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SOME PROPERTIES OF SOLUTIONS  
 OF DIFFERENTIAL EQUATIONS WITH RETARDED ARGUMENTS

1. We shall consider equations of the form

$$(E) \quad y^{(n)}(t) + F(t, y(\tau(t)), y'(\tau(t)), \dots, y^{(n-1)}(\tau(t))) = 0$$

and

$$(E_g) \quad y^{(n)}(t) + g(t)f(t, y(t), y(\tau(t))) = 0,$$

where  $g$  belongs to a family of functions  $G$  having some property  $W$ . By a solution of equation  $(E)$  (resp.  $(E_g)$ ) we shall understand every function of class  $C^n$  satisfying  $(E)$  (resp.  $(E_g)$ ) for sufficiently large  $t$ . Let  $S_E$  denote the set of solutions of equation  $(E)$ , and  $S_{E_g}$  the set of solutions of  $(E_g)$ . We assume that  $S_E \neq \emptyset$  and  $S_{E_g} \neq \emptyset$ . Let  $P_y$  be a propositional function defined on  $S_E \cup S_{E_g}$  and let

$$g_y(t) \stackrel{\text{df}}{=} \frac{F(t, y(\tau(t)), y'(\tau(t)), \dots, y^{(n-1)}(\tau(t)))}{f(t, y(t), y(\tau(t)))}$$

Staicos and Sficas [1] have formulated the following theorem.

Theorem 1.1. We have

$$\left[ \forall_{g \in G} \forall_{y \in S_{E_g}} P_y \right] \wedge \left[ \exists_{\Sigma \subset S_E} \forall_{x \in \Sigma} \sim P_x \Rightarrow g_x \in G \right] \Rightarrow \forall_{x \in \Sigma} P_x.$$

The present work is based upon Theorem 1.1. In Section 2 we give sufficient conditions for the oscillation of all solutions of equation (E), in Section 3 sufficient conditions for the oscillation of all bounded solutions of equation (E). The following theorem ([3], [4], [5]) plays an essential role in our considerations.

**Theorem 1.2.** If  $q$  and  $\tau$  are continuous for  $t \geq 0$  such that  $q(t) \geq 0$ ,  $0 \leq \tau(t) \leq t$ ,  $\lim_{t \rightarrow \infty} \tau(t) = \infty$  and

$$\int_{\tau(t)}^{\infty} [\tau(t)]^{\alpha} q(t) dt = \infty \text{ where } \alpha = \begin{cases} \gamma(n-1) & \text{for } 0 < \gamma < 1 \\ n-1-\varepsilon, 0 < \varepsilon < n-1 \text{ for } \gamma = 1 \end{cases}$$

or  $\tau$  is non-increasing and  $\int_{\tau(t)}^{\infty} [\tau(t)]^{n-1} q(t) dt = \infty$  for  $\gamma > 1$ , then every solution of the equation

$$y^{(2n)}(t) + q(t) |y(\tau(t))|^{\gamma} \operatorname{sgn} y(t) = 0$$

is oscillating.

In Section 4 we investigate the properties of non-oscillating solutions of some second order differential equation. The following theorem is very helpful for this aim.

**Theorem 1.3.** ([2] p. 37). If  $a(t)$ ,  $t_0 \leq t < \infty$ , is a continuous monotonic function and  $\lim_{t \rightarrow \infty} a(t) = c > 0$ , then every solution of the equation  $y''(t) + a(t)y(t) = 0$  is bounded.

2. Let  $F(t, u_1, \dots, u_n)$  be defined and continuous in  $D = \{(t, u_1, \dots, u_n) : t \geq t_0, -\infty < u_i < \infty, i = 1 \dots n\}$  such that  $F(t, u_1, \dots, u_n) u_1 > 0$  for  $u_1 \neq 0$ . Let  $\tau(t)$  be defined, non-increasing and continuous for  $t \geq t_0$  such that  $\tau(t) \leq t$  and  $\lim_{t \rightarrow \infty} \tau(t) = \infty$ . We assume that  $n$  is even.

For convenience we formulate further assumptions in the form of the following hypotheses.

Hypothesis  $H_1$ . There exists a number  $\alpha < 1$  such that for every function  $y(t)$  defined and continuous on  $[t_y, \infty)$ ,  $t_y \geq t_0$  with the properties

$$(i) \quad \lim_{t \rightarrow \infty} y(t) \neq 0$$

$$(ii) \quad y(t)y^{(n)}(t) \leq 0 \text{ for sufficiently large } t$$

we have

$$\int_{[t_y, \infty)} [\tau(t)]^{\alpha(n-1)} \frac{F(t, y(\tau(t)), \dots, y^{(n-1)}(\tau(t)))}{|y(\tau(t))|^\alpha \operatorname{sgn} y(t)} dt = \infty.$$

Hypothesis  $H_2$ . There exists  $\epsilon$ ,  $0 < \epsilon < n-1$ , such that for every function  $y(t)$  defined and continuous on  $[t_y, \infty)$ ,  $t_y \geq t_0$ , with properties (i), (ii), we have

$$\int_{[t_y, \infty)} [\tau(t)]^{n-1-\epsilon} \frac{F(t, y(\tau(t)), \dots, y^{(n-1)}(\tau(t)))}{|y(\tau(t))|^\epsilon} dt = \infty.$$

Hypothesis  $H_3$ . For every function  $y(t)$  defined and continuous on  $[t_y, \infty)$  with properties (i), (ii) we can select  $\beta > 1$  such that we have

$$\int_{[t_y, \infty)} [\tau(t)]^{n-1} \frac{F(t, y(\tau(t)), \dots, y^{(n-1)}(\tau(t)))}{|y(\tau(t))|^\beta \operatorname{sgn} y(t)} dt = \infty.$$

Now we are going to prove the following theorem.

Theorem 2.1. If any one of the hypotheses  $H_1$ ,  $H_2$ ,  $H_3$  holds, then every solution of equation (E) oscillates.

*Proof.* We apply Theorem 1.1. Let  $P_y$  mean:  $y$  oscillates. Suppose that  $H_1$  holds. Let us denote

$$f(t, y(t), y(\tau(t))) = |y(\tau(t))|^\alpha \operatorname{sgn} y(t), \quad 0 < \alpha < 1,$$

$$G = \left\{ g(t) : g(t) \text{ defined and continuous on } [t_g, \infty), \right.$$

$$\left. g(t) \geq 0, \int_{[t_g, \infty)} [\tau(t)]^{\alpha(n-1)} g(t) dt = \infty \right\}.$$

The validity of the first term of the predecessor of the implication results from Theorem 1.2. Assume that  $\Sigma = S_E$ . Observe that if  $y(t) \in S_E$  and  $y(t)$  does not oscillate, then  $y(t)y^{(n)}(t) \leq 0$ . Since  $n$  is even, this implies  $\lim_{t \rightarrow \infty} y(t) \neq 0$ . From  $H_1$  it follows that

$$g_y(t) = \frac{F(t, y(\tau(t)), \dots, y^{(n-1)}(\tau(t)))}{|y(\tau(t))|^{\alpha} \operatorname{sgn} y(t)} \in G$$

which ends the proof of Theorem 2.1. in the case where  $H_1$  holds.

Next assume that  $H_2$  holds. We then take

$$f(t, y(t), y(\tau(t))) = y(\tau(t))$$

and

$$G = \left\{ g : \text{the function } g(t) \text{ is defined and continuous on } [t_g, \infty), g(t) \geq 0, \exists_{0 < \varepsilon < n-1} \int_{t_g}^{\infty} [\tau(t)]^{n-1-\varepsilon} g(t) dt = \infty \right\}.$$

If  $H_3$  holds, then we take

$$f(t, y(t), y(\tau(t))) = |y(\tau(t))|^{\beta} \operatorname{sgn} y(t), \beta > 1$$

and

$$G = \left\{ g : \text{the function } g(t) \text{ is defined and continuous on } [t_g, \infty), g(t) \geq 0, \int_{t_g}^{\infty} [\tau(t)]^{n-1} g(t) dt = \infty \right\}.$$

In both cases we conclude the proof using Theorem 1.2, similarly as in the case  $0 < \alpha < 1$ .

**Remark 2.1.** If we assume that  $n$  is odd, then under the same assumptions we obtain that all solutions of equation (E) oscillate or tend to 0 together with all derivatives up to the order  $(n-1)$ . If either  $H_1$  or  $H_2$  holds, we do not have to assume that the function  $\tau$  is non-increasing.

**R e m a r k 2.2.** The class of equations to which Theorem 2.1. applies is wider than the class considered in [1], as the theorems of Staicos and Sficas cannot be applied in the case where for any  $0 < a \leq 1$ , we have  $\lim_{t \rightarrow \infty} t^{-a} \tau(t) = 0$ . Theorem 2.1 implies Theorem 3.1 of [7] and Theorems 1 and 2 of [6].

**3. Hypothesis  $H_4$ .** For every function  $y(t)$  defined and continuous on  $[t_y, \infty)$ ,  $t_y \geq t_0$ , with properties (i), (ii) we have

$$\int^{\infty} [\tau(t)]^{n-1} F(t, y(\tau(t)), \dots, y^{(n-1)}(\tau(t))) dt = \infty.$$

**Theorem 3.1.** If Hypothesis  $H_4$  holds, then every bounded solution of equation (E) is oscillating.

**P r o o f.** Let

$$f(t, y(t), y(\tau(t))) = |y(\tau(t))|^{\beta} \operatorname{sgn} y(t), \quad \beta > 1$$

$$G = \left\{ g(t) : g(t) \text{ defined and continuous on } [t_g, \infty), g(t) \geq 0, \right.$$

$$\left. \int^{\infty} [\tau(t)]^{n-1} g(t) dt = \infty \right\}.$$

We define  $\Sigma$  to be the set of bounded solutions of the equation (E). Let  $y(t) \in \Sigma$  and assume that  $y(t)$  is not oscillating. From  $H_4$  it follows that

$$[\tau(t)]^{n-1} \frac{F(t, y(\tau(t)), \dots, y^{(n-1)}(\tau(t)))}{|y(\tau(t))|^{\beta} \operatorname{sgn} y(t)} dt \geq$$

$$\geq \frac{1}{A^{\beta}} \int^{\infty} [\tau(t)]^{n-1} F(t, y(\tau(t)), \dots, y^{(n-1)}(\tau(t))) dt = \infty,$$

$$A = \operatorname{const} \neq 0.$$

Hence the function  $\frac{F(t, y(\tau(t)), \dots, y^{(n-1)}(\tau(t)))}{|y(\tau(t))|^{\beta} \operatorname{sgn} y(t)}$  belongs to  $G$ , which was to be proved.

4. We shall consider the equations

$$(E') \quad y''(t) + F(t, y(\tau_1(t)), y'(\tau_2(t))) = 0,$$

$$(E'_g) \quad y''(t) + g(t)y(t) = 0.$$

We make the following assumptions concerning the functions  $F(t, u, v)$  and  $\tau(t)$ :

(1)  $F(t, u, v)$  is defined and continuous in the set

$$\{(t, u, v) : t \geq t_0, -\infty < u, v < +\infty\}.$$

(2)  $F(t, u, v)$  has the property that every solution of equation  $(E')$  is extendable over the interval  $[t_y, \infty)$ .

(3) For every function  $y(t)$  defined and continuous on  $[t_y, \infty)$  which is not bounded and not oscillating we have

$$\lim_{t \rightarrow \infty} \frac{F(t, y(\tau_1(t)), y'(\tau_2(t)))}{y(t)} = c_y > 0$$

and  $\frac{F(t, y(\tau_1(t)), y'(\tau_2(t)))}{y(t)}$  is monotonic for sufficiently large  $t$ .

$$(4) \quad \tau_i(t) \in C[t_0, \infty), \quad i = 1, 2.$$

Theorem 4.1. If assumptions (1) - (4) hold, then every non-oscillating solution of equation  $(E')$  is bounded.

Proof. We apply Theorem 1.1 to equations  $(E')$  and  $(E'_g)$ . Let  $P_y$  denote:  $y$  is bounded on  $[t_0, \infty)$ . Let

$$g_y(t) \stackrel{\text{df}}{=} \frac{F(t, y(\tau_1(t)), y'(\tau_2(t)))}{y(t)},$$

$G \stackrel{\text{df}}{=} \{g(t) : g(t) \text{ is defined, continuous and monotonic on}$

$$[t_g, \infty), \lim_{t \rightarrow \infty} g(t) = c_g > 0\}.$$

Let  $\Sigma$  denote the set of all non-oscillating solutions of equation (E). The validity of the predecessor of the implication in Theorem 1.1 results from Theorem 1.3. Let  $y(t) \in \Sigma$  and assume that  $\sim Py$ . The function  $g_y(t)$  is continuous for sufficiently large  $t$ , hence from (3) it follows that  $g_y(t) \in G$ .

**Definition 4.1.** A function  $h(t, u, v)$  is said to be almost monotonic in a set  $D$  provided that

$$\begin{aligned} t_1 &\leq t_2, |u_1| \leq |u_2|, |v_1| \geq |v_2|, u_1 u_2 > 0, \\ v_1 v_2 &> 0, (t_i, u_i, v_i) \in D, \\ i = 1, 2 \Rightarrow h(t, u_1, v_1) &\leq h(t, u_2, v_2) \end{aligned}$$

or

$$\begin{aligned} t_1 &\leq t_2, |u_1| \leq |u_2|, |v_1| \geq |v_2|, u_1 u_2 > 0, \\ v_1 v_2 &> 0, (t_i, u_i, v_i) \in D, \\ i = 1, 2, \Rightarrow h(t, u_1, v_1) &\geq h(t, u_2, v_2). \end{aligned}$$

**Corollary 4.1.** If

(5)  $h(t, u, v)$  is defined, continuous, almost monotonic and non-negative in  $D = \{t \geq t_0, -\infty < u, v < +\infty\}$ ,

(6)  $uh(t, u, v) \leq A_0 t + A_1 |u| + A_2 |v|$ ,  $A_i = \text{const} \neq 0$ ,  $i=0,1,2$ ,

(7) for every  $a \in \mathbb{R}$  we have

$$\lim_{\substack{t \rightarrow \infty \\ |u| \rightarrow \infty \\ v \rightarrow a}} h(t, u, v) = h_a > 0,$$

(8)  $\tau(t) \in C[t_0, \infty)$ ,  $\tau(t) \geq 0$ ,  $\tau'(t) \geq 0$ ,  $\lim_{t \rightarrow \infty} \tau(t) = \infty$

then every non-oscillating solution of the equation

$$y''(t) + y(t)h(t, y(\tau(t))), y'(\tau(t))) = 0$$

is bounded.

Proof. The accepted assumptions guarantee the existence of the solution on the positive semi-axis. Observe that if  $y(t)$  is a non-bounded non-oscillating solution, then  $y(t)y'(t) > 0$  and  $y(t)y''(t) < 0$  for  $t \geq t^* \geq t_0$ . This implies that if  $t_2 \geq t_1 \geq t^*$  then

$$|y(\tau(t_1))| \leq |y(\tau(t_2))|$$

and

$$|y'(\tau(t_1))| \geq |y'(\tau(t_2))|, h(t, y(\tau(t)), y'(\tau(t)))$$

is monotonic for  $t \geq t^*$ . Since  $\lim_{t \rightarrow \infty} |y(t)| = \infty$ , from (7) it follows that  $h(t, y(\tau(t)), y'(\tau(t))) = c > 0$ .

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Received July 30, 1975.

