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ON ALMOST PARA-CONTACT METRIC MANIFOLDS
WITH SEMI-SYMMETRIC METRIC CONNECTIONSIntroduction

Semi-symmetric connections have been studied by various mathematicians including Yano [6], Mishra [1], Imai [2] and S.I.Hussain [4]. Recently I.Sato defined and studied almost paracontact manifolds [3] and has shown that it is similar to almost product manifolds.

In the present paper we study semi-symmetric metric connections on an almost para-contact manifold, in relation to a Riemannian connection. The later part of the paper is devoted to the study of curvature tensor and Nijenhuis tensor.

1. Preliminaries

Let M^n be an n-dimensional real differentiable manifold equipped with a C^∞ -(1,1) tensor field f , a C^∞ -vector field T , and C^∞ -1 form A , satisfying

$$(1.1) \quad \begin{aligned} & a) \quad \bar{X} = X - A(X)T, \quad \text{where } \bar{X} \stackrel{\text{def}}{=} f(X), \\ & b) \quad A(T) = 1. \end{aligned}$$

Then the structure (f, T, A) on M^n is called an almost paracontact structure [3] and M^n is said to be an almost para-contact manifold. It can be verified that on M^n the following holds

$$(1.2) \quad a) \quad \bar{T} = 0 \quad b) \quad A(\bar{X}) = 0 \quad c) \quad \text{rank } (f) = n-1.$$

An almost para-contact manifold M^n with structure (f, T, A) always admits a positive definite Riemannian metric g [3] which satisfies

$$(1.3) \quad \begin{aligned} a) \quad g(\bar{X}, \bar{Y}) &= g(X, Y) - A(X)A(Y), \\ b) \quad g(X, T) &= A(X). \end{aligned}$$

M^n endowed with such a metric g is called almost para-contact metric manifold with structure (f, T, A, g) .

From (1.3) a) it follows that

$$(1.4) \quad g(\bar{\bar{X}}, \bar{\bar{Y}}) = g(\bar{X}, \bar{Y}).$$

If we put

$$(1.5) \quad F(X, Y) \stackrel{\text{def}}{=} g(\bar{X}, Y),$$

then we have the following

$$(1.6) \quad \begin{aligned} a) \quad F(X, Y) - F(Y, X) &= 0, \\ b) \quad F(X, \bar{Y}) - F(\bar{X}, Y) &= 0, \\ c) \quad F(T, Y) &= 0. \end{aligned}$$

A linear connection ∇ is said to be semi-symmetric connection on the almost para-contact manifold M^n if its torsion tensor

$$S(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y]$$

satisfies the formula

$$(1.7) \quad S(X, Y) = A(Y)X - A(X)Y.$$

∇ is said to be semi-symmetric metric connection with respect to the associated Riemannian metric g if

$$(1.8) \quad \nabla_X g = 0.$$

We define ∇ to be a semi-symmetric metric f -connection iff in addition to (1.7) and (1.8) ∇ satisfies

$$(1.9) \quad (\nabla_X f) = 0.$$

Suppose D is a Riemannian connection on M^n , then we can always put [6]

$$(2.0) \quad \nabla_X Y = D_X Y + u(X, Y),$$

u being a tensor of (1.2) type satisfying

$$(2.1) \quad g(u(X, Y), Z) = -g(u(X, Z), Y).$$

Obviously we have

$$(2.2) \quad S(X, Y) = u(X, Y) - u(Y, X).$$

Yano [6] has expressed the value of $u(X, Y)$ in terms of S and S' , both being tensors of (1.2) type as follows

$$(2.3) \quad u(X, Y) = \frac{1}{2} \{S(X, Y) + S'(X, Y) + S'(Y, X)\},$$

where

$$(2.4) \quad g(S(Z, X), Y) \stackrel{\text{def}}{=} g(S'(X, Y), Z).$$

Thus (2.0) takes the form of

$$(2.5) \quad \nabla_X Y = D_X Y + \frac{1}{2} \{S(X, Y) + S'(X, Y) + S'(Y, X)\}.$$

It can be verified that [6]

$$(2.6) \quad S'(X, Y) = A(X)Y - g(X, Y)T$$

and thus we get

$$(2.7) \quad \nabla_X Y = D_X Y + A(Y)X - g(X, Y)T.$$

It is easy to verify that

$$\begin{aligned}
 (2.8) \quad & a) u(X,Y) = S'(Y,X), \\
 & b) g(S(X,Y),T) = 0, \\
 & c) u(X,T) = S(X,T) = S'(T,X) = \bar{\bar{X}}, \\
 & d) S'(X,Y) - S'(Y,X) = S(Y,X).
 \end{aligned}$$

Theorem 1.1. In an almost para-contact manifold M^n , the torsion tensor of the semi-symmetric metric connection satisfies the following identities

$$\begin{aligned}
 (2.9) \quad & a) S(X,T) = \bar{X}, \\
 & b) S(\bar{\bar{X}},T) - S(X,T) = 0, \\
 & c) S(\bar{\bar{X}},Y) = A(Y)X - A(X)A(Y)T, \\
 & d) S(\bar{\bar{X}},Y) + S(X,\bar{\bar{Y}}) = S(X,Y), \\
 & e) A(S(X,Y)) = 0, \\
 & f) \overline{\overline{S(X,Y)}} = S(X,Y).
 \end{aligned}$$

Now we wish to establish certain identities among the $(0,3)$ type tensors defined by [4]

$$\begin{aligned}
 (3.0) \quad & S'(X,Y,Z) \stackrel{\text{def}}{=} g(S(X,Y),Z), \\
 & u'(X,Y,Z) \stackrel{\text{def}}{=} g(u(X,Y),Z)
 \end{aligned}$$

or equivalently

$$S'(X,Y,Z) = \begin{vmatrix} g(Y,T) & g(X,T) \\ g(Y,Z) & g(X,Z) \end{vmatrix}$$

and

$$u'(X,Y,Z) = \begin{vmatrix} g(Y,T) & g(Z,T) \\ g(X,Y) & g(X,Z) \end{vmatrix}.$$

Theorem 1.2. The following relations hold in an almost para-contact metric manifolds

$$\begin{aligned}
 & \text{a) } u'(X, \bar{Y}, \bar{Z}) = s'(\bar{X}, \bar{Y}, Z) = 0, \\
 & \text{b) } u'(X, Y, Z) = S'(Z, Y, X), \\
 & \text{c) } u'(X, Y, Z) = -u'(X, Z, Y), \\
 (3.1) \quad & \text{d) } s'(X, Y, Z) = -S'(Y, X, Z), \\
 & \text{e) } S'(X, Y, Z) - S'(X, Z, Y) = u'(X, Y, Z), \\
 & \text{f) } u'(\bar{X}, Y, Z) - u'(X, \bar{Y}, Z) - u'(X, Y, \bar{Z}) = 0, \\
 & \text{g) } u'(\bar{\bar{X}}, Y, Z) - u'(X, Y, Z) = 0.
 \end{aligned}$$

Theorem 1.3. The connections ∇ , D and the $(0,3)$ type tensor u' of the almost para-contact metric manifold (f, T, A, g) are related by the following

$$\begin{aligned}
 (3.2) \quad & \text{a) } (\nabla_X F)(Y, Z) = (D_X F)(Y, Z) + u'(X, \bar{Y}, Z) - u'(X, Y, \bar{Z}), \\
 & \text{b) } (\nabla_X F)(Y, Z) = (D_X F)(\bar{Y}, \bar{Z}).
 \end{aligned}$$

The proof is an easy consequence of (1.5), (1.6)a) and (2.0).

Corollary. It follows from (3.2)a) that

$$(\nabla_X F)(Y, Z) = (D_X F)(\bar{Y}, \bar{Z})$$

iff

$$(3.3) \quad u'(X, \bar{Y}, Z) = u'(X, Y, \bar{Z}).$$

Theorem 1.4. We have

$$(3.4) \quad \nabla_X \bar{Y} = D_X \bar{Y} - F(X, Y)T$$

and

$$(3.5) \quad \overline{\nabla_X \bar{Y}} = \overline{(D_X \bar{Y})}.$$

2. The curvature tensor

We denote by R and K the curvature tensors of the semi-symmetric metric connection ∇ and the Riemannian connection D respectively i.e.

$$(3.6) \quad \begin{aligned} a) R(X,Y)Z &= \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla[X,Y]Z, \\ b) K(X,Y)Z &= D_X D_Y Z - D_Y D_X Z - D[X,Y]Z. \end{aligned}$$

Then we state the following theorem.

Theorem 2.1. The two curvature tensors are related by the following equation

$$(3.7) \quad \begin{aligned} R(X,Y)Z &= K(X,Y)Z + A(D_Y Z)X - A(D_X Z)Y + g(Y, D_X Z) - \\ &\quad - g(X, D_Y Z) + X(A(Z))Y - Y(A(Z))X + \\ &\quad + A(Z)S(X,Y) + \{Yg(X,Z) - Xg(Y,Z)\}T + \\ &\quad + g(X,Z)D_Y T - g(Y,Z)D_X T + g(X,Z)Y + \\ &\quad - g(Y,Z)X + g(Y,Z)A(X)T - g(X,Z)A(Y)T + \\ &\quad + g([X,Y],Z)T. \end{aligned}$$

3. The Nijenhuis tensor

In this section we study the Nijenhuis tensor in relation to the semi-symmetric metric connection and establish various identities involving it. The Nijenhuis tensor is defined by

$$(3.8) \quad \begin{aligned} a) N(X,Y) &= [\bar{X}, \bar{Y}] + \overline{[X,Y]} - \overline{[\bar{X}, Y]} - \overline{[X, \bar{Y}]}, \\ \text{or} \\ b) N(X,Y) &= [\bar{X}, \bar{Y}] + [X,Y] - [\bar{X}, Y] - [X, \bar{Y}] - A([X,Y])T. \end{aligned}$$

If we put

$$(3.9) \quad \begin{aligned} a) B(X,Y) &\stackrel{\text{def}}{=} \overline{[X,Y]} + [X,Y], \\ b) W(X,Y) &\stackrel{\text{def}}{=} \overline{[\bar{X}, Y]} + \overline{[X, \bar{Y}]}. \end{aligned}$$

Then (3.8)a) reduces to

$$(4.0) \quad N(X, Y) = B(X, Y) - W(X, Y).$$

Further if we put

$$(4.1) \quad \begin{aligned} & \text{a) } B(X, Y, Z) \stackrel{\text{def}}{=} g(B(X, Y), Z), \\ & \text{b) } W(X, Y, Z) \stackrel{\text{def}}{=} g(W(X, Y), Z), \\ & \text{c) } N(X, Y, Z) \stackrel{\text{def}}{=} g(N(X, Y), Z) \end{aligned}$$

then it is evident from the definitions that

$$(4.2) \quad N(X, Y, Z) = B(X, Y, Z) - W(X, Y, Z).$$

Theorem 3.1. The Nijenhuis tensor N defined on M^n with the Riemannian connection D satisfies the following identity

$$(4.3) \quad N(X, Y) = (D_{\bar{X}}f)(Y) - (D_{\bar{Y}}f)(X) - \overline{(D_X f)(Y)} + \overline{(D_Y f)(X)}.$$

Theorem 3.2. $B(X, Y)$ defined by (3.9)a) satisfies the following equation

$$(4.4) \quad B(X, Y) = \nabla_{\bar{X}}\bar{Y} - \nabla_{\bar{Y}}\bar{X} + \nabla_X Y - \nabla_Y X - A([X, Y])T - S(X, Y).$$

Remark 3.1. Let ∇ be semi-symmetric metric f -connection over M^n . Then from (4.4) it follows that $B(X, Y)$ takes the form of

$$(4.5) \quad B(X, Y) = [X, Y] + A([X, Y])T + \overline{(\nabla_X Y - \nabla_Y X)}.$$

Theorem 3.3. The following relations always hold on an almost para-contact metric manifold

$$\begin{aligned}
 & \text{a) } B(\bar{X}, Y) = [\bar{X}, Y] + [X, \bar{Y}] - A([\bar{X}, Y])T - \\
 & \quad - A(X)[T, \bar{Y}] + \bar{Y}(A(X))T, \\
 & \text{b) } B(X, \bar{Y}) = [X, \bar{Y}] + [\bar{X}, Y] - A([X, \bar{Y}])T - \\
 & \quad - A(Y)[\bar{X}, Y] + \bar{X}(A(Y))T, \\
 & \text{c) } B(\bar{X}, \bar{Y}) = [X, Y] + [\bar{X}, \bar{Y}] - A([\bar{X}, \bar{Y}])T - A(X)[T, Y] - \\
 & \quad - A(Y)[X, T] + A(X)(T(A(Y)))T - \\
 & \quad - A(Y)(T(A(X)))T - X(A(Y))T + Y(A(X))T.
 \end{aligned}
 \tag{4.6}$$

The proof of above follows from (3.8)a) and (1.1)a).
 As a consequence of Theorem 3.3 and (3.8)a) we can state the following theorem.

Theorem 3.4a). The following identities are satisfied on M^n with the structure (f, T, A, g)

$$\begin{aligned}
 & \text{a) } B(\bar{X}, Y) - B(X, \bar{Y}) = \{A([X, \bar{Y}]) - A([\bar{X}, Y])\}T + \\
 & \quad + A(Y)[\bar{X}, T] - A(X)[T, \bar{Y}] + \bar{Y}(A(X))T - \bar{X}(A(Y))T, \\
 & \text{b) } B(\bar{X}, \bar{Y}) - B(X, Y) = A([X, Y]) - A[\bar{X}, \bar{Y}]T - \\
 & \quad - A(X)[T, Y] - A(Y)[X, T] + A(X)T(A(Y))T - \\
 & \quad - A(Y)T(A(X))T - X(A(Y))T + Y(A(X))T, \\
 & \text{c) } N(X, Y) = B(X, Y) - \overline{B(\bar{X}, \bar{Y})} - A(X)[T, \bar{Y}].
 \end{aligned}
 \tag{4.7}$$

From (4.0) we find that if in an almost para-contact structure $B(X, Y) = 0$ then Nijenhuis tensor is of the form $N(X, Y) = -N(X, Y)$ on the other hand, from (4.7)c) we have

$$N(X, Y) = -A(X)[T, \bar{Y}]$$

and therefore, in view of these we state the following theorem.

Theorem 3.4b). A necessary condition for the almost para-contact structure to satisfy $B(X,Y) = 0$ is that

$$W(X,Y) = A(X)[T, \bar{Y}].$$

It is easy to verify that

$$\begin{aligned} (4.8) \quad & \text{a) } A(B(X,Y)) = A([\bar{X}, \bar{Y}]), \\ & \text{b) } A(B(X,Y)) = 0, \\ & \text{c) } A(N(X,Y)) = A([\bar{X}, \bar{Y}]) = A(B(X,Y)). \end{aligned}$$

Moreover we have

$$\begin{aligned} (4.9) \quad & \text{a) } A(W(X,Y)) = 0, \\ & \text{b) } W(X,Y) - \overline{B(\bar{X}, Y)} = A(X) \overline{[T, \bar{Y}]}. \end{aligned}$$

Theorem 3.5. We have

$$\begin{aligned} (5.0) \quad N(X,Y) &= A(X) \{ N(T,Y) + \overline{[T, \bar{Y}]} \} + \\ &+ A([\bar{X}, \bar{Y}])T - W(X,Y) + \overline{W(\bar{X}, Y)}. \end{aligned}$$

Theorem 3.6. In an almost para-contact metric structure (f, T, A, g) $W(X,Y) = 0$ if

$$(5.1) \quad B(X,Y) = A(X) \{ N(T,Y) + \overline{[T, \bar{Y}]} \} + A([\bar{X}, \bar{Y}])T.$$

From (4.9)(b), (5.0) reduces to

$$(5.2) \quad N(X,Y) = A(X)N(T,Y) - \overline{B(\bar{X}, Y)} + \overline{W(\bar{X}, Y)} + A([\bar{X}, \bar{Y}])T.$$

Now it is clear that Nijenhuis tensor must vanish in order that $B(X,Y) = 0$ as well as $W(X,Y) = 0$.

But from (5.2) it follows that if $B(X,Y) = 0 = W(X,Y)$, then

$$N(X,Y) = A(X)N(T,Y) + A([\bar{X}, \bar{Y}])T.$$

Therefore, we have

$$A([\bar{X}, \bar{Y}])T = 0$$

or

$$A([\bar{X}, \bar{Y}]) = 0.$$

Thus we have the following theorem.

Theorem 3.7. In order that in an almost para-contact metric structure (f, T, A, g) , $B(X, Y) = 0 = W(X, Y)$ it is necessary for the 1-form A to satisfy

$$A([\bar{X}, \bar{Y}]) = 0 \quad \text{for all } X, Y.$$

Theorem 3.8. An almost para-contact metric structure with semi symmetric metric f -connection has vanishing Nijenhuis tensor.

Proof. From (4.3) and (2.7) we have

$$\begin{aligned} N(X, Y) &= \nabla_{\bar{X}} fY - f\nabla_{\bar{X}} Y - \nabla_{\bar{Y}} fX + f\nabla_{\bar{Y}} X - \overline{\nabla_X fY} + \\ &\quad + \overline{f\nabla_X Y} + \overline{\nabla_Y fX} - \overline{f\nabla_Y X} = \\ &= (\nabla_X f)(Y) - (\nabla_Y f)(X) - \overline{(\nabla_X f)(Y)} + \overline{(\nabla_Y f)(X)} = 0, \end{aligned}$$

in view of ∇ being semi-symmetric metric f -connection. Thus the Nijenhuis tensor vanishes.

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