  $e_p$  be nonnegative real numbers such that  $a_p + b_p + c_p + d_p + e_p < 1$  and for any  $x, y$  in  $A$ , and  $p \in \Gamma$

$$(1) \quad p(f(x) - g(y)) \leq a_p p(x - y) + b_p p(x - f(x)) \\ + c_p p(y - g(y)) + d_p p(x - g(y)) + e_p p(y - f(x)).$$

Włodarczyk [9] proved that  $f$  has a unique fixed point if  $f = g$ . In this section, we prove that  $f, g$  have a unique common fixed point if  $b_p = c_p$  and  $d_p = e_p$ . When  $f = g$ , because of  $p(x - y) = p(y - x)$ , one can, without loss of generality, assume  $b_p = c_p$  and  $d_p = e_p$ . So our result generalizes the result of Włodarczyk [9]. Since our Theorem includes Theorem 3.3 of Włodarczyk [9], it also includes the corresponding theorems in: Hardy and Rogers [2], Goebel, Kirk and Shimi [1], Kannan [4], Nova [7] and Wong [10].

**DEFINITION.** Let  $\Gamma_0 \subset \Gamma$ ,  $\Gamma_0 \neq \{0\}$ . A subset  $A$  of  $E$  is said to be of *type*  $\Gamma_0$  with respect to  $x_0 \in A$ , if the inequality  $p(y) \leq p(x)$ , for some  $x \in A - x_0$  and for all  $p \in \Gamma_0$  implies that  $y \in A - x_0$ .

**THEOREM 1.** *Let  $E$  be a sequentially complete Hausdorff locally convex topological vector space with calibration  $\Gamma$ , let  $A$  be a subset of  $E$  and let  $f : A \rightarrow E$ ,  $g : A \rightarrow E$  be two nonself mappings. Assume  $A$  is of type  $\Gamma_0$  ( $\Gamma_0 \subset \Gamma$ ), with respect to  $x_0 \in A$ ,  $f$  and  $g$  satisfy (1), such that  $a_p, b_p, c_p, d_p, e_p$  are non-negative real-valued functions on  $E \times E$  for  $p \in \Gamma$ . If*

$$(i) \quad \gamma \equiv \sup_{x,y \in E} \{a_p(x, y) + b_p(x, y) + c_p(x, y) + 2d_p(x, y)\} < 1; \text{ for } p \in \Gamma.$$

- (ii)  $b_p \equiv c_p, d_p \equiv e_p$  for  $p \in \Gamma$ ,
- (iii)  $f(x_0) - x_0 \in \frac{1-a_p-b_p-c_p-2d_p}{1-c_p-d_p}(A - x_0)$ , for all  $p \in \Gamma_0$ ,
- (iv)  $(g \circ f)(x_0) - x_0 \in \frac{1-a_p-b_p-c_p-2d_p}{1-c_p-d_p}(A - x_0)$  for all  $p \in \Gamma_0$ , where  $a_p, b_p, c_p$  and  $d_p$  are evaluated at  $(x, y)$ .

Then  $x_n \rightarrow u$ , and  $u$  is the fixed point of  $f$  or  $g$  in  $A$ . If both  $f$  and  $g$  have fixed points, then each of  $f, g$  has a unique fixed point and these two fixed points coincide.

**Proof.** Let the sequence  $\{x_n\}$  be defined as follows

$$x_{2n+1} = f(x_{2n}), \quad x_{2n+2} = g(x_{2n+1}), \quad n = 0, 1, 2, \dots$$

We show that  $x_n \in A$ ,  $n \in \mathbb{N}$ . Indeed, since  $A$  is of type  $\Gamma_0$ , the set  $A - x_0$  is balanced and, since  $\frac{1-a_p-b_p-c_p-2d_p}{1-c_p-d_p} < 1$ ,  $p \in \Gamma_0$ , then

$$\begin{aligned} f(x_0) - x_0 &\in \frac{1-a_p-b_p-c_p-2d_p}{1-c_p-d_p}(A - x_0) \subset (A - x_0), \\ g(x_1) - x_0 &\in \frac{1-a_p-b_p-c_p-2d_p}{1-c_p-d_p}(A - x_0) \subset (A - x_0), \end{aligned}$$

for all  $p \in \Gamma_0$ . Consequently,  $f(x_0) = x_1 \in A$ , i.e.,  $x_n \in A$  for  $n = 0, 1$ . Suppose it is true for  $n = k$ . We show that it is true for  $n = k + 1$ .

**CASE I.** For  $x_{2n+1}$ , where  $n = k + 1$ ,

$$(2) \quad p(x_{2(k+1)+1} - x_0) = p(x_{2k+3} - x_0) \leq \sum_{m=0}^{2k+2} p(x_{m+1} - x_m).$$

If  $m$  is even then for all  $p \in \Gamma$ ,

$$\begin{aligned} p(x_{m+1} - x_m) &= p(f(x_m) - g(x_{m-1})) \\ &\leq a_p p(x_m - x_{m-1}) + b_p p(x_m - f(x_m)) + c_p p(x_{m-1} - g(x_{m-1})) \\ &\quad + d_p p(x_m - g(x_{m-1})) + e_p p(x_{m-1} - f(x_m)) \\ &= a_p p(x_m - x_{m-1}) + b_p p(x_m - x_{m+1}) + c_p p(x_{m-1} - x_m) \\ &\quad + d_p p(x_m - x_m) + e_p p(x_{m-1} - x_{m+1}) \\ &\leq (a_p + c_p + e_p)p(x_{m-1} - x_m) + (b_p + e_p)p(x_m - x_{m+1}). \end{aligned}$$

It implies,

$$p(x_{m+1} - x_m) \leq \frac{a_p + c_p + e_p}{1 - b_p - e_p} p(x_m - x_{m-1}).$$

Also,

$$\begin{aligned} p(x_m - x_{m-1}) &= p(f(x_{m-2}) - g(x_{m-1})) \\ &\leq a_p p(x_{m-2} - x_{m-1}) + b_p p(x_{m-2} - f(x_{m-2})) \\ &\quad + c_p p(x_{m-1} - g(x_{m-1})) + d_p p(x_{m-2} - g(x_{m-1})) + e_p p(x_{m-1} - f(x_{m-2})) \end{aligned}$$

$$\begin{aligned}
&= a_p p(x_{m-2} - x_{m-1}) + b_p p(x_{m-2} - x_{m-1}) + c_p p(x_{m-1} - x_m) \\
&\quad + d_p p(x_{m-2} - x_m) + e_p p(x_{m-1} - x_{m-1}) \\
&\leq (a_p + b_p + d_p)p(x_{m-2} - x_{m-1}) + (c_p + d_p)p(x_{m-1} - x_m), \quad \text{for all } p \in \Gamma.
\end{aligned}$$

It further implies,

$$p(x_m - x_{m-1}) \leq \frac{a_p + b_p + d_p}{1 - c_p - d_p} p(x_{m-1} - x_{m-2}).$$

Using (ii), we get,

$$p(x_{m+1} - x_m) \leq \left( \frac{a_p + b_p + d_p}{1 - c_p - d_p} \right)^2 p(x_{m-1} - x_{m-2})$$

for all  $p \in \Gamma$ .

So by induction, we obtain,

$$(3) \quad p(x_{m+1} - x_m) \leq \left( \frac{a_p + b_p + d_p}{1 - c_p - d_p} \right)^m p(x_1 - x_0).$$

Similarly, if  $m$  is odd,

$$p(x_{m+1} - x_m) \leq \left( \frac{a_p + b_p + d_p}{1 - c_p - d_p} \right)^m p(x_1 - x_0).$$

Therefore,

$$\begin{aligned}
p(x_{2(k+1)+1} - x_0) &\leq \sum_{m=0}^{2k+2} p(x_{m+1} - x_m) \\
&\leq \sum_{m=0}^{2k+2} p(x_{m+1} - x_m) \left( \frac{a_p + b_p + d_p}{1 - c_p - d_p} \right)^m p(x_1 - x_0) \\
&= \frac{1 - \left( \frac{a_p + b_p + d_p}{1 - c_p - d_p} \right)^{2k+3}}{1 - \left( \frac{a_p + b_p + d_p}{1 - c_p - d_p} \right)} p(x_1 - x_0) \\
&\leq \frac{1 - c_p - d_p}{1 - a_p - b_p - c_p - 2d_p} p(x_1 - x_0) \quad \text{for all } p \in \Gamma.
\end{aligned}$$

Since  $A$  is of type  $\Gamma_0$  with respect to  $x_0$ , hence

$$x_{2(k+1)+1} - x_0 \in A - x_0 \quad \text{and so} \quad x_{2(k+1)+1} \in A.$$

CASE II. For  $x_{2n+2}$ , where  $n = k + 1$ ,

$$P(x_{2(k+1)+2} - x_0) = p(x_{2k+4} - x_0) \leq \sum_{m=0}^{2k+3} p(x_{m+1} - x_m).$$

Using (3), we get,

$$\begin{aligned} p(x_{2(k+1)+2} - x_0) &\leq \sum_{m=0}^{2k+3} \left( \frac{a_p + b_p + d_p}{1 - c_p - d_p} \right)^m p(x_1 - x_0), \\ &\leq \frac{1 - c_p - d_p}{1 - a_p - b_p - c_p - 2d_p} p(x_1 - x_0), \end{aligned}$$

since  $a_p + b_p + d_p < 1 - c_p - d_p$ .

Since  $A$  is of type  $\Gamma_0$  with respect to  $x_0$ , therefore  $x_{2(k+1)+2} \in A$ . By the induction argument  $x_n \in A$ ,  $(\forall)n \in \mathbb{N}$ .

The inequality (3), implies that  $\{x_n\}$  is a Cauchy sequence. Hence it converges to some point  $u$  in  $E$ . Without loss of generality, we can assume that  $x_{n+1} \neq x_n$  for each  $n$ , either  $x_{2n-1} \neq u$  for infinitely many  $n$  or  $x_{2n} \neq u$  for infinitely many  $n$ . By the symmetry we may assume that  $x_{2n} \neq u$  for infinitely many  $n$ . Thus there is a subsequence  $\{k(n)\}$  of  $\{n\}$  such that  $x_{2k(n)} \neq u$  for each  $n$ .

For any  $n \geq 1$  and all  $p \in \Gamma$  we have

$$\begin{aligned} (4) \quad p(u - f(u)) &\leq p(u - x_{2k(n)}) + p(x_{2k(n)} - f(u)) \\ &= p(u - x_{2k(n)}) + p(g(x_{2k(n)-1}) - f(u)). \end{aligned}$$

Now,  $p(f(u) - g(x_{2k(n)-1})) \leq a_p p(u - x_{2k(n)-1}) + b_p p(u - f(u)) + c_p p(x_{2k(n)-1} - g(x_{2k(n)-1})) + d_p p(u - g(x_{2k(n)-1})) + e_p p(x_{2k(n)-1} - f(u)) = a_p p(x_{2k(n)-1} - u) + b_p p(u - f(u)) + c_p p(x_{2k(n)-1} - x_{2k(n)}) + d_p p(u - x_{2k(n)}) + e_p p(x_{2k(n)-1} - f(u)) \leq \gamma \max\{p(x_{2k(n)-1} - u), p(u - f(u)), p(x_{2k(n)-1} - x_{2k(n)}), p(u - x_{2k(n)}), p(x_{2k(n)-1} - f(u))\} \leq \gamma p(f(u) - u)$  as  $n$  is sufficiently large.

Thus

$$(5) \quad p(f(u) - g(x_{2k(n)-1})) \leq \gamma p(f(u) - u).$$

Since  $\gamma < 1$ . So  $f(u) = u$ .

Further we have to show that  $u \in A$ . But

$$\begin{aligned} p(u - x_0) &= p(\lim_m x_m - x_0) = \lim_m p(x_m - x_0) \\ &\leq \lim_m \sum_{i=0}^{m-1} p(x_{i+1} - x_i) = \lim_m \sum_{i=0}^{m-1} p(x_{i+1} - x_i) \left( \frac{a_p + b_p + d_p}{1 - c_p - d_p} \right)^i p(x_1 - x_0) \end{aligned}$$

for all  $p \in \Gamma$  (using 3). So, by passing to the limit,

$$p(u - x_0) \leq \frac{1 - b_p - d_p}{1 - a_p - b_p - c_p - 2d_p} p(x_1 - x_0)$$

for all  $p \in \Gamma$ . Since  $A$  is of type  $\Gamma_0$  with respect to  $x_0$ , so  $u \in A$ . Hence  $u$  is the fixed point of  $f$  in  $A$ . If  $u, v$  are the fixed points of  $f$  and  $g$  respectively,

such that  $u \neq v$ , then  $p(u-v) = p(f(u)-g(v)) \leq (a_p + 2d_p)p(u-v) < p(u-v)$  for all  $p \in \Gamma$ , what is a contradiction. So  $u = v$ .

## 2. A Meir-Keeler type fixed point theorem

In 1969, Meir and Keeler [5] obtained a remarkable generalization of the Banach's results. Park and Bae [8] extended the Meir-Keeler theorem to two commuting maps by adopting Jungck's method. Consequently, a number of new results in this line followed. Recently, Hicks and Kubicek [3] and Włodarczyk [9] studied fixed point theorems in locally convex topological vector spaces. In This section a Meir-Keller type fixed point theorem for a pair of maps on locally convex topological vector spaces is given.

**THEOREM 2.** *Let  $E$  be a sequentially complete Hausdorff locally convex topological vector spaces with calibration  $\Gamma$ . Consider two mappings  $f, g$  from  $E$  into  $E$  satisfying a condition: for any given  $\epsilon > 0$ , there exists  $\delta > 0$  such that the inequality*

$$\epsilon \leq p(x-y) < \epsilon + \delta \text{ implies } p(f(x)-g(y)) < \epsilon \text{ for all } p \in \Gamma.$$

*If at least one of  $f$  and  $g$  is continuous then  $f$  or  $g$  has a fixed point. If both  $f$  and  $g$  have fixed points, then each of them has a unique fixed point and these two points coincide.*

**Proof.** Fix  $x_0 \in E$  and define  $\{x_n\}$  by  $x_{2n+1} = f(x_{2n})$ ,  $x_{2n+2} = g(x_{2n+1})$ . Then  $\{x_n\}$  is a Cauchy sequence. Indeed, if otherwise, then there exists  $\epsilon > 0$ , such that  $\limsup p(x_m - x_n) > 2\epsilon$ , for all  $p \in \Gamma$ . By hypothesis, there exists  $\delta > 0$ , such that,

$$(7) \quad \epsilon \leq p(x-y) < \epsilon + \delta \text{ and so } p(f(x)-g(y)) < \epsilon \text{ for all } p \in \Gamma.$$

Replace  $\delta$  by  $\delta' = \min\{\delta, \epsilon\}$ . Firstly, we show that  $\lim p(x_n - x_{n+1}) \downarrow 0$ ,  $(\forall)p \in \Gamma$ . Let  $C_n = p(x_n - x_{n+1})$ . Since from (6)  $C_n$ , is a decreasing sequence, then (6) fails for  $C_{m+1}, p \in \Gamma$ , where  $C_m$  is chosen less than  $\epsilon + \delta$ . Hence

$$(8) \quad \lim_n C_n \downarrow 0 \text{ for all } p \in \Gamma.$$

By (8), we can find an  $M$  so that  $C_M < \delta'/3$ . Pick  $m, n > M$ , so that

$$(9) \quad p(x_m - x_n) > 2\epsilon, \quad p \in \Gamma, \quad |p(x_m - x_j) - p(x_m - x_{j+1})| \leq C_j < \frac{\delta'}{3}$$

for all  $p \in \Gamma$ .

Since  $C_m < \epsilon$  and  $p(x_m - x_n) > \epsilon + \delta'$ , for all  $p \in \Gamma$ , therefore there exists an integer  $j \in [m, n]$  with  $\epsilon + \frac{2\delta'}{3} < p(x_m - x_j) < \epsilon + \delta'$ , for all  $p \in \Gamma$ . Indeed from (9),  $p(x_m - x_{j+1}) - C_j \leq p(x_m - x_j)$ . It gives,  $\epsilon + \delta' - \frac{\delta'}{3} = \epsilon + \frac{2\delta'}{3} < p(x_m - x_j)$ . Also  $p(x_m - x_j) < \epsilon + \delta'$  for all  $p \in \Gamma$ . Hence

$\epsilon + \frac{2\delta'}{3} < p(x_m - x_j) < \epsilon + \delta'$ . Using (7), we conclude that for all  $m$  and  $j$ ,

$$\begin{aligned} p(x_m - x_j) &\leq p(x_m - x_{m+1}) + p(x_{m+1} - x_{j+1}) + p(x_{j+1} - x_j) \\ &\leq C_m + \epsilon + C_j < \frac{2\delta'}{3} + \epsilon, \quad \text{for all } p \in \Gamma. \end{aligned}$$

Hence it is a contradiction. So  $\{x_n\}$  is a Cauchy sequence. Since  $E$  is sequentially complete,  $\{x_n\}$  converges to some point  $x \in E$ . Thus  $f(x_{2n}) \rightarrow x$  and  $g(x_{2n+1}) \rightarrow x$ . If  $f$  is continuous, then

$$f(x) = f(\lim_{n \rightarrow \infty} g(x_{2n+1})) = \lim_{n \rightarrow \infty} f(x_{2n+2}) = x.$$

So  $x$  is a fixed point of  $f$ . Let  $u$  and  $v$  be the fixed points of  $f$  and  $g$  respectively such that  $u \neq v$ . Then by using (7), we have that  $p(u - v) = p(f(u) - g(v)) < p(u - v)$ , for all  $p \in \Gamma$ , a contradiction. Therefore  $u = v$ .

**COROLLARY 3.** *Let  $E$  be a sequentially complete Hausdorff locally convex topological vector space with calibration  $\Gamma$ . Let  $f$  be a mapping from  $E$  into  $E$  satisfying: for given  $\epsilon > 0$ , there exists  $\delta > 0$  such that the condition  $\epsilon \leq p(x - y) < \epsilon + \delta$  implies  $p(f(x) - f(y)) < \epsilon$ , for all  $p \in \Gamma$ . Then  $f$  has a unique fixed point.*

**COROLLARY 4.** *Let  $E$  be a sequentially complete Hausdorff locally convex topological vector space with calibration  $\Gamma$ . Let  $f$  be a surjective mapping from  $E$  into  $E$  satisfying a condition: for given  $\epsilon > 0$ , there exists  $\delta > 0$  such that, the inequality*

$$(10) \quad p(x - y) < \epsilon \quad \text{implies } \epsilon \leq p(f(x) - f(y)) < \epsilon + \delta,$$

for all  $p \in \Gamma$ .

*Then  $f$  has a unique fixed point.*

**P r o o f.** We shall show that  $f$  is a one-to-one mapping. Indeed, let  $x \neq y$  and  $p(x - y) < \epsilon$  but  $f(x) = f(y)$ . Using (10), we obtain  $0 \leq p(x - y) < p(f(x) - f(y)) = 0$ ,  $p \in \Gamma$ , what is impossible.

Let  $g$  be the inverse of  $f$ . Then (10) becomes  $p(g(x) - g(y)) < \epsilon$ , whenever  $\epsilon \leq p(x - y) < \epsilon + \delta$ . By Corollary (3),  $g$  has the unique fixed point  $u$ . Thus  $g(u) = u = f(g(u)) = f(u)$ . So  $u$  is the unique fixed point of  $f$ .

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