

Contents

Brief Introduction to the Book	III
About the Authors	V
Preface	VII
Notations	XV

CHAPTER 1

Introduction	1
1.1 Research Object and Tasks of Structural Analysis	2
1.1.1 Research Object	2
1.1.2 Tasks	3
1.2 Computational Models of Structures	4
1.2.1 Simplification of Structural Systems	5
1.2.2 Simplification of Members	5
1.2.3 Simplification of Joints	6
1.2.4 Simplification of the Supports	7
1.2.5 Simplification of Material Properties	8
1.2.6 Simplification of Loads	8
1.3 Classification of Member Structures and Loads	10
1.3.1 Classification of Member Structures	10
1.3.2 Classification of Loads	11
1.4 A Brief History of the Development of Structural Analysis	12
1.4.1 Energy Principles and Energy Methods	13
1.4.2 Force Method and Displacement Method	15
1.4.3 Matrix Displacement Method and Finite Element Method	18
1.5 A Brief Introduction to Important Figures in Structural Analysis	20

CHAPTER 2

Kinematic Analysis of Plane Member Systems	27
2.1 Several Concepts of Kinematic Analysis	28
2.1.1 Degree of Freedom and Constraint	28
2.1.2 Instantaneously Changeable System and Constantly Changeable System	30

2.1.3	Instantaneous Hinge	31
2.2	Basic Construction Rules of Plane Geometrically Unchangeable Systems	32
2.2.1	The Rule of Pin-Joined Member System	32
2.2.2	The Rule of Two Rigid Discs	33
2.2.3	The Rule of Three Rigid Discs	34
2.3	Computational Degree of Freedom of Plane Member Systems	39
2.3.1	Computational Degree of Freedom of Rigid Disc System	40
2.3.2	Computational Degree of Freedom of the Hinged System	42
2.3.3	Computational Degree of Freedom of the Mixed System	44
2.4	Geometrical Stability and Static Determinacy of Systems	45
	Problems	46

CHAPTER 3

	Analysis of Statically Determinate Structures	49
3.1	Single-Span Statically Determinate Beams	50
3.1.1	Single-Span Statically Determinate Beams and Internal Forces	50
3.1.2	Relations Between Loads and Internal Forces	52
3.1.3	Method of Segmental Superposition	54
3.2	Multi-Span Statically Determinate Beams	57
3.3	Statically Determinate Plane Trusses	62
3.3.1	Characteristics and Classification of Trusses	62
3.3.2	Method of Joints	64
3.3.3	Method of Sections	67
3.3.4	Combined Application of the Method of Joints and the Method of Sections	69
3.4	Statically Determinate Plane Frames	71
3.4.1	Characteristics of Frames	71
3.4.2	Calculation of Support Reactions	71
3.4.3	Internal Force Analysis and Drawing Internal Force Diagram of Frames	75
3.4.4	Quick Drawing of Moment Diagrams of Statically Determinate Frames	84
3.5	Statically Determine Composite Structures	86
3.6	Three-Hinged Arches	92
3.6.1	Support Reactions and Internal Force Calculation of Three-Hinged Arches	93
3.6.2	Rational Axes of Three-Hinged Arches	99
3.7	General Properties of Statically Determinate Structures	104
	Problems	106

CHAPTER 4

Principle of Virtual Work and Deflection Calculation	113
4.1 Overview of Deflection Calculation	113
4.1.1 Concept of Structural Displacements	113
4.1.2 Purpose of Deflection Calculation	115
4.2 Principle of Virtual Work for Deformable Structures	116
4.2.1 Principle of Virtual Work for Rigid Body System	116
4.2.2 Application Conditions of Principle of Virtual Work for Deformable Structures	116
4.2.3 Virtual Work Equation for Deformable Structures	119
4.2.4 Principle of Virtual Forces and Principle of Virtual Displacements	122
4.3 Unit-Load Method for Structural Deflection Calculation	124
4.4 Deflection Calculation under Loads	127
4.4.1 Formula for Deflection Calculation under Loads	127
4.4.2 Deflection Formulas for Various Structures	128
4.4.3 Examples of Deflection Calculation under Loads	130
4.5 Graph Multiplication Method	136
4.5.1 Graph Multiplication Method and Its Application Conditions . .	136
4.5.2 Several Specific Problems of Applying Graph Multiplication Method	137
4.5.3 Examples of Graph Multiplication Method	140
4.6 Deflection Calculation under Temperature Change	143
4.7 Reciprocal Theorems of Linearly Elastic Structures	146
4.7.1 Theorem of Reciprocal Works	146
4.7.2 Theorem of Reciprocal Displacements	148
4.7.3 Theorem of Reciprocal Reactions	149
4.7.4 Theorem of Reciprocal Displacement-Reaction	150
Problems	151

CHAPTER 5

Force Method	157
5.1 Determination of Degree of Static Indeterminacy	158
5.1.1 Equilibrium and Geometric Construction Characteristics of Statically Indeterminate Structures	158
5.1.2 Determination of Degree of Indeterminacy and Number of Redundant Constraint Forces	159
5.2 Fundamental Concept of the Force Method	161
5.2.1 Primary Unknowns, Primary System, and Basic Equations of Force Method	161
5.2.2 Analysis of Structures with Multiple Degrees of Indeterminacy by Force Method	165
5.2.3 Canonical Equations of Force Method	167

5.3	Analysis of Statically Indeterminate Frames and Bent Structures	169
5.4	Analysis of Statically Indeterminate Trusses and Composite Structures	177
5.5	Analysis of Symmetric Structures and Half Structures	182
5.5.1	Selection of Symmetric Primary System	184
5.5.2	Determination of Half Structure in Terms of Symmetry	188
5.6	Two-Hinged and Hingeless Arches	193
5.6.1	Solving Two-Hinged Arch by the Force Method	194
5.6.2	Solving Hingeless Arch by the Force Method	200
5.7	Internal Force Analysis of Structures under Support Movement or Temperature Change	204
5.7.1	Support Movement	204
5.7.2	Temperature Change	208
5.8	Deflection Computation of Statically Indeterminate Structures	210
5.9	Check for Calculated Results of Statically Indeterminate Structures . .	215
5.9.1	Check of Equilibrium Conditions	216
5.9.2	Check of Deformation Conditions	217
	Problems	218

CHAPTER 6

	Displacement Method	223
6.1	Fundamental Concept of the Displacement Method	224
6.1.1	A Simple Example of Displacement Method	224
6.1.2	Primary Unknowns and Basic Equations of Displacement Method	227
6.1.3	Basic Idea of Calculating Frame Structures by Displacement Method	228
6.1.4	Determination of Primary Unknowns of Displacement Method	229
6.2	Slope-Deflection Equation of Prismatic Member	232
6.2.1	Calculating Member-End Internal Forces from Member-End Displacements	234
6.2.2	Calculating Fixed-End Internal Forces from Loads	238
6.3	Analysis of Frames Without Sidesway	241
6.3.1	Selection of Primary Unknowns	241
6.3.2	Establishment of Basic Equations	241
6.4	Analysis of Frames with Sidesway	245
6.5	Analysis of Symmetric Structures	253
6.6	Primary System in the Displacement Method	256
6.6.1	Primary System of the Displacement Method	257
6.6.2	Basic Equations of the Displacement Method	258
6.6.3	Process of Establishing the Basic Equations of the Displacement Method	260
6.6.4	Canonical Equations of Displacement Method	262
6.7	Principle of Potential Energy and Displacement Method	264
6.7.1	Principle of Stationary Potential Energy	264

6.7.2	Linear Elastic Strain Energy of Prismatic Member	266
6.7.3	Principle of Potential Energy and Equilibrium Equation of Displacement Method	267
6.8	Rayleigh–Ritz Method	272
6.9	Moment-Distribution Method and No-Shear Distribution Method	274
6.9.1	Basic Principle of the Moment-Distribution Method	275
6.9.2	Computation of Continuous Beams and Frames Without Sidesway Using the Moment-Distribution Method	280
6.9.3	No-Shear Distribution Method	286
6.10	Characteristics of Statically Indeterminate Structures	292
	Problems	294

CHAPTER 7

	Influence Lines for Structures under Moving Loads	301
7.1	Concepts of Moving Load and Influence Line	302
7.2	Equilibrium Method for Constructing Influence Lines of Simply Supported Beams	304
7.3	Influence Lines for Girders and Trusses	309
7.3.1	Influence Lines for Internal Forces of Girders	309
7.3.2	Influence Lines for Axial Forces of Trusses	311
7.4	Kinematic Method for Constructing Influence Lines of Statically Determinate Structures	315
7.5	Applications of Influence Lines	321
7.5.1	Responses Due to Various Kinds of Loads	322
7.5.2	Most Unfavorable Position of Moving Loads	324
7.5.3	Determination of Critical Position for Polygonal Influence Line	326
7.5.4	Determination of Critical Position for Triangle Influence Line	330
7.6	Kinematic Method for Constructing Influence Lines of Statically Indeterminate Beams	333
	Problems	341

CHAPTER 8

	Matrix Displacement Methods	345
8.1	Fundamental Principle of the Matrix Displacement Method	346
8.2	Elemental Stiffness Matrix	347
8.2.1	Elemental Stiffness Matrix in Local Coordinate System	348
8.2.2	Properties of Elemental Stiffness Matrix	350
8.3	Coordinate Transformation of Elemental Stiffness Matrix	351
8.3.1	Elemental Stiffness Matrix in the Global Coordinate System	351
8.3.2	Elemental Stiffness Matrix of Continuous Beam	355
8.3.3	Elemental Stiffness Matrix of Axial Force Bar	357
8.4	Global Stiffness Matrix of Structure	360
8.4.1	Element and Node Numberings	360

8.4.2	Direct Stiffness Method for Assembling Global Stiffness Matrix	362
8.4.3	Imposing Support Conditions	364
8.4.4	Properties of Global Stiffness Matrix	365
8.4.5	Treatment of Pinned Joints	366
8.5	Equivalent Nodal Loads	366
8.5.1	Basic Equation of Matrix Displacement Method	366
8.5.2	Equivalent Nodal Loads of Elements	367
8.5.3	Equivalent Nodal Loads of Structure	369
8.6	Computational Procedures and Examples	372
8.6.1	Example of Truss Analysis	373
8.6.2	Example of Frame Structure	378
8.6.3	Example of Composite Structure	384
8.6.4	Matrix Displacement Method for Rectangular Frame Neglecting Axial Deformation	388
	Problems	391
	Bibliography	397
	Appendix A1. Answers to Problems	399
	Appendix A2. Index	407
	Appendix A3. Matlab Program Codes of the Matrix Displacement Method for Plane Structural Analysis	409