

Nicolae Soare

## ON THE EXISTENCE OF THE LINEAR CONNECTIONS COMPATIBLE WITH SOME $(f, g)$ -STRUCTURES

In this note we study the  $(f, g)$ -structures determined by a tensor field  $f$  of type (1.1) so that  $f^{2v+3} - f = 0$  and a Riemannian structure  $g$ , satisfying a supplementary condition.

The case of the  $(f, g)$ -structures with  $f^3 + f = 0$  was studied by R. Miron and Gh. Atanasiu [5].

Using Obata's operators associated to the considered  $(f, g)$ -structures and Wilde's method of characterizing the set of solutions of a system of tensorial equations [10], are found all the linear  $(f, g)$ -connections and the groups of transformations of connections of the  $(f, g)$ -structures.

### 1. $(f, g)$ -structures

Let  $M$  be a Riemannian manifold with the Riemannian metric  $g$ ,  $\mathcal{C}(M)$  the affin modul of the linear connections on  $M$ ,  $\mathcal{T}_s^r(M)$  - the modul of the tensors of type  $(r, s)$ ; for  $\mathcal{T}_0^1(M)$  and  $\mathcal{T}_1^0(M)$ , are used the notations  $\mathcal{X}(M)$  and  $\mathcal{X}^*(M)$  respectively.

All the objects are of class  $C^\infty$ .

DEFINITION 1.1. We call  $f$ -structure on  $M$ , a non-null field of tensors  $f \in \mathcal{T}_1^1(M)$ , of rank  $r$ , where  $r$  is a constant everywhere, so that

$$f^{2v+3} - f = 0.$$

If  $M$  is a  $f(2v+3, -1)$ -manifold, that is  $M$  is an  $n$ -dimensional Riemannian manifold, equiped with a  $f$ -structure, then for

$$(1.1) \quad e = f^{2v+2}, \quad m = I - f^{2v+2} \quad (\text{I denoting identity operator}) \quad \text{we have [7]}$$

$$(1.2) \quad fe = ef = f, \quad fm = mf = 0, \quad f^{2v+2}e = e, \quad f^{2v+2}m = 0,$$

$$(1.3) \quad e + m = I, \quad em = me = 0, \quad e^2 = e, \quad m^2 = m.$$

Thus the operators  $e$  and  $m$  are complementary projection operators on  $M$ .

The Riemannian structure  $g$  on  $M$  can be considered as  $\mathcal{X}^*(M)$ -valued differential 1-form and we have  $g : \mathcal{X}(M) \rightarrow \mathcal{X}^*(M)$ ,  $g(X) = g_X$ , where  $g_X(Y) = g(X, Y)$  for every  $X, Y \in \mathcal{X}(M)$ . If  $f \in T_1^1(M)$ , then  ${}^t f$  is the transpose of  $f$ ,  ${}^t f : \mathcal{X}^*(M) \rightarrow \mathcal{X}^*(M)$ ,  ${}^t f(h) = h \circ f$ , for every  $h \in \mathcal{X}^*(M)$ .

DEFINITION 1.2. We call  $(f, g)$ -structure on  $M$ , a couple made up a  $f$ -structure and a Riemannian structure  $g$  so that

$$(1.4) \quad {}^t f^{v+1} \circ g \circ f^{v+1} = -g \circ e.$$

THEOREM 1.1. Let  $M$  be a paracompact differential manifold with a  $f$ -structure. Then, there is a  $(f, g)$ -structure.

PROOF. In truth, if  $\gamma$  is a Riemannian metric, fixed on  $M$ , then

$$(1.5) \quad g = \frac{1}{2}(\gamma - {}^t f^{v+1} \circ \gamma \circ f^{v+1} - \gamma \circ m - {}^t m \circ \gamma + 3{}^t m \circ \gamma \circ m)$$

verifies the condition (1.4).

PROPOSITION 1.1. For a  $(f, g)$ -structure on  $M$  and  $e, m$  defined by the equations (1.1) we have

$$(1.6) \quad \begin{aligned} g \circ f^{v+1} &= -{}^t f^{v+1} \circ g, & g^{-1} \circ {}^t f^{v+1} &= -f^{v+1} \circ g^{-1} \\ g \circ m &= {}^t m \circ g, & g^{-1} \circ {}^t m &= m \circ g^{-1}. \end{aligned}$$

PROPOSITION 1.2.  $\omega = g \circ f^{v+1}$  is a differential 2-form on  $M$ .

DEFINITION 1.3. We call Obata operators associated to  $f$ -structure, the applications  $A, A^* : T_1^1(M) \rightarrow T_1^1(M)$  defined by

$$(1.7) \quad \begin{aligned} A(w) &= \frac{1}{2}(w - mw - wm + 3wmn - f^{v+1}w f^{v+1}), \\ A^*(w) &= w - A(w). \end{aligned}$$

We also consider the Obata operators [6] associated to  $g$ :

$$(1.8) \quad B(u) = \frac{1}{2}(u - g \circ {}^t u \circ g), \quad B(u) = \frac{1}{2}(u + g^{-1} \circ {}^t u \circ g).$$

We can demonstrate

PROPOSITION 1.3. For a  $(f, g)$ -structure on  $M$  and for  $A, A^*$  and  $B, B^*$  defined by (1.7) and (1.8) we have:

- 1)  $A$  and  $A^*$  are complementary projections on  $T_1^1(M)$ .
- 2)  $B$  and  $B^*$  commute pairwise with  $A$  and  $A^*$ .

3)  $A \circ B$  and  $A^* \circ B^*$  are projections on  $T_1^1(M)$ .

4)  $\text{Ker } A^* \cap \text{ker } B^* = \text{Im}(A \circ B)$ .

In truth, by simple calculation, we obtain the result 1).

The affirmation 2) is true, because, taking into account the relations (1.6), we have

$$\begin{aligned} (A \circ B - B \circ A)(u) &= \dots \\ &= \frac{1}{4}(m \circ g^{-1} \circ {}^t u \circ g - g^{-1} \circ {}^t m \circ {}^t u \circ g) + (g^{-1} \circ {}^t u \circ g \circ m - g^{-1} \circ {}^t u \circ {}^t m \circ g) \\ &\quad - 3(m \circ g^{-1} \circ {}^t u \circ g \circ m - g^{-1} \circ {}^t m \circ {}^t u \circ {}^t m \circ g) \\ &\quad + (f^{v+1} \circ g^{-1} \circ {}^t u \circ g \circ f^{v+1} - g^{-1} \circ {}^t f^{v+1} \circ {}^t u \circ {}^t f^{v+1} \circ g) = 0, \end{aligned}$$

for every  $u \in T_1^1(M)$ , or

$$A \circ B = B \circ A.$$

Thus we have the relations

$$A \circ B^* = B^* \circ A,$$

$$A^* \circ B = B \circ A^*.$$

The above mentioned relations give us the possibility to formulate [10]:

**PROPOSITION 1.4.** *The system of tensorial equations*

$$(1.9) \quad A^*(u) = a, \quad B^*(u) = b$$

has a solution  $u \in T_1^1(M)$ , if and only if

$$(1.10) \quad A(a) = 0, \quad B(b) = 0, \quad A^*(b) = B^*(a).$$

If the conditions (1.10) are fulfilled, then the general solution of the system (1.9) is

$$u = a + A(b) + (A \circ B)(w) \quad \forall w \in T_1^1(M).$$

## 2. $(f, g)$ -linear connections

In the following  $\hat{\nabla} \in \mathcal{C}(M)$  will be a linear connection fixed on  $M$ . Every tensor field  $u \in T_1^1(M)$  may be considered as a field of  $\mathcal{X}(M)$ -valued differential 1-forms. So, if  $\nabla$  is a linear connection on  $M$ , then we note with  $D$  and  $\tilde{D}$  the associated connections, acting on the  $\mathcal{X}(M)$ -valued differential 1-forms and respectively on the differential 1-forms  $g : \mathcal{X}(M) \rightarrow \mathcal{X}^*(M)$ :

$$(2.1) \quad D_x u = \nabla_X u - u \nabla_X, \quad \forall X \in \mathcal{X}(M),$$

$$(2.2) \quad \tilde{D}_X g = {}^t \nabla_X \circ g - g \circ \nabla_X, \quad \forall X \in \mathcal{X}(M),$$

where

$$({}^t\nabla_X g)(Y, Z) = Xg(Y, Z) - g(\nabla_X Y, Z), \quad \forall X, Y, Z \in \mathcal{X}(M).$$

DEFINITION 2.1. A linear connection  $\nabla$  on  $M$  is called  $(f, g)$ -linear connection if

$$(2.3) \quad D_X f = 0, \quad \tilde{D}_X g = 0, \quad \forall X \in \mathcal{X}(M).$$

Of course, for every  $(f, g)$ -linear connection, we have

$$(2.4) \quad \begin{aligned} D_X e &= \nabla_X e - e \nabla_X = 0, \quad D_X m = \nabla_X m - m \nabla_X = 0, \\ D_X f^k &= \nabla_X f^k - f^k \nabla_X = 0, \quad k \text{ natural number, } X \in \mathcal{X}(M). \end{aligned}$$

We see that  $D$  and  $\tilde{D}$  commute with the operators  $A, A^*, B, B^*$ . We take

$$\nabla_X = \mathring{\nabla}_X + V_X,$$

$X \in \mathcal{X}(M)$ ,  $V \in \mathcal{T}_2^1(M)$ ,  $V_X Y = V(X, Y)$  and find the tensor field  $V$  so that  $\nabla$  satisfies the conditions (2.3).

$\nabla$  will be a  $(f, g)$ -linear connection if and only if the field  $V$  verifies the system

$$V_X \circ f - f \circ V_X = -\mathring{D}_X f, \quad {}^t V_X \circ g + g V_X = \tilde{D}_X g.$$

This system is equivalent with the system

$$(2.5) \quad \begin{aligned} A^*(V_X) &= -\frac{1}{2}(f \circ \mathring{D}_X f + \mathring{D}_X m - 3m \circ \mathring{D}_X m) \\ B^*(V_X) &= \frac{1}{2}g^{-1} \circ \tilde{D}_X g. \end{aligned}$$

Applying Proposition 1.4, it becomes evident that the system (2.5) has the solutions and the general solutions is

$$(2.6) \quad \begin{aligned} V_X &= -\frac{1}{2}(f \circ \mathring{D}_X f + \mathring{D}_X m - 3m \circ \mathring{D}_X m) + \frac{1}{4}(\tilde{D}_X g - {}^t f^{v+1} \circ \tilde{D}_X g \circ f^{v+} \\ &\quad - \tilde{D}_X g \circ m - {}^t m \circ \tilde{D}_X g + 3{}^t m \circ \tilde{D}_X g \circ m) + (A \circ B)(W_X), \end{aligned}$$

where  $W \in \mathcal{T}_2^1(M)$ . Thus, we have

THEOREM 2.1. *There are  $(f, g)$ -linear connections: one of them is*

$$(2.7) \quad \nabla_X = \mathring{\nabla}_X + V_X$$

where  $\mathring{\nabla}$  is an arbitrary linear connection, fixed on  $M$ , and  $V_X$  is given by (2.6),  $W$  being an arbitrary tensor field.

If  $\overset{\circ}{\nabla}$  is the Levi-Civita connection of  $g$ , then we have  $\tilde{\tilde{D}}_X g = 0$  and Theorem 2.1 becomes

THEOREM 2.2. For every  $(f, g)$ -structure, the following linear connection

$$(2.8) \quad \overset{\circ}{\nabla}_X = \overset{\circ}{\nabla}_X - \frac{1}{2}(f \circ \overset{\circ}{D}_X f + \overset{\circ}{D}_X m - 3m \circ \overset{\circ}{D}_X m), \quad \forall X \in \mathcal{X}(M),$$

where  $\overset{\circ}{\nabla}$  is the Levi-Civita connection of  $g$ , has the following characteristics:

- 1)  $\overset{\circ}{\nabla}$  is dependent uniquely of  $f$  and  $g$ ;
- 2)  $\overset{\circ}{\nabla}$  is a  $(f, g)$ -linear connection.

The linear connection  $\overset{\circ}{\nabla}$  will be called the  $(f, g)$  canonic connection.

THEOREM 2.3. The set of all the  $(f, g)$ -linear connections is given by

$$(2.9) \quad \overline{\nabla}_X = \nabla_X + (A \circ B)(W_X), \quad W \in \mathcal{T}_{\frac{1}{2}}(M),$$

where  $\nabla$  is a  $(f, g)$ -linear connection, in particular  $\nabla = \overset{\circ}{\nabla}$ .

Observing that (2.9) can be considered as a transformation of  $(f, g)$ -linear connections, we have

THEOREM 2.4. The set of the transformations of  $(f, g)$ -linear connections and the multiplications of the applications is an abelian group, noted with  $G(f, g)$ , isomorph with the additiv group of the tensors  $W \in \mathcal{T}_{\frac{1}{2}}(M)$ , which have the characteristic

$$W_X \in \text{Im}(A \circ B) = \text{Ker } A^* \cap \text{Ker } B^*, \quad X \in \mathcal{X}(M).$$

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FACULTATEA DE MATEMATICA

Str. Academiei 14

BUCUREȘTI, ROMANIA

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