Vol. XV No 3 19

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ON CERTAIN NONLOCAL PROBLEM WITH MIXED BOUNDARY CÓNDITION FOR A PARABOLIC SYSTEM OF PARTIAL DIFFERENTIAL EQUATIONS

1. Introduction

In the present paper we give the solution of a certain nonlocal problem with mixed boundary condition for a parabolic system of partial differential equations. The method presented in this paper makes possible the reduction of nonlocal problem to a system of Volterra integral equations. We shall make use of the results established by the author in papers [1] and [2].

Consider the problem (N):

Find a vector-function $\overline{u}(x,t)$ satisfying the system of equations

(1.1)
$$\frac{\partial \vec{u}}{\partial t} = 4D \frac{\partial^2 \vec{u}}{\partial x^2} + \vec{f}(x,t)$$

in the domain $(x,t) \in Q = (0,1) \times (0,T)$, $0 < T < \infty$, where

$$\overrightarrow{u}(x,t) = \begin{bmatrix} u_1(x,t) \\ \vdots \\ u_n(x,t) \end{bmatrix}, \quad \overrightarrow{f}(x,t) = \begin{bmatrix} f_1(x,t) \\ \vdots \\ f_n(x,t) \end{bmatrix}, \quad D = \begin{bmatrix} d_{ij} \end{bmatrix} \quad i,j=1,\ldots,n.$$

and Re $\lambda > 0$ for any eigenvalue λ of the matrix D, such that

(1.2)
$$\lim_{t\to 0^+} \overline{u}(x,t) = \overline{\varphi}(x) \quad \text{for} \quad x \in (0,1)$$

(1.3)
$$A(t)\overline{u}_{x}(0,t) - B(t)\overline{u}(1,t) = \overline{H}(t),$$

where

$$\vec{u}_{x}(0,t) = \lim_{x \to 0^{+}} \vec{u}_{x}(x,t), \quad \vec{u}(1,t) = \lim_{x \to 1^{-}} \vec{u}(x,t) \quad \text{for } t \in (0,T)$$

(1.4)
$$\vec{u}(1,t) - \sum_{j=1}^{p} \mu_{j}(t) \cdot \vec{u}(x_{j},t) = \vec{h}(t) \text{ for } t \in (0,T),$$

 x_1, \dots, x_p are fixed points of the interval (0,1). We assume that

- (i) $\varphi(x)$ is a continuous vector-function with bounded variation in the interval (0,1),
- (ii) $\vec{H}(t)$, $\vec{h}(t)$ are two continuous vector-functions, piecewise of class C^1 in the interval $\langle 0,T \rangle$,
- (iii) A(t), B(t), $\mu_j(t)$ (j=1,...,p) are n-dimensional matrices piecewise of class $C^1(0,T)$, det A(t) \neq 0 for every $t \in (0,T)$.

We recall that if $D = \begin{bmatrix} d_{ij} \end{bmatrix}$ is an n-dimensional matrix such that Re $\lambda > 0$ for any eigenvalue λ of the matrix D then by M(x,t) for $(x,t) \in (-\infty,+\infty) \times (0,+\infty)$ we shall understand the sum

(1.5)
$$M(x,t) = I + 2 \sum_{k=1}^{+\infty} \exp\left[-k^2\pi^2 t D\right] \cos k\pi x.$$

Introduce the following notations

(1.6)
$$\vec{u}_1(x,t) = -2D \int_0^t \left[M(\frac{x}{2}, t-s) - M(\frac{x-2}{2}, t-s) \right] \vec{f}_1(s) ds$$

(1.7)
$$\vec{u}_2(x,t) = D \int_0^t \left[M_x'(\frac{x-1}{2}, t-s) - M_x'(\frac{x+1}{2}, t-s) \right] \vec{f}_2(s) ds$$

(1.8)
$$\overline{u}_3(x,t) = \frac{1}{4} \int_0^1 \left[M\left(\frac{x-8}{2}, t\right) + M\left(\frac{x+8}{2}, t\right) - M\left(\frac{x-8-2}{2}, t\right) - M\left(\frac{x-8-2}{2}, t\right) \right]$$

$$-M\left(\frac{x+s-2}{2}, t\right)$$

(1.9)
$$\vec{u}_4(x,t) = \frac{1}{4} \int_0^t \int_0^1 \left[M\left(\frac{x-s}{2}, t-\eta\right) + M\left(\frac{x+s}{2}, t-\eta\right) - \frac{1}{4} \left(\frac{x+s}{2}, t-\eta\right) \right]$$

-
$$M\left(\frac{x-s-2}{2}, t-\eta\right) - M\left(\frac{x+s-2}{2}, t-\eta\right) = \hat{f}(s,\eta) ds d\eta$$

where $f_1(s)$, $f_2(s)$, $\varphi(s)$, $f(s,\eta)$ are some fixed functions.

2. The auxiliary problem

Let us consider the problem (F):

Find vector-function $\vec{u}(x,t)$ such that (1.1) holds in Q subject to the following boundary conditions:

(2.1)
$$\lim_{t \to 0^+} \overrightarrow{u}(x,t) = \overrightarrow{\varphi}(x) \quad \text{for} \quad x \in (0,1)$$

(2.2)
$$\lim_{t \to 0^+} \overline{u}_x'(x,t) = \overline{f}_1(t) \text{ for } t \in (0,T)$$

(2.3)
$$\lim_{x\to 1^-} \bar{u}(x,t) = f_2(t) \text{ for } t \in (0,T).$$

We shall construct solution of (F) problem explicitely, without referring to integral equations. To this aim, let us recall the main results of the paper [1].

Theorem 1. If for every eigenvalue λ of the matrix D the condition Re $\lambda > 0$ is satisfied then:

- a) M(x,t) is of the class C^{∞} in the domain (x,t) $(-\infty,+\infty)\times(0,+\infty)$ and the respective derivatives can be obtained by term-by-term differentiation of the respective series.
 - b) $\lim_{t\to 0^+} \frac{\partial^s M(x,t)}{\partial x^s} = 0$ for $s = 0,1,2,..., x \neq 0,\pm 2,\pm 4,...$
- c) For $(x,t) \in (-\infty,+\infty) \times (0,+\infty)$ each column of the matrix M(x,t) is a solution of the homogeneous system (1.1) i.e.

$$\frac{\partial M(x,t)}{\partial t} = D \frac{\partial^2 M(x,t)}{\partial x^2}.$$

Now, we can prove the following theorem.

Theorem 2. If the vector-functions $f_1(t), f_2(t)$ are continuous in the interval (0,T) and possess bounded and piecewise continuous derivatives f_1' , f_2' for $t \in (0,T)$ then:

- a) the functions u_1 , u_2 defined by (1.6), (1.7) satisfy the homogeneous system of equations (1.1) (f(x,t) = 0)
- b) $\lim_{t\to 0^+} \widehat{u_i}(x,t) = 0$ (i=1,2) for every fixed $x \in (0,1)$
- c) $\lim_{x\to 0^+} \overline{u_1'}(x,t) = f_1(t), \lim_{x\to 1^-} \overline{u_1}(x,t) = 0$ for every $t \in (0,T)$
- d) $\lim_{x\to 0^+} \frac{\vec{u}_{2x}(x,t)}{\vec{u}_{2x}(x,t)} = 0$, $\lim_{x\to 1^-} \frac{\vec{u}_{2}(x,t)}{\vec{u}_{2}(x,t)} = f_2(t)$ for every $t \in (0,T)$.

Proof. The validity of part a) and b) of Theorem 2 results from Theorem 1 and from elementary analytical calculations (cf. [1]). Now, we establish the validity of part c) of the theorem. To this aim let us note that $\lim_{x\to 1^-} \overline{u_1}(x,t) = 0$ because $\mathbb{N}(\frac{1}{2}, t-s) = \mathbb{N}(\frac{-1}{2}, t-s)$ and

$$\vec{u}_{1x}'(x,t) = -2D \int_{0}^{t} \left[\frac{1}{2} M_{x}'(\frac{x}{2}, t-s) - \frac{1}{2} M_{x}'(\frac{x-2}{2}, t-s) \right] \vec{f}_{1}(s) ds =$$

$$= -D \int_{0}^{t} M_{x}'(\frac{x}{2}, t-s) \vec{f}_{1}(s) ds + D \int_{0}^{t} M_{x}'(\frac{x-2}{2}, t-s) \vec{f}_{1}(s) ds.$$

By Theorem 5 of paper [2] it follows that

$$\lim_{x\to 0^+} D \int_0^t M_x'(\frac{x}{2}, t-s) \, \hat{f}_1(s) ds = -\hat{f}_1(t) \quad \text{for} \quad t \in (0,T)$$

and

$$\lim_{x\to 0^+} D \int_0^t M_x'(\frac{x-2}{2}, t-s) \tilde{f}_1(s) ds = 0 \quad \text{for} \quad t \in (0,T)$$

which completes the proof of the part c). Analogously part d) can be proved.

Theorem 3. If the vector-function $\varphi(x)$ possesses a bounded variation in the interval $x \in (0,1)$ and it is a sum of its trigonometric Fourier series for every $x \in (0,1)$, then the vector-function $\widehat{u_3}(x,t)$ defined by (1.8) is a solution of the homogeneous system (1.1) $(\widehat{f}(x,t)=0)$) and satisfies the conditions

$$\lim_{t\to 0^+} \overline{u}_3(x,t) = \overline{\varphi}(x) \quad \text{for } x \in (0,1)_0,$$

$$\lim_{x\to 0^+} \overline{u}_{3x}'(x,t) = 0,$$

$$\lim_{x\to 1^-} \overline{u}_3(x,t) = 0 \quad \text{for } t \in (0,T).$$

Proof. From the definition (1.5) we obtain

$$\frac{1}{4}\left[\mathbb{M}\left(\frac{\mathbf{x}-\mathbf{s}}{2}, \mathbf{t}\right) + \mathbb{M}\left(\frac{\mathbf{x}+\mathbf{s}}{2}, \mathbf{t}\right) - \mathbb{M}\left(\frac{\mathbf{x}-\mathbf{s}-2}{2}, \mathbf{t}\right) - \mathbb{M}\left(\frac{\mathbf{x}+\mathbf{s}-2}{2}, \mathbf{t}\right)\right] =$$

=
$$2 \sum_{k=0}^{+\infty} \exp \left[-(2k+1)^2 \pi^2 t D \right] \cos \frac{2k+1}{2} \pi x \cos \frac{2k+1}{2} \pi s$$
.

This series is uniformly convergent with respect to x and s (t being fixed). Thus, we have

(2.4)
$$\overline{u_3}(x,t) = \sum_{k=1}^{+\infty} \exp[-(2k+1)^2 \pi^2 t D] \cos \frac{2k+1}{2} \pi x \cdot \overline{a_k},$$

where

$$a_k = 2 \int_0^1 \overline{\phi}(s) \cos \frac{2k+1}{2} \pi s ds$$
 for $k = 0,1,2,...$

The series (2.4) converges uniformly for t ϵ <0,T> because the series $\sum_{k=0}^{+\infty} \overline{a_k}$ converges (cf. lemma in [2]). Then

$$\lim_{t\to 0^+} \overline{u_3}(x,t) = \sum_{k=0}^{+\infty} \cos \frac{2k+1}{2} \pi x \cdot \overline{a_k} = \overline{\varphi}(x)$$

by the assumption.

The formula (2.4) implies that $\lim_{x\to 0^+} \frac{1}{3x}(x,t) = \lim_{x\to 0^+} \frac{1}{3x}(x,t) = \lim_{x\to 1^-} \frac{1}{3x}(x,t) = 0$. The series (2.4) is almost uniformly convergent in Q, so it can be differentiated term-by-term and it is clear that $u_3(x,t)$ satisfies the homogeneous system of equations (1.1).

Now, we can prove the following theorem.

- Theorem 4. If:
- a) f(x,t) is continuous in the rectangle \overline{Q} ,

b)
$$\lim_{x\to 0^+} \overline{f}(x,t) = \lim_{x\to 1^-} \overline{f}(x,t) = 0$$
,

- c) f(x,t) is piecewise of the class C^2 with respect to x (t being fixed),
- d) $\sup_{t \in (0,T)} \int_{0}^{1} \| \tilde{f}''_{xx}(x,t) \| dx < +\infty,$
- e) the number of points of discontinuity $f_{xx}''(x,t)$ as a function of x is not greater than n_0 (n_0 is independent on t),

then the vector-function $\overline{u_4}(x,t)$ defined by (1.9) is a solution of the system (1.1) and satisfies the homogeneous boundary and initial conditions

$$\lim_{t\to 0^+} \overline{u_4}(x,t) = \lim_{x\to 0^+} \overline{u_4'}(x,t) = \lim_{x\to 1^-} \overline{u_4}(x,t) = 0.$$

Proof According to the theory of Fourier series, the function f(x,t) which satisfies given assumptions can be written in the form

$$\overline{f}(x,t) = \sum_{k=0}^{+\infty} \overline{b_k}(t) \cos \frac{2k+1}{2} \pi x,$$

where

$$\vec{b}_{k}(t) = 2 \int_{0}^{1} \vec{f}(s,t) \cos \frac{2k+1}{2} \pi s \, ds$$
 for $k=0,1,2,...$

are continuous functions for $t \in (0,T)$ satisfying the inequality

$$\|\overrightarrow{b}_{k}(t)\| \leq \frac{A}{k^{2}}, \quad k = 0,1,2,\ldots$$

A is a positive constant.

From the uniform convergence of the series

$$\frac{1}{4} \int_{0}^{1} \left[M\left(\frac{x-s}{2}, t-\eta\right) + M\left(\frac{x+s}{2}, t-\eta\right) - M\left(\frac{x-s-2}{2}, t-\eta\right) - M\left(\frac{x+s-2}{2}, t-\eta\right) \right]$$

$$- M\left(\frac{x+s-2}{2}, t-\eta\right) \int_{0}^{\infty} \hat{f}(s,\eta) ds =$$

$$= \sum_{k=0}^{+\infty} \exp\left[-(2k+1)^{2} \pi^{2} (t-\eta) D\right] \cos \frac{2k+1}{2} \pi x \ \hat{b}_{k}(\eta)$$

it follows that

Hence

$$\vec{u}_{4x}'(x,t) = \sum_{k=0}^{+\infty} \vec{b}_{k}(t) \cos \frac{2k+1}{2} \pi x +$$

$$- D \sum_{k=0}^{+\infty} \cos \frac{2k+1}{2} \pi x \int_{0}^{t} (2k+1)^{2} \pi^{2} \exp \left[-(2k+1)^{2} \pi^{2} (t-\eta)D\right] \vec{b}_{k}(\eta) d\eta =$$

$$= \vec{f}(x,t) + 4D \frac{\partial^{2} \vec{u}_{4}}{\partial x^{2}}.$$

The proof of the second part of the theorem follows from (2.5)

Theorems 2, 3 and 4 imply the following corollary.

Corollary. If the functions f_1 , f_2 , ϕ , f satisfy the assumptions of Theorems 2, 3 and 4 respectively, then the problem (F) possesses the solution. This solution can be written in the form

(2.6)
$$\overrightarrow{u}(x,t) = \overrightarrow{u}_1(x,t) + \overrightarrow{u}_2(x,t) + \overrightarrow{u}_3(x,t) + \overrightarrow{u}_4(x,t)$$

where \bar{u}_1 , \bar{u}_2 , \bar{u}_3 , \bar{u}_4 are defined by (1.6), (1.7), (1.8), (1.9).

3. Solution of the problem (N)

We can prove the following theorem.

Theorem 5. If \vec{h} , $\vec{\phi}$, \vec{H} , a, B, μ_j (j=1,...,p) satisfy conditions (i), (ii), (iii), and $\vec{f}(x,t)$ satisfies the assumptions of Theorem 4 then there exists a solution of the problem (N).

Proof. Let us denote

$$\vec{f}_1(t) = \lim_{x \to 0^+} \vec{u}_x'(x,t), \quad \vec{f}_2(t) = \lim_{x \to 1^-} \vec{u}(x,t)$$

where a solution $\overline{u}(x,t)$ of the problem (N) is sought in the form (2.6).

From the first nonlocal condition (1.3) we obtain

(3.1)
$$\hat{f}_1(t) = A^{-1}(t)\hat{H}(t) + A^{-1}(t)B(t)\hat{f}_2(t)$$
.

Combining formulas (2.6) and (3.1) we can write

$$\vec{u}(x,t) = \int_{0}^{t} K(x,t,s) \vec{f}_{2}(s) ds -
- 2D \int_{0}^{t} \left[M(\frac{x}{2}, t-s) - M(\frac{x-2}{2}, t-s) \right] A^{-1}(s) H(s) ds +
+ \vec{u}_{3}(x,t) + \vec{u}_{4}(x,t),$$

where

$$K(x,t,s) = D\left[M'_{x}\left(\frac{x-1}{2}, t-s\right)\right] - M'_{x}\left(\frac{x+1}{2}, t-s\right) - 2D\left[M\left(\frac{x}{2}, t-s\right) - M\left(\frac{x-2}{2}, t-s\right)\right]A^{-1}(s)B(s),$$

is continuous with respect to t ϵ <0,T> , s ϵ <0,t> for every fixed x ϵ (0,1).

From the second nonlocal condition (1.4) we infer that the function $f_2(t)$ must satisfy the following system of Volterra integral equations of the second kind

(3.2)
$$\vec{f}_2(t) - \int_0^t \sum_{j=1}^p \mu_j(t) K(x_j, t, s) \vec{f}_2(s) ds = \vec{F}(t),$$

where

(3.3)
$$\overrightarrow{F}(t) = -2 \sum_{j=1}^{p} \mu_{j}(t) D \int_{0}^{t} \left[M(\frac{x_{j}}{2}, t-s) - M(\frac{x_{j}}{2}, t-s) \right] A^{-1}(s) \overrightarrow{H}(s) ds +$$

$$+ \overrightarrow{h}(t) + \sum_{j=1}^{p} \mu_{j}(t) \left[\overrightarrow{u}_{3}(x_{j}, t) + \overrightarrow{u}_{4}(x_{j}, t) \right].$$

Hence we conclude that there exists exactly one solution of the system (3.2). This solution is continuous and piecewise of class C^1 . The formulas (3.1) and (2.6) define the solution of the problem (N).

Remark. If the condition $\lim_{x\to 0^+} f(x,t) = \lim_{x\to 1^-} f(x,t) = 0$ is not satisfied but f(x,t) is continuous in $\langle 0,1\rangle \times \langle 0,T\rangle$, then we can use the substitution

$$\vec{v}(x,t) = \vec{u}(x,t) - x \int_{0}^{t} \left[\vec{f}(1,s) - \vec{f}(0,s) \right] ds - \int_{0}^{t} \vec{f}(0,s) ds.$$

This substitution reduces the problem (N) to the problem (N*)

$$\overline{v}'_t = 4D \overline{v}''_{xx} + \overline{g},$$

where

$$\overline{g}(x,t) = \overline{f}(x,t) - x \left[\overline{f}(1,t) - \overline{f}(0,t)\right] - \overline{f}(0,t)$$

$$\overline{g}(0,t) = \overline{g}(1,t) = 0$$

$$\overline{v}(x,0) = \overline{\varphi}(x)$$

with conditions

$$A(t)\overline{v}'_{X}(0,t) - B(t)\overline{v}(1,t) =$$

$$= \overline{H}(t) - A(t) \int_{0}^{t} [\overline{f}(1,s) - \overline{f}(0,s)] ds + B(t) \int_{0}^{t} \overline{f}(1,s) ds,$$

$$\overline{v}(1,t) - \sum_{j=1}^{p} \mu_{j}(t)\overline{v}(x_{j},t) =$$

$$= \overline{h}(t) - \int_{0}^{t} \overline{f}(1,s) ds + \sum_{j=1}^{p} \mu_{j}(t) \left\{ x_{j} \int_{0}^{t} [\overline{f}(1,s) - f(0,s)] ds + \int_{0}^{t} \overline{f}(0,s) ds \right\}.$$

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